

UNIT	RC 610	MODEL LPE 200/	NO	
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This LOG LIST contains information on modifications of the basic unit, due to Options, Engineering Change Notes, and Field Change Orders.

Do not forget to list all future modifications on this page.

	OPTION ECN or FCO No.	DATE of Installation	SIGN	SHORT DESCRIPTION
	ECN 1102 1104, 1105		2	
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- KI 23			·	
KCSL 44				

1. GENERAL

RC 4000 has, in principle, two data channels, a Low Speed Data Channel (LDC) and a High Speed Data Channel (HDC). Each of these data channels is shared among several input/output units.

Sharing of the data channels among several devices requires each device to be terminated by a buffer register and a data channel transceiver, and to be controlled by a set of standardized signal sequences. The buffer register provides word-by-word data transfer to and from the device.

The data transfer via LDC is performed character by character under microprogram control. The LDC communicates directly with the internal working registers. Transmission of data via LDC is mainly used in connection with slow character-oriented devices such as typewriters, paper tape readers, and paper tape punches.

Data transfer via HDC take place in blocks. Data are transferred directly to or from the internal core store on a cycle-stealing basis. The block transfer is not program controlled, i.e. program execution proceeds simultaneously with the HDC input/output operations. Specification and initiation of the block transfer are performed via the LDC; therefore all devices, which are connected to the HDC, are also connected to the LDC.

All input/output operations via LDC can be handled by a single program instruction, INPUT/OUTPUT (IO), which has the standard instruction format. The effective address of the instruction indicates the device address (18 bits) and the device command (6 bits). A data word (max. 24 bits) is transferred to or from the specified working register (W-register).

The program instruction, AUTOLOAD WORD (AW), controls a series of 4 input operations via LDC. This instruction reads four 6-bit characters, and is used for initial program loading from the paper tape reader.

2. LOW SPEED DATA CHANNEL

2.1. Introduction

The Low Speed Data Channel (LDC) is based upon a 2 way transmission system with 30 buslines for data and control signals. The buslines can be sensed by or controlled from both the Central Processor (CPU) and all peripheral devices connected to the system.

The IDC has 24 data buslines and 6 buslines for channel control signals. The data buslines are used to transfer a 24-bit Data Word and to

transfer a Device Address and a Device Command. The Data Word can either be transferred from CPU to the addressed device or vice versa.

2.2. Operational Description

The input/output operation, which is controlled by the microprogram belonging to the IO instruction, can briefly be described as follows. The input/output operation includes a Selection Phase and a Data Phase. In the Selection Phase (indicated by the control signal IO Address) the Device Address and the Device Command are available for all devices on the 24 data buslines. The addressed device responds to these by sending its Ready and Connected status bits via 2 of the channel control buslines. These bits are transferred to the Exception Register (EX(22:23)). If they indicate that the device is free, i.e. connected and ready, one of the channel control signals (IO Activate) activates the device. If the addressed device is not free, the input/output operation is rejected and the computer proceeds immediately to the next instruction. If selection takes place, the device will accept the device command code from the buslines.

In the Data Phase (indicated by the control signal IO Transfer) a Data Word (max. 24 bits) is transferred from the specified W-register to the selected device or vice versa. The direction depends on the device command type. The device command is given by 6 bits, 2 of which specify the 4 types, Sense, Control, Read, and Write. The Sense command performs transfer of a Data Word from the selected device to the selected W-register. The Write and Control commands imply transfer from the W-register to the selected device. The Read command does not involve any data transfer. When the Data Phase is terminated, the device is left to its own control. As long as the initiated operation is in progress, the device must generate a Not Ready signal on request.

2.3. Device Address and Device Command

In the Selection Phase of the IO instruction the Device Address and the Device Command are transferred via the 24 data buslines (IO BUS(0:23)) as follows

IO BUS (0:17)

Device Address

IO BUS (18:23)

Device Command.

The Device Address consists of 18 bits. In practice an 8-bit address field (256 devices) is enough, and the device controllers are allowed to interpret the device address modulo 256.

The Device Command code of 6 bits includes a basic command field of 2 bits and a modifier field of 4 bits

IO BUS (22:23)

Basic command field

IO BUS (18:21)

Modifier field.

The 16 possible modifications are specific for each type of devices. In the microprogram, controlling the input/output operations, only the following 4 basic commands are recognized:

IO BUS (22.23) = b00 Sense

IO BUS (22,23) = b01 Control

IO BUS (22,23) = b10 Read

IO BUS (22,23) = b11 Write

2.4. LDC Input/Output Signals

Figure 1-4 shows the timing charts of the possible input/output operations. The operations are completely controlled by the IO instruction microprogram in accordance with the received device Connected and Ready Status. An IDC output signal is defined as a signal transferred from the CPU via a busline to a device controller. An IDC input signal is a signal generated in the device controller and transferred via a busline to the CPU. The input/output signal functions are specified below.

LDC Outputs:

IO Enable

The signal indicates the period of the IO operation. When IO Enable = 1, the addressed device must reply to the busline signals; when IO Enable = 0, no device must interfer with the channel.

IO Address

The signal on this busline indicates the selection phase. Device address and command information are on the buslines IO BUS (0:23).

IO Activate

This busline signal indicates that the addressed device has to be selected and that the device command code has to be stored.

IO Transfer

The signal indicates the data phase. In output operations (Write, Control) a Data Word is available on the buslines IO BUS (0:23).

In input operations (Sense) the data and status word from the selected device (DEV Data) must be gated to the buslines IO BUS (0:23).

IO BUS (0:23)

In the selection phase (IO Address = 1):

IO BUS (0:17) = Device Address

IO BUS (18:23) = Device Command

In the data phase (IO Transfer = 1) for Write and Control commands:

IO BUS (0:23) = W(0:23) (data word to be transferred from CPU to device controller).

In the data phase for Sense commands IO BUS (0:23) is used for transfer of DEV Data (0:23) from device controller to CPU.

LDC Inputs:

DEV Connected

This signal, which is generated in the device controller, indicates that the device power supply is switched on and that all cable connection e.g. to the external device, are established.

DEV Connected must be gated to the busline IO Connected when the device is addressed and IO Address = 1.

DEV Ready

The signal indicates that the device controller is
ready to accept IO instructions. During operation
the device is Not Ready and IO instructions are rejected. DEV Ready must be gated to the busline
IO Ready when the device is addressed and IO Address = 1.

DEV Data (0:23)

This is a data word to be transferred from device controller to CPU (W register) during execution of a Sense command. DEV Data (0:23) has to be gated to the buslines IO BUS (0:23) during the period indicated by IO Transfer.

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	wg.				
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	Replaced by	Time Scale: 0 1 2 3 4 µsec			
	tepla	Time Scale: 0 1 2 3 4 µsec			
. •					
		LDC Outputs:			
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	que	IO Enable			
•	Replaces Dwg. No.				
	ъм.	IO Address			
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(ž	IO Activate 0			
	٧.				
·	Check	IO Transfer 0			
-	Design	IO BUS(0:23) 0			
		IO BUS(0:23) 0			
	Check				
		LDC Inputs:			
	Office				
	'g. C				
-	Dwg.	DEV Connected 0			
		DEV Ready 1			
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	Z	1) IO BUS(0:17) = Device Address			
	AL	IO BUS(18:23)= Device Command			
*	TR				
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5	REGNECENTRALEN				
IC doc: V9 139	S	RC 4000 Low Speed Data Channel Figure 1 Dwg. No. Timing Chart for REJECTED TO Instruction			
روم	A/S	Timing Chart for REJECTED IO Instruction			
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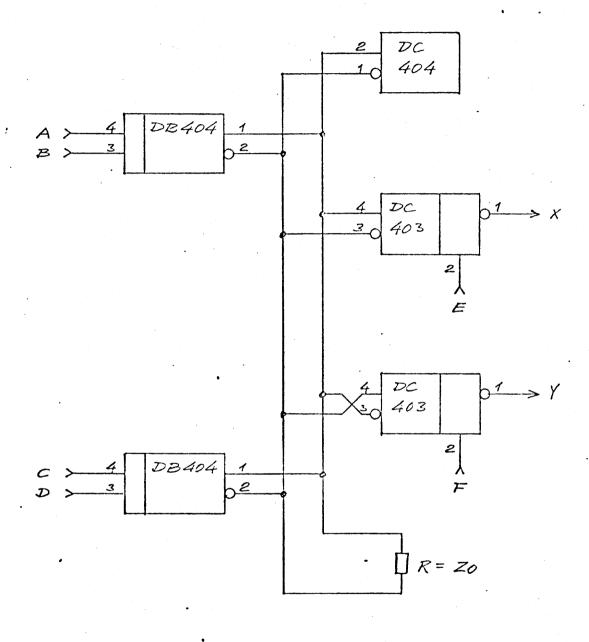
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Replaces Dwg. No.		IO Address 0 — In Activate 0 —	MC 4
In Check		IO Transfer 0	-MCD
Office Check Design		IO BUS(0:23) 0	SB shifter til nyt indvald uder noger disideret udidgalise pats.
Dwg. C		DEV Connected 0	
Drawn by		DEV Ready 0 DEV Data(0:23) 0	for CPU til den. så derfor ingen. data fra den.
31	249.68 MW.		
	ENTRALEN	 1) IO EUS(0:17) = Device Address IO BUS(18:23) = Device Command 2) IO EUS(0:23) = 24 bit Output Character 	
) 	Unit RC 4000 Low Speed Data Channel Dwg. No. Timing Chart for WRITE AND CONTROL Co	Figure

Time Scale: O 1 2 3 4 5 µsec	
	3
10 Thobas	
IO Address 1 TO Activate	
IO Activate 0	
TO RUS(0.23)	
10 100 (0.2)	· · · · · · · · · · · · · · · · · · ·
LDC Inputs: DEV Connected 1	
DEV Ready 0	
DEV Data 1	
Designed by 24.9 63 MLCO	
1) IO BUS(0:17) = Device Address IO BUS(18:23) = Device Command	
Timing Chart for RFAD Command	Figure 4

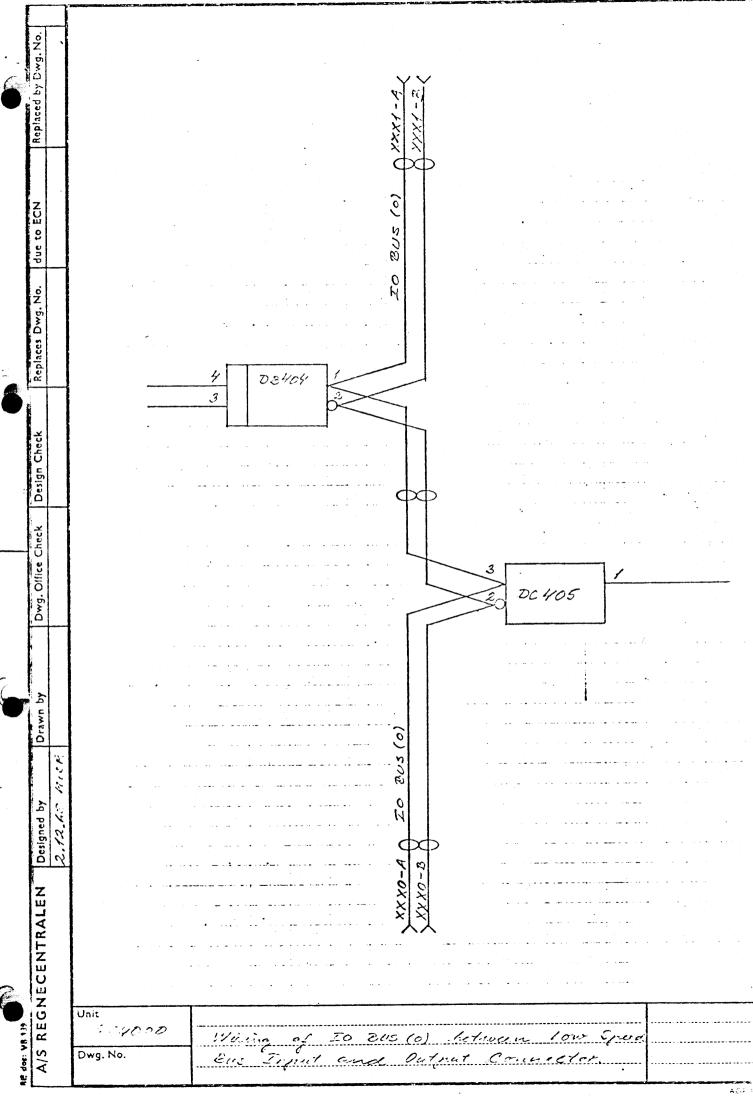
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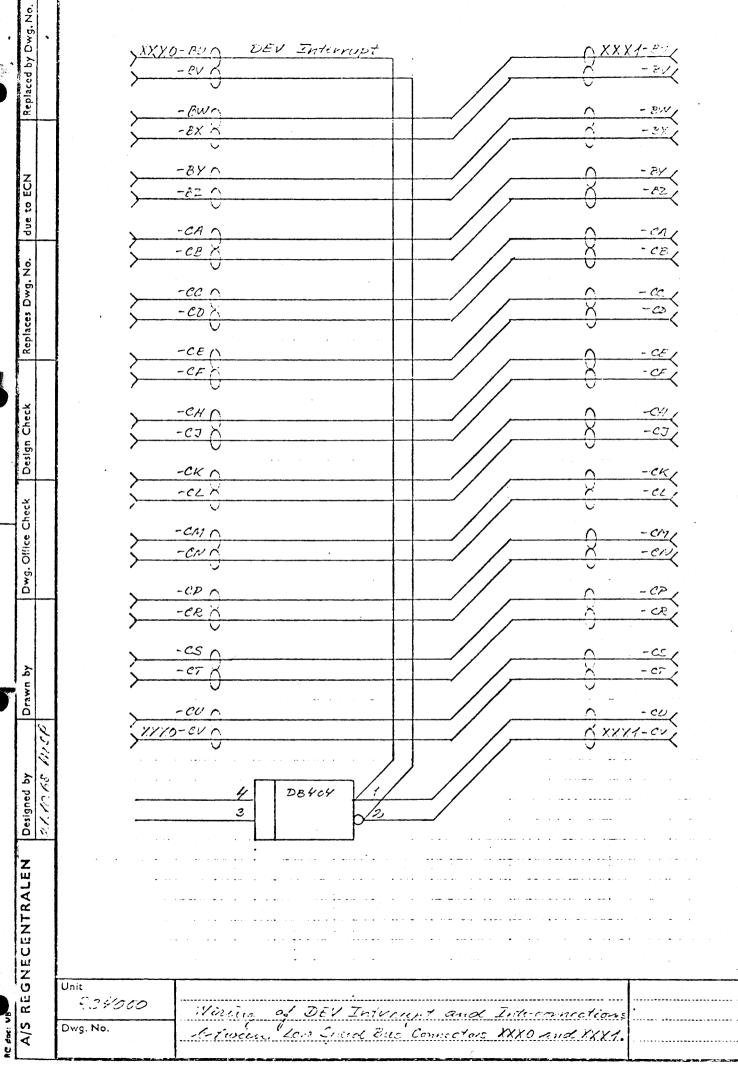
RCLM400 Functional Description

DB404, DB405, DC403, DC404



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Ē.	CENTRALEN	Last Revision	DC 403, DC 404		





Receptable, type 8016 - 90, code PIN name wired to wired to A / ZO EUS (0) В 2 C (1) D E (2) F (3) H 3 | (4) K | 9 L 10 (5) MIZZ NI (6) P // R 1/2 (2) S 1/3 TIG U //: (6) W 19 191 X 20 (10) Y 27 Z 122 (11) AA 💆 AB 20 (12) AC 12 AD SA AE 25 (13) (14) AH A 3 32 AK (15) ALES (16) AM --ANI (17) APIC AR .: (18) AS S AT S AU L (19) AV I (20) AW 2/ AX 化 (51) AY -: AZ 1/2 IC EUS (22) BA X

Unit: /SC

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400000 CENTRALEN Designed 21.10.68 HULP
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LOW SPEED BUS

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PIN	wired to	wired to	name
BB 🚜			
BC 🜮			IO EUS (23)
BD √ €			
BE 📝			IO Erable
BF co		·	
BH C/			IO PONTOSS
BJ 🚓			
BK 🥴			In lictivate
BL SW			
BM (C)			IO Transfer
BN 54			
BP 77			IO Connected
BR Jan			70 8000
BS Z			ZO Readin
BT 4.5			TEN Training
BV ac			DEV Interpret
- BW -3	VVV = 211=		
BX	XXX1 - 30-		
BY	- 2V - - BW		
BZ 166	- E.V		
CA 57	- £Y		
CB	- 82		
CC 1/m 3	- CA		
CD 2.5	- 18	,	
CE 1	- 60		
CF170	- CD		
CH 22	- 1.6		
CJ See	- CF		
CK! 105	- 14		
CL 2/4	- 37		
CM122	- CK		
CN SX	- 64		
CP 1/9	- 311		
CR どっ	- 011		
CS\A/	- ci		
CT ĉ.;	- CR		
CUIS	- 00		
CV 32	1XX1 - CT		
CW 3.5			01
CX SA			07
CYTES			01
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DATES			EHIELD

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N. B. S. A. A. 205 .. W. 155

PIN	wired to	wired to	n ame
A ,	·		Zo EUS (0)
B			
C .			(1)
D 1/2			
E S			(2)
F G			
H 7			(3)
<u>)</u> 8			(4)
K 9			(4)
M //			(5)
N /2			
P /2			(6)
R 72			
\$ 10			(7)
T 1/6			
U /7			(8)
V 18			(9)
W 13			1 37
X 20 Y 21			(10)
Z 2.1			(15)
AA			(11)
AΒ			
A C 🕾			(12)
AD 26			
AE 2%		<u> </u>	(13)
AF 22		<u> </u>	(14)
A H A Go			(74)
AK 37		 	(15)
AL		1	
A M 35			(16)
ANISE			
AP 35			(17)
AR 26			
AS 37			(18)
AT 38			
AU 37			(19)
AV 60			(28)
AX Ø:			1
AX 85			(21)
AZ Vy		1	
25/1/			IO 202 (22)

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Receptable, type 8016-90, code name PIN wired to wired to BB A 20 805 (23) BCI 22 BDi 🚧 BE P? IO Enable BF |30 BHICK IO Adares BJ J2 BK 53 20 Activate BL 34 IO Thankfor BM 33 BN 56 BP 32 IO Connected BRISS IO Readu BSICO BT 160 BU 61 XXXO - EN BV 101 - 27 BW 63 - 24 BXICY - 32 - ca BYIAT - CB BZ 66 CA 62 - 00 CB. GF - (2 CC: 69 - 26 CD 20 - CF CE: 27 - CH - 00 CF 🌝 CH 1/2 - CK C31 20 - 66 - 011 CK! 次广 - cn CL 2% CM 22 - CP - CE CN' 28 CP CP - cs CR′ ∂a - 07 - 20 C\$ 37 CT & XXXO- CV DEV Internunt CU 57 CV 27 CW SS CX CL 01 CY CY 01 CZ 88 CHIELD DA. 89 DB 90 CHIELD

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ICI DATAMATICS

RCSL: 44-RT171
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September 1970

LPE 200
CONTROLLER FOR CONNECTION
OF LP 200 PRINTER ON-LINE TO
RC 4000

TECHNICAL MANUAL

A/S REGNECENTRALEN

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	FC 5 LOAD	The state of the s	_ '	A10533	
	FC 6 LOAD	-		A10534	
	FC 7 END OF LOAD	-	#C9	A10535	
	FC 8 PRINT			A10536	
	FC 9 PRINT	-	954	A10537	
	FC 10 PRINT	-	-	A10538	
	FC 11 PAPER FEED	_	-	A10539	
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	FC 13 PAPER FEED	=	-	A10541	
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	LD 4 COMMAND AND ADDRESS DECODING	_		A10336	
	LD 5 COMMAND AND ADDRESS DECODING		-	A10337	
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LD 12	PUSHBUTTON LOGIC	-	-	A10344
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LD 14	OPERATOR CONTROL AND IND, LOGIC .	-	-	A10346
LD 15	OPERATOR CONTROL AND IND, LOGIC .	_	-	A10347
LD 16	CLOCK AND TIMING CIRCUITS		-	A10348
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LD 19	BASIC CONTROL LOGIC	-		A10351
LD 20	BASIC CONTROL LOGIC	_	-	A10352
LD 21	BASIC CONTROL LOGIC		-	A10353
LD 22	TEST INFORMATION	-	***	A10354
LD 23	REGISTER 1 AND REGISTER 2	-	_ '	A10355
LD 24	REGISTER 1 AND REGISTER 2	- ,	-	A10356
LD 25	REGISTER 1 AND REGISTER 2	-	ten	A10357
LD 26	n-REGISTER		e m	A10358
LD 27	READ ONLY STORE	-	-	A10359
	NOTE: INPUT CODE TABLE RC STAN-			
	DARD INCL. OPTIONS.			
LD 27	READ ONLY STORE	-	ra	A10360
	NOTE: INPUT CODE TABLE, RC			
	STANDARD INCL. OPTIONS.			
LD 28	READ ONLY STORE	•	-	A10361
LD 29	READ ONLY STORE	-	-	A10362
	NOTE: INPUT CODE TABLE,			
	RC STANDARD INCL. OPTIONS.			
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	NOTE: INPUT CODE TABLE,			
	RC STANDARD.			

Contents continued

LD 30	READ ONLY STORE	Dwg.	No.	A10364
	NOTE: INPUT CODE TABLE,			
	RC STANDARD INCL. OPTIONS.			
LD 31	LINE BUFFER (SHIFT REGISTER)	-	-	A10365
LD 32	CONTROL CHARACTER DECODING	_ '	<u>.</u> '	A10366
LD 33	CONTROL CHARACTER DECODING	-		A10445
LD 34	CONTROL CHARACTER DECODING	-	-	A10446
LD 35	CONTROL CHARACTER DECODING	units	-	A10369
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LD 44	INDEX AND CHAR. COUNT LOGIC	-	-	A10378
LD 45	INDEX AND CHAR. COUNT LOGIC			A10379
LD 46	CHARACTER COUNTER		-	A10380
LD 47	COMPARATOR	-	■ 11	A10381
LD 48	HAMMER STROBE GENERATOR	-		A10382
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1

This paper describes the RC610 LINE PRINTER which consists of:

- 1. LPE 200 Control electronic
- 2. LP 200 Print mechanism.

The description will mainly deal with the LPE 200 designed and manufactured by A/S REGNECENTRALEN.

The LP 200 is a DATA PRODUCTS printmechanism MODEL dp/p - 4300 designed and manufactured by DATA PRODUCTS CORPORATION, 8535 WARNER DRIVE, CULVER CITY, CALIFORNIA.

For further information on LP 200 see section 25.

Functional Description

The RC610 LINE/PRINTER contains all the electronic and mechanical components required to accept and store one line of data from RC4000 serial by character (up to a maximum of 132 characters), print the line on multiple-part fanfold paper or on tabulating stock, and move the paper to the position corresponding to the next print line.

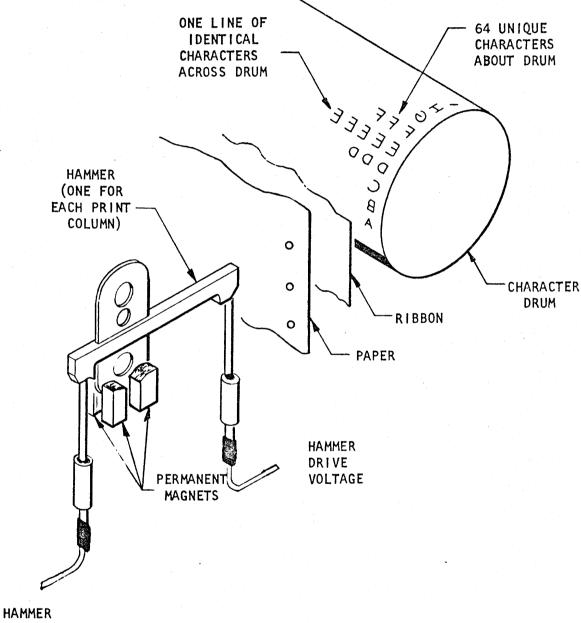
The RC610 LINE/PRINTER utilizes a continuously rotating drum on which characters are arranged in horizontal rows, the number of rows being determined by the number of characters in the character set. Each vertical column about the circumference of the drum thus contains all the characters in the set, and the number of columns defines the maximum number of characters per line. Each character is stored in a one-line shift register buffer arranged as a cyclic store, when the store is loaded a character address location corresponds to the column in which it will be printed. Printing is accomplished by shifting in the cyclic store in synchronism with the rotating characters and actuating a hammer (see Fig. 1) associated with the address location, when the proper character approaches the print position.

1.1

The line of data stored in the buffer is shifted one character at a time to the first position of the cyclic store and compared with the drum character approaching the print position. If the drum character currently in the printing position is A, the logic will sequentially fire the appropriate hammers to print all the A-s in the stored line of data. As the drum rotates each character in the buffer is compared with each successive drum character as it comes into printing position. In one revolution or less of the character drum, the entire line of data will be printed.

LPE 200

1-2



CONTROL

LPE 200

A20744

HAMMER OPERATION

Fig 1

Figure

The LP 200 (printer mechanism) is connected to the low speed data channel via LPE 200 (control electronic) which buffers one line.

LP200 Operational Description

2.1

The LP 200 is a drum type print mechanism with the following general specifications:

Printing rate

Up to 1000 lines-per-minute.

Characters per line

Up to 132.

Characters per inch

10.

Lines per inch

6.

Line to Line Spacing

0.167 (-0.010) inch.

Character Sets

64 and 96 standard.

Character Drum Speed

1000/667 rpm minimum for

64/96 character drum.

Paper Feed

Tractor type, using a pair of pin-feed tractors above a pair of tractors below the print

position.

Paper Speeds

One line - 15 msec max.

two lines - 25 msec max.

three lines - 30 msec max.

5 msec per line after third

corresponding to max. paper

feed speed 35 inches per second.

Paper Feed Control

The paper feed may be controlled either by a 8 channel format tape or by counting lines.

Paper Format

19 inches maximum width, prints on 13.2 inch width in the center of a 19 inch form.

Paper Dimensions

Standard edge-punched 1/2 inch centers fanfold paper from 4.5 to 19 inches in width.

Paper Types

Up to six parts, 12-pound bond (single copy minimum weight, 15 pound bond); or a tabulating card (0.007 inch) plus a second record sheet.

Paper Loading

Drum gate pivots outward through an opening between the ribbon mask and the hammer bank.

Horizontal Alignment

LEFT TRACTOR DETENTS. Upper and lower left tractors are individually positioned by detents to coarse define location of left-hand paper holes.

FORM WIDTH ADJUSTMENT. Upper and lower right tractors are individually positioned by lock-nuts

hand paper holes. Adjustable for 4-1/2 inch to 19 inch forms.

to align tractors with right

HORIZONTAL PAPER TENSION AD-JUSTMENT. Individual adjustments on upper and lower right-hand tractors to provide proper horizontal paper tension. HORIZONTAL PAPER POSITION AD-JUSTMENT. Provides vernier adjustment of all four tractors to horizontally align forms while printing. Vertical Alignment

VERTICAL PAPER TENSION ADJUST-MENT. Varies distance between upper and lower tractor pairs to provide proper vertical paper tensioning.

VERTICAL PAPER POSITION ADJUST-MENT. Adjusts paper vertically † 1 line from its mid-range position.

Character Typeface

On the standard drums, 64 and 96 characters, OCR-B font is used except for the basis of ten characters.

Character Spacing

Horizontal character spacing is $0.100 (\frac{1}{2} 0.005)$ inch between centers. The maximum cumulative error is no more than $\frac{1}{2} 0.010$ inch per 132 character line.

Line Straightness

No character deviates more than - 0.010 inch from a straight line drawn parallel to the line of characters.

Input Character Set

The standard character set is a subset of the ISO 7 bit character set. Two standard print drums are available. One having 64 graphics capital letters only, the other having 96 graphics including small letters. 4 (optionally 9) control characters are used. The characters are internally represented by the bits

b7 b6 b5 b4 b3 b2 b1

having the weights

64 32 16 8 4 2 1

In the code table columns and rows are indentified by decimal equivalents of the binary numbers:

The decimal value of a character code is thus the sum of column and row numbers. Empty positions in the table are characters which are not used with the printer.

The character set is divided in control characters, columns 0 and 16, and graphical characters, columns 32 to 112. The table shows the assignment of characters according to the ISO recommendation for the two standard print drums with 64 and 96 characters respectively. Other print drums with expanded character sets may be supplied. Characters which are not assigned by the ISO-standard will be reached by means of the shift option. After having received the character SHIFT OUT, the printer will interpret the character codes to be in a new set of graphical characters. Control characters, columns 0 and 16 have the same meaning while column 32 is reserved for a standard expansion of the graphics set. This assignment of codes will remain valid until the character SHIFT IN is received, thus returning control to the standard character set.

The two standard print drums differ only in the respect that the big one also has small letters. Both have a set of national letters so that it is possible to construct 3 varities of alphabets: danish, german, and swedish. In these the rows 11, 12, and 13 of columns 80 and 112 are assigned as follows:

	Danish		Ger	man	Swedish	
11	Æ	æ	Ä	a.	Ä	ä
12	ø	ø	ö	ö	ö	 ö
13	Â	å.	ü	ü	Å	8.

The characters not used nationally are available after shift out, column 32. The choice of national characters in the shift in alphabet is done prior to the installation.

Control Characters

The control characters have the meanings:

- CR Carriage Return, causes the printing of the line buffer contents followed by a return of print position to the beginning of the same line.
- FF Form Feed, causes the printing of the line buffer followed by a paper feed to the first line of the next form as indicated by format control tape track 0. The print position is moved to first position of this line.
- NL New Line, causes printing of a line followed by paper feed of one line. Print position is moved to first position of this line.
- VT Vertical Tabulation, causes printing of a line followed by paper feed controlled by the format control tape track 1. Print position is moved to first position of this line.

		0	16	32	48	64	80	96	112
	0			SPACE	0		Р		Р
ı	1			1	1	Ä	Q	а	q
	2			11	2	В	R	b	r
1	3				3	С	S	С	s
ı	4				4	D	T	d	t
	5			%	5	E	U	е	U
	6			&	6	F	٧	f	٧
	7			٥	7	G	W	g	w
Ì	8		CAN	(. 8	Н	Х	h	×
	9	НТ)	9:	1	Υ	i	У
	10	NL		*	:	Ĵ	Z	i	z
	11	VT	ESC	+	;	Κ	nat,	k	nat.
	12	FF		7	<	L	nat.	. [nat.
	13	CR		-	=	M	nat,	m	nat
	14	SO		•	>	N		n	
<u>~</u>	15	SI			3	0		0	DEL

00370

After shift out

¥	0	16	32	48	64	80	96	112
0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15	HT NL VT FF CR SO SI	CAN ESC	SPA:A:O:U Χ ÆΦ.Δ:α:o:υ θ Φ å	0 1 2 3 4 5 6 7 8 9				DEL

Note underline is placed on the base-line.

Write Command

3.1

A write command initiates the output of one character from a working register. The contents of a working register is interpreted as follows:

irrelevant character

0:16 17:23

After the write command the printer will be busy for approximately 12 uS (from I/O ACTIVATE), if a graphic character is transferred. If printing is started the printer will be busy until completion of the printing, which will generally not exceed 100 mS (depending on size of print drum, characters actually printed etc.). When the line buffer is full, further graphical characters will be lost. Printing will not start until initiated by a control character.

Characters which are not defined to have any effect with the printer are ignored.

An interrupt signal is sent upon completion of the printing.

The printer has a LOCAL/REMOTE switch. In remote state the printer is program controlled. In local state the operator may insert and adjust forms etc.

If the operator switches to local during printing the transition to local status is delayed until the printing has been completed. In local status the printer accepts write commands until a control character, which causes printing, is received. When the control character is received the printer goes busy. No mechanical operation, however, is executed until the operator switches to remote status.

Sense Command

3.2

When the printer is available a sense command may be used to transfer a status word to a working register. The status holds the following information:

3-1

0:56:23

The status bits are:

- 0 Intervention by operator
- 1 PARITY
- 2 Time out
- 3 not used
- 4 not used
- 5 Intervention required.

The Intervention by operator is set to logical 1 when the printer goes local, and remains logical 1 until next write command is received.

PARITY is set to logical 1 if any of the following conditions is received.

- 1. Parity error in the converter
- 2. Parity error in the line buffer
- 3. Check character error i.e. shifting in the line buffer was incorrect.
- 4. Echo error i.e. one or more hammers have failed.

 The parity status bit remains logical 1 until next write command.

The Time out bit is set to logical 1 if any of the following conditions occur:

- 1. Echo from hammers too long
- 2. Character Drum off speed
- 3. A paper feed operation has lasted too long
- 4. A print operation has lasted too long.

The time out bit remains logical 1 until cleared by Master clear.

Intervention required is set to logical 1 if the end of paper is reached, paper torn or drum gate open. The intervention required bit remains logical 1 until paper is corrected and drum gate closed. If the printer detects a paper out situation during printing, the line in progress will be completed.

This section describes the operating controls and the procedures required for operation of the line printer.

Operators Controls and Indicators

The following describes the various operators controls and indicators. These controls are located on the operator panel, the relay box, the drum gate, and the paper feed assembly.

Operators controls located on the operators control panel: (See Fig. 2).

Power/Operable Pushbutton Indicator

The Power/Operable pushbutton indicator is a dual indicator switch which controls the ac-power to the printer. The switch is the push-to-set, push-to-reset type. When the switch is depressed to apply power, the power portion of the indicator lights. When the switch is depressed to remove power, the power indicator extinguishes.

The operable indicator is illuminated presupposed:

- 1. DEVICE CONNECTED
 - (i.e. all power supplies ok)
- 2. Paper correctly installed
- 3. Drum gate closed
- 4. No Time-out signal present.

The signals involved in the operable indicator is interpreted as follows:

1. Device connected

Device connected will be set to logical 0 and the operable indicator extinguished if any of the following conditions occurs:

- a. Multi-power supply not ok
- b. Hammer and Paper feed power supply not ok
- c. Hammer current reference voltage not ok.

When the Power switch has been activated to apply power, it will last approximately 16 seconds before Device connected becomes logical 1.

If Device connected is set to logical 0 due to power failure the situation is only resetable by turning power off and then on again, but this should not be done unless qualified service-personnel has been notified.

2. Paper out

If the printer detects a Paper out situation during printing the line in progress will be completed.

The operable indicator will be extinguished and the Paper out indicator lighted when the paper out situation occur.

The operable indicator will be lighted and the paper out indicator extinguished when the paper is corrected.

Status bit 5 is logical 1 as long as the Paper out situation exsists.

3. Drum gate open

If the drum gate is left open or opened during operation, hammer strobe will be inhibited immediately. Simultaneously the status bit 5 is set to logical 1 and the operable indicator extinguished. Status bit 5 will be set to logical 0 and the operable indicator lighted, when the drum gate is closed.

CAUTION

Do not open drum gate during printing.

4. Time-out

Operable indicator is extinguished and status bit 2 set to logical 1 if any of the following conditions occurs:

- a. Hammer echo too long
- b. Drum speed
- c. Error in Paper drive motor voltage (forward voltage in too long time or too much reverse voltage)
- d. Print-cycle.

The Time out signal inhibits the hammer strobe and if c is the case the paper feed power amplifier will be disabled.

The time out signal is only resetable by means of the MCL-button, this is done because the time out error is a rather serious error, and the MCL-button should not be activated unless qualified service-personnel has been notified.

Remote/Local pushbutton Indicator

The Remote/Local pushbutton indicator is a dual indicator switch. The switch is the push-to-set, push-to-reset type. In remote state the printer is program controlled. In the local state the operator may insert and adjust forms etc.

If the operator switches to local during printing the transition to local is delayed until the printing has been completed. In this situation the remote indicator is extinguished when the pushbutton is depressed, the local indicator, however, is not lighted until the printing has been completed.

In local status the printer accepts write commands until a control character, which demands printing, is received. When control character is received the printer goes busy. No mechanical operation however, is executed until the operator switches to remote status. The Remote/Local indicator gives the following information. Light in an indicator is equal to logical 1:

Remote	Local	
indicator	indicator	
0	0	Local wanted
0	1	Local state
1	0	Remote state
1	1	Remote wanted

Parity/Paper-out Indicator

The Parity/Paper-out indicator is a dual indicator.

The parity portion of the indicator will be lighted if any of the following conditions occur:

- 1. Parity error in the converter
- 2. Parity error in the line buffer
- 3. Check character error i.e. shifting in the line buffer was incorrect.
- 4. Echo error i.e. one or more hammers have failed.

The parity indicator is extinguished when a new write command, concerning the printer, is executed.

The signals involved in the Parity indicator is interpreted as follows:

1. Parity error in the converter.

As soon as a character is sent to the LPE 200 it will be converted to an internal character representation by means of a read-only-store, if a parity error in the output from the read-only-store is present, the Parity indicator will be lighted, the status bit 1 set to logical 1, and the character ignored.

If a new write command is ordered the Parity indicator will be extinguished and the status bit 1 set to logical 0.

2. Parity error in the line buffer

The parity indicator is lighted and the status bit 1 set to logical 1, when a parity error in the line buffer is detected, however, the line in progress will be completed.

The parity check takes place during the entire print-cycle regardless to whether the character with wrong parity has been printed or not, and characters with wrong parity inhibit hammer strobe, i.e. they are not printed. This means that if the character should have been printed, there will be no echo from the hammer and at the end of the printing the column counter will contain the address of the line buffer cell with wrong parity.

The Parity indicator is extinguished, the status bit 1 set to logical 0, and the column counter reset when a new write command is ordered.

3. Check character error

The check character is used to check if shifting in the line buffer takes place correctly.

If a check character error is detected the Parity indicator will be lighted and the status bit 1 set to logical 1, however, the line in progress will be completed.

The Parity indicator is extinguished, the status bit 1 set to logical 0 when a new write command is ordered.

4. Echo error

If a hammer has failed to print in a column which should have been printed or a hammer has printed in a column which should not have been printed, the Parity indicator will be lighted and the status bit 1 set to logical 1.

The address of the hammer which failed will be present in the column counter after printing.

The Parity indicator is extinguished, the status bit 1 set to logical 0, and the column counter reset when a new write command is ordered.

Refer to 4.2 for the description of the Paper-out portion of the Parity/Paper-out indicator.

Over Temp., Hammer current indicator

Over Temp., Hammer current indicator is a single indicator.

The indicator is lighted and Hammer-Paper feed power supply disabled if any of the following conditions occurs:

- 1. Hammer current has been on for more than 400 mS
- 2. Over temperature in the paper drive motor.

Also an audio signal is given in these situations. The loud speaker is located on the operators control panel.

The error situation is only resetable by turning power off and then on again, but this should not be done unless qualified service-personnel has been notified.

Local Start/Stop Pushbutton Indicator

The Local Start/Stop pushbutton indicator is a dual indicator switch which starts and stops local operations.

The switch is the push-to-set, push-to-reset type.

The type of local operation executed when the pushbutton is activated is under control of the Form mode/Line mode switch, and the Testprint/Paper feed switch.

The Form mode/Line mode switch and the Testprint/Paper feed switch will normally be locked in the Form mode and Paper feed positions indicated by light in the Form mode and Paper feed portions of these indicators.

The switches are locked by means of the On line/Off line switch located on the maintenance panel. The On line/Off line switch should only be operated by trained service personnel and the switch must always be left in On line position after service. If the On line/Off line switch is left in On line position the printer will perform paper feed, according to the paper tape loop channel O, when the Local Start/Stop pushbutton is activated. If the Local Start/Stop is activated while printer is in Remote condition it will have no effect.

As long as the Local operation is in progress there will be light in the Start portion of the indicator. When no local operation is in progress there will be light in the Stop portion of the indicator.

Form mode/Line mode pushbutton indicator
This pushbutton indicator is a dual indicator switch. The switch
is the push-to-set, push-to-reset type.
For description of the function refer to Local Start/Stop switch
(4.5).

Testprint/Paper feed pushbutton indicator

This pushbutton indicator is a dual indicator switch. The switch

is the push-to-set, push-to-reset type.

For description of the function refer to Local Start/Stop switch

(4.5).

Operators Control located on the relay box

A 20 ampere ac circuit breaker placed in series with the input ac
is mounted on the relay box. When the breaker trips, the switch
handle will travel to off position. The breaker is reset by operating the switch handle to On position.

Operators Control located on the drum gate

The operators phasing control is mounted to the right on the drum gate. Adjusting this control varies the point in time that hammer flight is initiated. This in turn varies the registration of the character as it is being printed. Bad phasing is indicated by a difference in ink density between the top and the bottom of a printed character. The top or bottom of the character may actually be missing. The phasing control should be adjusted until the tops and bottoms of the characters on each printed line are of the same density.

Operators Control, located on the paper feed assembly

Paper positioning controls (See Fig. 3)

The paper is horizontally positioned by two controls; the tractors provide a coarse horizontal position adjustment. Fine horizontal adjustment of - 3 character widths are made with the horizontal paper position adjustment.

4.9

4.10

4.10.1

4.6

4.7

Vertical positioning of the paper is a function of four controls: the paper drive release lever, vertical paper position adjustment, dynamic vertical paper position adjustment, and the vertical paper position indicator. The paper drive release lever enables the paper to be adjusted any number of lines up or down by means of the vertical paper position adjustment when the paper drive system is stopped, and one line up or down by means of the dynamic paper position adjustment when the paper drive system is in motion. The vertical paper position indicator provides a reference for vertically aligning the paper and is used in conjunction with the vertical paper position adjust.

Paper tensioning controls (See Fig. 3)

4.10.2

The paper is tensioned by two controls: the vertical paper tension adjustment and the tractor horizontal paper tension adjustment. The vertical paper tension adjustment is used to tauten the paper between the upper and lower tractors. The two horizontal paper tension adjustments are adjusted independently, to tauten the paper between the left and right tractors.

Copies control (See Fig. 3)

4.10.3

The copies control, a three position knob, is provided to vary the distance between the drum and the hammer bank in order to accommodate various thicknesses of paper (see Fig. 3). The knob is set to 1, 3, or 6 to provide for optimum printing. The calibrations are nominal and should be tested for various part paper.

Operating Procedures required for operation of the printer

- 1. Application of power to the printer
- 2. Ribbon installation
- 3. Ribbon removal
- 4. Tape Loop preparation
- 5. Tape Loop installation
- 6. Paper loading
- 7. Paper tension

- 1. Open the front doors
- 2. Place the main circuit breaker located on the relay box in On position. If the neon-indicator fails to illuminate, notify service personnel.
- 3. Press the Power switch located on the operators control panel, and the Power indicator should illuminate. After app. 16 seconds the power will be ok, drum on speed and the Operable indicator illuminated, presupposed paper correctly installed, drum gate closed and no time out signal present.

Removal of power to the printer

4.13

- 1. Press the Power switch located on the operators control panel, and the Power indicator will be extinguished.
- 2. Wait until the drum has stopped rotating.
- 3. Open front doors.
- 4. Place the main circuit breaker in Off position and the neon-indicator will be extinguished.

NOTE

Main circuit breaker must not be operated before the Power switch has been pressed and the drum has stopped rotating.

Ribbon Installation (see Fig. 4)

4.14

The operator should utilize the gloves supplied in the ribbon box when removing and replacing the ribbon. The printer uses standard 14 inch by 15 yards long, inked roll ribbon of high quality fabric. Perform the following procedures when installing the ribbon:

- a. Turn POWER OFF and open drum gate after character drum stops.
- b. Grasp the two ribbon spools by the left end. Insert right end of upper and lower spools into upper and lower spring-loaded hubs provided on the casting.
- c. Push the spools to the right against the spring-loaded hubs until the left ends of spools can be engaged in the two drive hubs.

- d. Align each spool so that the key on the drive hub locks into the slot in the spool.
- e. Place left and right edges of ribbon in between guides on drum gate (see Fig. 4).
- f. Close drum gate.

Ribbon Removal

4.15

Ribbon removal is the reverse of installation.

Tape Loop Preparation

4.16

The printer uses standard 8-channel business machine tape to control paper stepping. Paper, mylar or aluminum tape may be used; however, paper tape has a very short lifetime and may decrease operating reliability. Mylar or aluminum tape is therefore recommended.

Fig. 5 illustrates the relationship between the sprocketed tape and the form. Each tape drive sprocket is equivalent to one line space on the form. Thus, for a standard 11 inch form, 66 drive sprockets define one form length on the tape. When determining the next hole positions to be punched, the operator should count the line spaces from the last punched line and punch a hole in the channel location horizontal to the hole corresponding to the next line on the form.

The vertical location of the tape holes is dependent upon the particular application. The standard printer is logically mechanized to proceed to channel O when the LOCAL START/STOP pushbutton is operated; therefore channel 0 must be reserved for top of form. The seven remaining channels may be utilized in various ways. Fig. 5 illustrates a tape configuration where a single hole is punched for each of eight entries required for the form. Most large forms require more than eight entries. Any one channel may be used to define all the entries required for any one form. In this case, a hole is punched in that channel for each required line entry and the computer is programmed to successively enter the paper instructions for that channel. Thus each channel may be used for a specific form. Any one tape loop can then accomodate up to a maximum of seven forms. This approach results in programming simplicity since one paper instruction address is associated with each of the seven forms.

Use the following procedures to prepare a paper tape loop.

- a. Determine the required entries from the computer programmer based on the number of forms and location of entries on each form.
- b. Obtain paper instruction program for applicable form(s) from programmer.
- c. Using any manual or machine tape punch, punch a hole in tape channel 0 for the top-of-form position of the paper. (The top-of-form may be referenced to the actual top edge of the form or may be used as the initial entry.)
- d. Count the line spaces from the paper top-of-form entry to the second form entry. Punch a hole that number of sprocket holes after the top-of-form hole in the tape channel specified for the second entry.
- e. Count the number of line spaces from the top-of-form entry to the third from entry, punch a hole that number of drive holes after the top-of-form hole in the tape channel specified for the third entry.
- f. Count the line spaces for each successive form entry and punch holes in the specified tape channels.
- g. Punch a second hole in tape channel 0 at a distance from the first top-of-form hole equal to the number of lines on the form.
- h. Remove the tape from the punch.

NOTE

The tape loop should be a minimum of six inches in circumference. If form is too short, make tape loop two or three form lengths long to permit tape loop to ride freely on tape loop reader. When form is over six inches, use only one form length.

i. Using any method recommended by the tape manufacturer, splice tape ends together with the side of the tape shown in Fig. 5 being on the outer surface of the tape loop. If possible, avoid splicing tape in area of punched holes.

- a. Operate Remote/Local pushbutton to Local.
- b. Open printer top cover. Lift tape loop reader handle until drive sprocket shoe clears drive sprocket teeth.
- c. Place the tape loop over the tape loop reader capstan and fit the tape drive holes over drive sprocket teeth with cahnnel O toward the short end of the capstan.
- d. Close the tape loop reader, noting that the tape remains fitted on the drive sprocket while the drive sprocket shoe clamps it in place.
- e. Advance to top-of-form by depressing Local Start/Stop push-button.

NOTE

The tape should halt with the channel 0 star wheel just beyond the top-of-form hole. If the tape halts out of phase notify service personnel.

f. After the cover is secured and the doors closed, the printer is prepared to operate if paper and ribbon are properly installed.

CAUTION

Ensure that paper and ribbon are properly loaded before operating the printer.

NOTE

With no tape loop installed, tape loop instructions will behave as if all holes are punched in all channels.

Paper Loading (See Fig. 3)

4.18

When the form being loaded is identical to the form used for the previous operation, the tractors should be properly positioned. In this case the form should be loaded onto the tractors and properly tensioned. When a new form is to be loaded, perform the following procedures:

- a. Operate Remote/Local pushbutton to Local and lift printer
- . top cover.
- b. Ensure that tape loop is installed in reader and press Local Start/Stop pushbutton.
- c. Open drum gate and printer front doors to obtain access to the paper feed mechanism.
- d. Adjust the horizontal paper position adjustment, and the vertical paper position adjustment to the center of their range.
- e. Open ribbon mask assembly. (See Fig. 4).
- f. Open all four tractor clamps.
- g. Place paper in cabinet and insert paper up between the ribbon mask and hammer bank.
- h. Close ribbon mask and position the first print column on the form to correspond with the first print column on the hammer bank as determined by the scale on the ribbon mask and hold in that position.
- i. Slide the upper left tractor to the closest detented position to engage the tractor teeth in the form drive holes.
- j. Slide the lower left tractor over to the detented position corresponding to the upper tractor.
- k. Position the paper top-of-form entry adjacent to the top (x) on the side of the ribbon mask if the form is printed before it is advanced; or by the second (x) if the form is to be advanced before printing.
- 1. Place drive holes over upper and lower left tractor teeth and close clamps.
- m. Loosen upper and lower right tractor locks, and slide tractors over to engage teeth of tractors in drive holes of form.
- n. Close clamps and lock tractors in that position.
- o. Operate the horizontal and vertical paper tension adjustment until the paper is taut between all four tractors and close drum gate.
- p. Operate the horizontal paper position adjustment to align paper with proper column using ribbon mask calibrations as a guide.
- q. Close ribbon mask and drum gate.

- r. Ensure that the paper is properly tensioned as described in paragraph 4.19.
- s. With paper and ribbon installed, program the Controller to instruct the printer to print several pages of data.
- t. While printing, adjust the horizontal and vertical paper position adjustments until the printed line is properly positioned on paper.

Paper Tension Adjustment without Paper Drive Releaser
In order to provide clear, sharp printing and minimize paper breakage, the paper must be placed under maximum vertical and horizontal tension. Adjustment of paper tension is as follows.

Horizontal Paper Tension Adjustment 4.19.1
Adjust horizontal paper tension as follows:

a. Rotate the horizontal paper tension adjustments (see Fig. 3) to obtain as much horizontal tension as possible short of tearing or deforming the paper drive holes.

Vertical Paper Tension Adjustment Adjust vertical paper tension as follows:

4.19.2

4.19

a. Rotate vertical paper tension adjustment (see Fig. 3) to obtain maximum vertical tension in paper short of tearing paper drive holes.

NOTE

Some vertical deformation of the holes normally occurs when the paper is properly tensioned.

b. Check paper for smooth taut surface between all four tractors; remove any wrinkles in paper by simultaneously adjusting appropriate horizontal and vertical paper tension adjustments.

CAUTION

Excesseive tension of the paper can cause the paper to tear during printing. Slackness can cause poor vertical registration. Ensure proper tensioning before attempting operation.

Paper Loading with Paper Drive Releaser (See Fig. 3)
When the form being loaded is identical to the form used for the previous operation, the tractors should be properly positioned.
In this case, the form should be loaded onto the tractors and properly tensioned. When a new form is to be loaded, perform the following procedures:

- a. Operate Remote/Local pushbutton to Local and lift printer top cover.
- b. Ensure that tape loop is installed in reader and press Local Start/Stop pushbutton.
- c. Open drum gate and printer front doors to obtain access to the paper feed mechanism.
- d. Adjust the horizontal paper position adjustment, and the dynamic paper position adjustment to the center of their range.
- e. Open ribbon mask assembly. (see Fig. 4).
- f. Open all four tractor clamps.
- g. Place paper in cabinet and insert paper up between the ribbon mask and hammer bank.
- h. Close ribbon mask and position the first print column on the form to correspond with the first print column on the hammer bank as determined by the scale on the ribbon mask and hold in that position.
- i. Slide the upper left tractor to the closest detented position to engage the tractor teeth in the form drive holes.
- j. Slide the lower left tractor over to the detented position corresponding to the upper left tractor.
- k. Place drive holes over upper and lower left tractor teeth and close clamps.
- Loosen upper and lower right tractor locks, and slide tractors over to engage teeth of tractors in drive holes of form.
- m. Close clamps and lock tractors in that position.
- n. Operate the horizontal and vertical paper tension adjustments until the paper is taut between all four tractors.

- o. Set the paper drive release lever in the ADJUST position and rotate the vertical paper position adjustment until
- the bottom edge of the first character line to be printed is aligned with the lower edge of the ribbon mask opening.
- p. If the computer format instructs the printer to print before paper is stepped, adjust the vertical paper position indicator as follows:
 - 1. Rotate the outer ring of the vertical paper position indicator until the bottom line of position A is aligned with any one of the lines on the nylon inner ring.
 - 2. Rotate the vertical paper position adjustment knob upward until the previously selected line on the nylon inner ring lines up with the top line of position A.
- q. If the computer format instructs the printer to step paper before it is printed, operate the vertical paper position indicator as described in the above steps (p1 and p2) using position C.
- r. Reset the paper drive release lever to RUN and close drum gate.
- s. With paper and ribbon installed, program the Controller to instruct the printer to print several pages of data.
- t. While printing, adjust the horizontal and dynamic vertical paper position adjustments until the printed line is properly positioned on paper.

Paper Tension Control with Paper Drive Releaser (see Fig. 3)
In order to provide clear, sharp printing and minimize paper breakage, the paper must be placed under proper vertical and horizontal tension. Adjustment of paper tension is as follows:

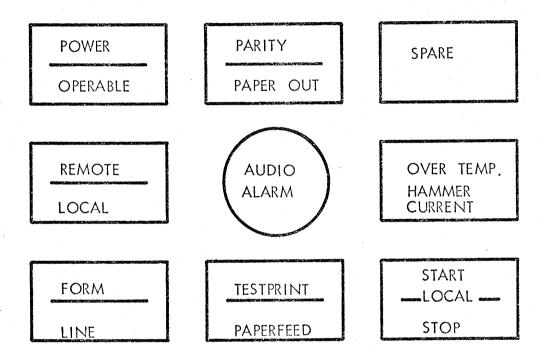
- a. Turn power on.
- b. Activate the printer to advance to top-of-form.
- c. Turn power off.
- d. Open drum gate and ribbon mask.
- e. Rotate the horizontal paper tension adjustment to obtain the proper horizontal tension (see Fig. 3). Proper horizontal tension is indicated when the tractor teeth just begin to deform the outer edges of the paper holes.

- f. Rotate the vertical paper tension adjustment to obtain the maximum vertical tension (see Fig. 3). Proper vertical tension is indicated when the upper and lower tractor teeth just begin to deform the top and bottom edges of the paper holes.
- g. Check paper for a smooth, taut surface between all four tractors.

CAUTION

Slack paper can cause the paper to tear or break during printing. Slack paper will also cause poor vertical registration.

- h. Remove any wrinkles or slack by simultaneously readjusting the appropriate horizontal and vertical tension controls as required.
- i. After the cover is secured and the doors closed, the printer is now prepared to operate.



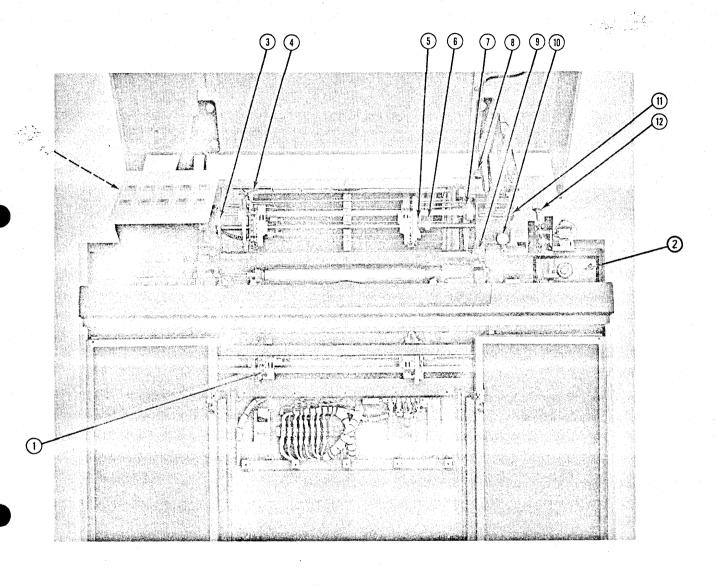
LPE 200

OPERATORS CONTROL PANEL

fig. 2

A 20752

figure



- 1. TRACTOR (ONE OF FOUR)
- PHASING CONTROL 2.
- 3. HORIZONTAL PAPER POSITION ADJUSTMENT
- 4. TRACTOR CLAMP
- 5. HORIZONTAL PAPER TENSION ADJUSTMENT (ONE OF TWO)
- 6. TRACTOR LOCK (ONE OF TWO)

- VERTICAL PAPER POSITION INDICATOR 7.
- 8. PAPER DRIVE RELEASE LEVER, VERTICAL
- COPIES CONTROL 9.
- VERTICAL PAPER TENSION ADJUSTMENT 10.
- VERTICAL PAPER POSITION ADJUSTMENT 11.
- DYNAMIC VERTICAL PAPER POSITION 12. **ADJUSTMENT**

OPERATING CONTROLS AND INDICATORS

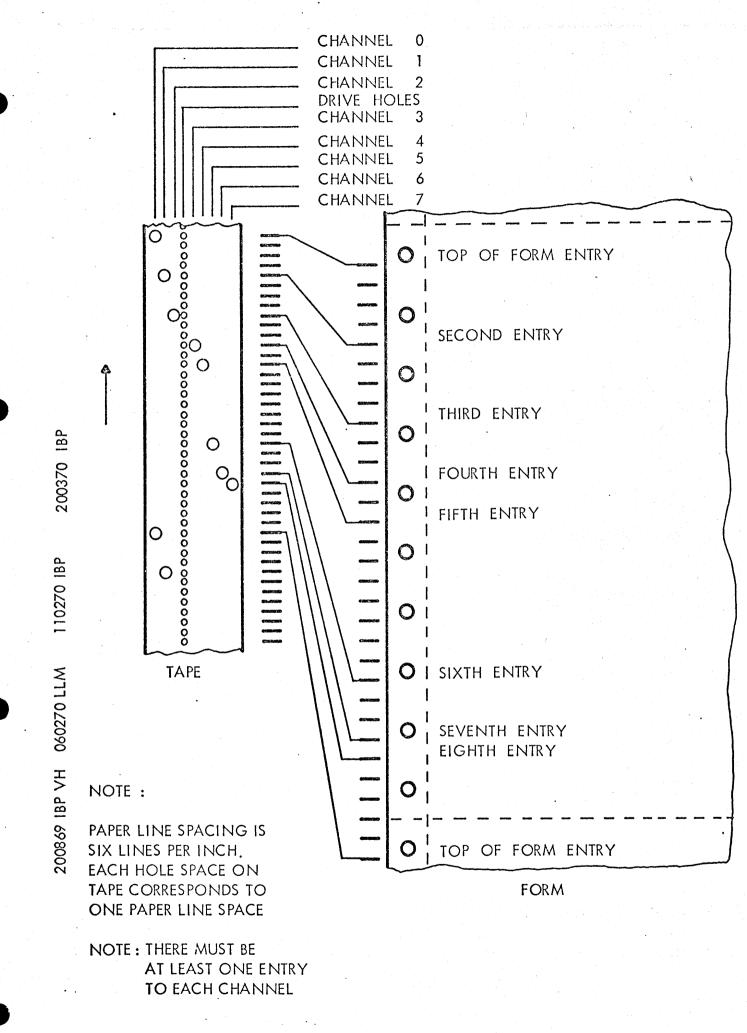
Fig 3

- 190869 IBP-VH 290170 LLM 110270 IBP 200370 IBP
- UPPER SPRING LOADED HUB RIGHT RIBBON GUIDE
- 2.
- 3. DRUM GATE
- 4. UPPER DRIVE HUB
- 5. 6. UPPER SPOOL KEY
- UPPER RIBBON MOTOR

- LEFT RIBBON GUIDE
- LOWER RIBBON MOTOR
- 9. LOWER SPOOL KEY
- LOWER DRIVE HUB 10.
- RIBBON MASK ASSEMBLY 11.
- 12. LOWER SPRING LOADED HUB

RIBBON INSTALLATION AND REMOVAL

Fig 4

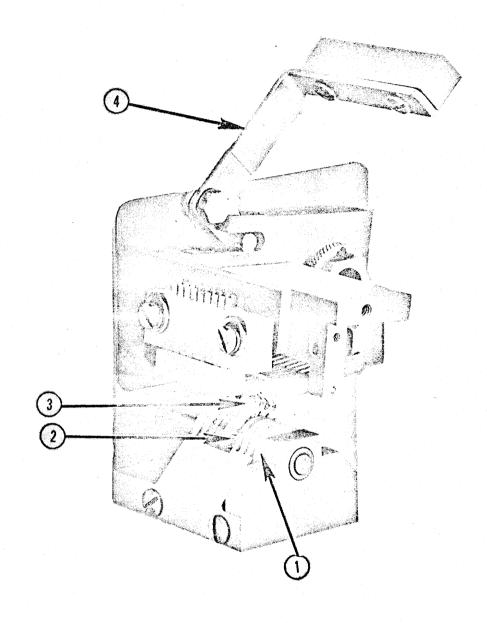


LPE 200

TAPE - LOOP PREPARATION

fig. 5

A 20751



- 1. CAPSTAN
- 2. DRIVE SPROCKET

- 3. DRIVE SPROCKET SHOE
- 4. HANDLE

TAPE LOOP READER

Fig 6

LPE 200 A20745

Figure

Optional available are

5.1

- HT Horizontal tabulation, causes moving of the print position to the next print position which is divisible by 16.
- SO Shift out, causes the printer to interpret the following character codes according to the table for shift out.
- SI Shift in, returns to standard character code assignment.
- CAN Cancel, causes reset of the line buffer, Shift in, and return of print position to first position.
- ESC Escape, is used to expand the control character set. An escape sequence for the printer must have a certain structure to be valid

ESC n NL

ESC n VT

where n is one of the characters of column 48, where only the four least significant bits are taken into account for the function. Any other structure acuses the ESC character to be ignored.

ESC n NL causes printing of one line followed by a paper feed of n lines (0 < n < 15).

ESC n VT causes printing of one line followed by a paper feed controlled by the format tape track n.

NOTE

ESC O NL is equivalent to CR

ESC O VT is equivalent to FF.

Tables for preventive maintenance list the preventive maintenace routines and the suggested intervals for those routines. The recommended procedures have been derived empirically and necessarily reflect several assumptions. An operation criterion of a 16 hour day, five day week is used. The recommended intervals are those required to ensure maximum and consistent print quality at a high duty cycle over an extended period of time. Applications, for which qualitative demands are less stringent, may utilize a more liberal maintenance schedule. The procedures also assume a typical data processing environment. The referenced procedures for the routines will elaborate on any possible occurences that may effect the intervals.

Character Drum Cleaning

6.1.1

Accumulated ink or other residue may be removed from the character drum with denatured alcohol, trichloroethylene or equivalent. It should be noted a suggested weekly interval is usually required to ensure the very best print quality. If the application allows, this interval may be extended without affecting the reliability of the equipment.

Each time the character drum is cleaned, the housing mounting the drum should be vacuumed. The operator should remove any ribbon or paper residue that may have accumulated within the housing.

Filter Cleaning

6.1.2

When the filters are dirty, use vacuum or compressed air to remove accumulated dust from metal fibers. The recommended procedure is to remove the filters from the printer and blow with clean compressed air. The filters are accessed by loosening the four quick-turn screws. Refer to 6 for preventive maintenance scedule.

Lubrication

6.2

Fig. 7 illustrates the location of the various printer mechanism lubrication points. Use oil supplied with the printer or use any of the following oils:

Gulf Harmony no. 53, Gulf Oil Company Standard 35, Standard Oil Company of California Caloloc Turbine Oil no. 15, Standard Oil Company of California.

CAUTION

Use oil sparingly and keep all exposed surfaces free of oil to prevent accumulation of dirt, lint or paper dust.

Ribbon Motor Lubrication

6.2.1

The ribbon drive motors should be oiled at intervals of six months. Open the drum gate and apply five drops of oil to each lubrication hole provided in the upper ribbon motor housing. Lower ribbon motor lubrication holes may be accessed with the drum gate closed by means of a pressure gun. After allowing 15 minutes to permit oil to penetrate, wipe motors clean of any oil which may bleed from holes after drum gate has been in closed position following lubrication.

Tape Loop Reader Lubrication

6.2.2

At intervals of six months, apply one or two drops of oil to each of the two oilite bearings supporting the tape loop sprocket shaft. Use pointed stick or toothpick, applying oil on shaft against end of bearing.

Tractor Shaft Lubrication

6.2.3

When the tractor(s) do not slide freely on shaft, a few drops of oil should be applied about the area that the tractors slide on the shaft. After sliding the tractors in both directions along the shaft, wipe shaft clean of any excess oil.

Additional Lubrication Points

6.2.4

The following points should also be lubricated, at six month intervals, with one or two drops of oil applied to the point of the contact area.

- a. Vertical paper position adjustment threads.
- b. Vertical paper tension adjustment threads.
- c. Horizontal paper position adjustment threads.

18P	
200370	
AL 0	
200370	
LLM	
200370	
200370 IBP	

	MAINTENANCE TIME			10 minutes to clean	2 minutes	10 minutes per hammer	5 minutes per tractor to align	5 minutes per tractor to adjust
	REFERENCE PROCEDURE			6.1.3	6.2.3			*
MAINTENANCE TIME SCHEDULE	INTERVAL	Daily	Daily	Weekly or every 80 operating hours.	Weekly or every 80 operating hours,	Weekly or every 80 operating hours.	Monthly or every 320 operating hours.	Monthly or every 320 operating hours
TABLE PREVENTIVE MAIN	ROUTINE	Visually inspect paper track areas for excessive paper dust, Vacuum if required,	Ensure that cooling blower is maintaining positive air pressure to hammer bank and paper feed assembly.	Inspect drum for excessive ink or paper dust residue. Clean if necessary, Vacuum drum gate assembly.	Check tractors for mobility along splined shaft. Oil if necessary.	Check vertical registration of individual characters. Adjust hammer (s) if necessary.	Check tractor alignment.	Check tractor chain tension.
		* refer to	Model	dp/p-4300)			

Model dp/p-4300 INSTRUCTION MANUAL MECHANICS 208716-1 Revision D Sept. 1967

200370 IBP 200370 LLM 200370 JA 200370 IBP

	TABLE PREVENTIVE MAINTENANCE	TIME SCHEDULE (CONTINUED)	UED)	•
	ROUTINE	INTERVAL	reference Procedure	MAINTENANCE TIME
* refer to	Check cooling air filter mounted below the blower. Clean if re – quired.	Bi-monthly or every 120 hours of op- eration	6.1.2.	5 minutes to clean
Model dp/p - 43	Check paper drive belt tension and wear. Adjust or replace if required.	Monthly or every 320 operating hours.		5 minutes to clean, 20 minutes to adjust, 45 minutes
00	Check tractor phasing	Quarterly or every 1280 hours of op- eration.	*	15 minutes to adjust
	Check hammer back stop screw for wear. Adjust hammer or replace back stop screw as required.	Semi – annually or every 2560 hours of operation		10 minutes per hammer or back stop screw
	Inspect all mounting screws, bolts and nuts to ensure that they are securely fastened.	Semi – annually or every 2560 hours of operation.		30 minutes
	Oil all lubrication points.	Semi-annually or every 2560 hours of operation,	9 3 3 3 3 3 3 3 3 3 3	10 minutes

* refer to Model dp/p - 4300 INSTRUCTION MANUAL MECHANICS 208716-1 Revision D Sept. 1967

Upper Ribbon Motor 1.

200869 IBP-VH 290170 LLM 110270 JA 200370 IB

- 2. Lower Ribbon Motor
- Horizontal Paper Position Adjustment
- 3. 4. Splined Shaft (One of Two)
- Horizontal Paper Tension Adjustment (One of Two)
- 6. Vertical Paper Tension Adjustment
- Vertical Paper Position Adjustment 7.
- 8. Tape Loop Oilite Bearings
- Never Move or Loosen Ribbon Note: Mask Socket Head Screws (2) (In Upper Cutout)

LPE 200

LUBRICATION POINTS

Fig 7

A20750

Figure

	-
•	7
	٠

Pape		7.1
a)	Dimensions	
	Standard edge punched 1/2 inch centers fanfold paper from	
	4,5 to 19 inches in width.	
b)	Types	
	Up to six parts, 12-pound bond (single minimum weight, 15-	
	pound bond; or tabulating card (0.007 inch) plus a second	
	record sheet.	
Rib	bon	7.2
The	printer uses standard 14 inch by 15 yards long, inked roll	
rib	bon of high quality fabric.	
Tap	e variation of the control of the	7.3
The	printer uses standard 8-channel business machine tape to con-	
tro	l paper stepping. Paper, Mylar or aluminum tape may be used.	
How	ever paper tape has a very short lifetime and may decrease	
ope	rating reliability. Mylar or aluminum tape is therefor recom-	
men	ded.	
Cle	aning	7.4
Acc	umulated ink or other residue may be removed from the character	
dru	m with denatured alcohol, trichloroethylene or equivalent.	
Lub	rication	7.5

Gulf Harmony no. 53, Gulf Oil Company Standard 35, Standard Oil Company Caloloc Turbine oil no. 15, Standard Oil Company. The LPE 200 is connected to the RC4000 Low Speed Data Channel. For signal specifications refer to the description of RC4000 DATA CHANNELS. (Low speed).

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a) Power

1.4 KW

b) Voltage 220 VAC - 10 0/0
Alternative voltages are RC standard

90 - 100 - 110 - 120 - 130

200 - 210 - 220 - 230 - 240 VAC + 10 0/0

All voltages input are 1-phase, 3-wires

Phase

Neutral

Ground

c) Frequency 50 Hz + 2 0/0

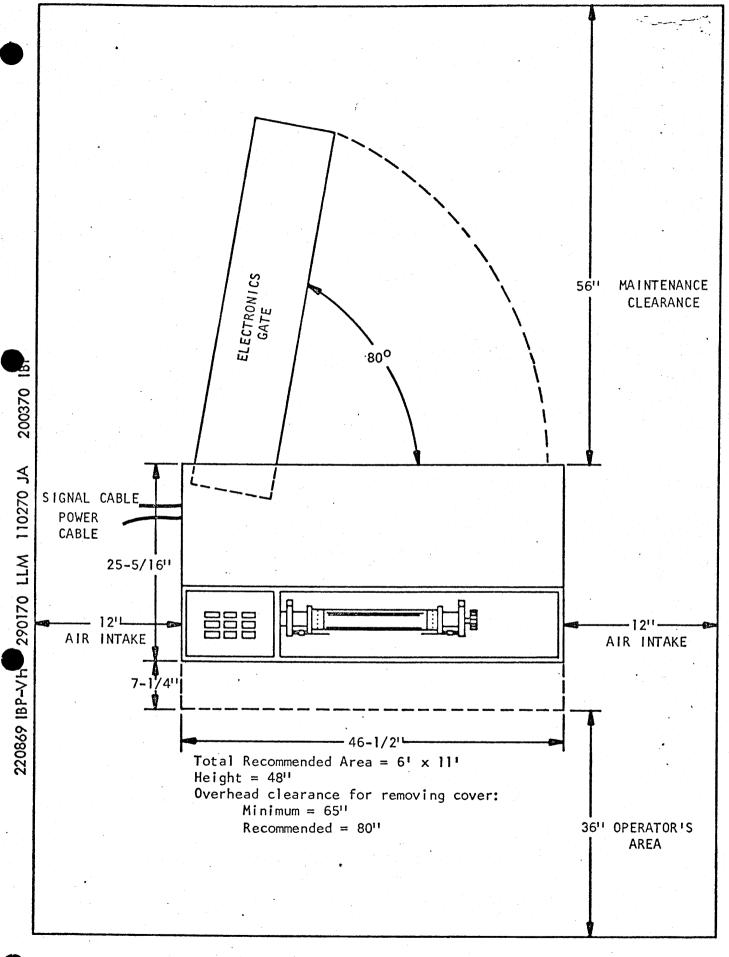
Environmental Conditions

10.1

- a) Operating $10^{\circ}\text{C} (50^{\circ}\text{F}) \text{ to } 38^{\circ}\text{C} (100^{\circ}\text{F}) \text{ at}$ 20 0/0 to 80 0/0 relative humidity.
- b) Storage
 -18°C (0°F) to 52°C (125°F) at
 5 0/0 to 95 0/0 relative humidity.

PHYSICAL CH.	ARACTERIS	TICS		11
Demensions		119 cm (47 in)		11.1
	Depth	66 cm (26 in)		
	Height	122 cm (48 in)		
Weight	400 kg	; (850 lbs) app.		11.2
Installation	n Disoram	(See Fig 8)		11.3

AA158



LPE 200

INSTALLATION DIAGRAM

Figure

Fig 8

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13.1

Bus Receivers

Logic diagram 3.

For detailed information on the I/O BUS lines 17:23 refer to the RC4000 Data Channel (low speed) in section 8.

Test Information

13.2

Logic diagram 22.

The seven bit input code can be simulated from the Sim 0-6 lines. The weight of the bits is as follows:

Sim 0 1 2 3 4 5 6 Weight 1 2 4 8 16 32 64

For further information refer to section 20 - 20.8.

Data Gates

13.3

Logic diagrams 23, 24, 25.

Data input to Reg 1 can be one of four:

- 1. from line 23...17 (seven bit input code)
- 2. from character converter 0-8
 (eight bit internal code and parity)
- 3. from similator 0-6
 (seven bit input code)
- 4. from Line buffer output SR 0-7, P, M
 (eight bit internal code, parity, and mark)

Register 1 and 2

13.4

Logic diagrams 23, 24, 25.

Together with Reg 2 the Reg 1 forms the 133rd column in the line buffer (132 printable columns and 1 check character column).

Reg 1 and Reg 2 are 10 bits flip-flop registers, the bits have the following weight:

REG 1, REG 2 0 1 2 3 4 5 6 7 P M
Weight 1 2 4 8 16 32 64 128 P M

Read Only Store

Logic diagrams 27, 28, 29, 30

The printer accepts input characters according to the ISO 7-bit code. The graphics are internally represented by their character number on the character drum, referring to the Index pin.

As the input characters and the character numbers are not identical, the input characters are to be converted to the internal code.

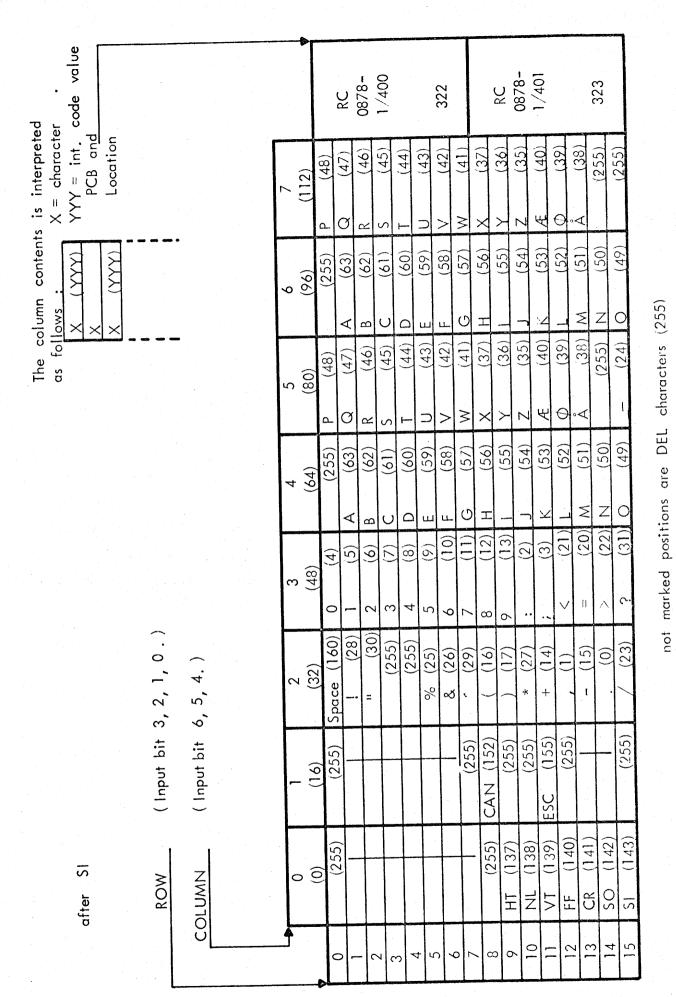
The 7-bit input code can be one of four variants:

Input Code Tables available are

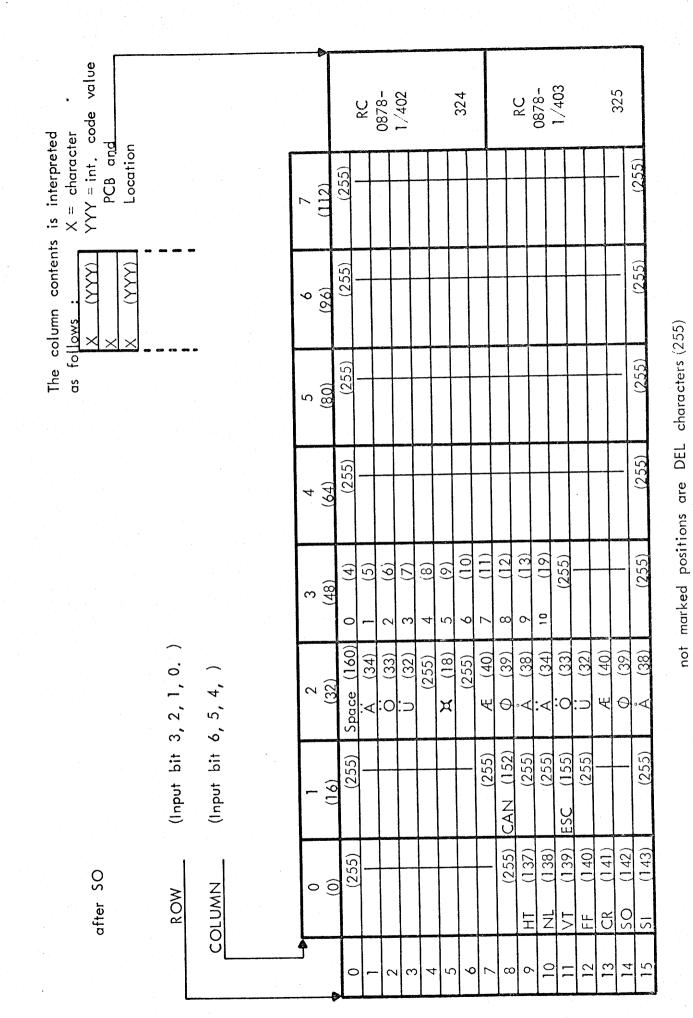
- 1. Input Code Table,
 RC-Standard
 for 64 char. drum, RC-standard.
- 2. Input Code Table,
 RC-Standard incl. Options
 for 64 char. drum, RC-standard
- 3. Input Code Table,
 RC-Standard
 for 96 char. drum, RC-standard
- 4. Input Code Table,
 RC-Standard incl. Options
 for 96 char. drum, RC-standard.

														-			
is interpreted X = character YYY = int. code value PCB and Location			RC	0878-	1/400			322			RC C	0878-	1/407			323	
The column contents is interpreted as follows: $X = \text{character}$ $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	7 (112)	(48)	(47)	(46)	(45)	(44)	(43)	(42)	(41)	(37)	(36)	(35)	(40)	(36)	(38)	(255)	(255)
* * * * * * * * * * * * * * * * * * *		۵ـ	Ø	œ	S	 	\supset	>	≥	×	>	7	¥	0	۰∀		
(YYY)	96)	(255)	(63)	(62)	(61)	(09)	(59)	(58)	(57)	(56)	(55)	(54)	(53)	(52)	(51)	(50)	(49)
o o o o o o o o o o o o o o o o o o o			A	В	U	۵	ш	ᄔ	O	듸		_	\forall	_	≥	Z	0
The column as follows X X X X X X X X X X X X X X X X X X X	5 (80)	(48)	(47)	(46)	(45)	(44)	(43)	(42)	(41)	(37)	(36)	(35)	(40)	(39)	(38)	(255)	(24)
		Ь	Ø	×	S	-	Ω	>	≷	×	>	7	¥	0	∘∢	_	
	4 (6.4)	(255)	(63)	(62)	(61)	(09)	(26)	(58)	(57)	(56)	(55)	(54)	(53)	(52)	(51)	(50)	(46)
			⋖	В	U	۵	ш		C	I		<u> </u>	\propto	_	X	Z	0
	3	(4)	(5)	(9)	(7)	(8)	(6)	(10)	(11)	(12)	(13)	(2)	(3)	(21	(20)	(22)	(3)
		c	-	_	<u>س</u>	4	5	9	7	8	6		• \	>		^	0
1, 0,)	2 (22)	(160)	1		(255)	(255)	% (25)			(16)	(17)	(27)		(1)	- (15)		(23)
3, 2, 6, 5,		Snace		=			0	∞	`			*	+		1		
(Input bit 3,	- 5	(255)	-														(255)
		055)	777					 			(255)	(138)	(139)	(140)	(141)	(255)	(255)
ROW	0 9											Z	\ \ \	<u>Н</u> ц	2	j	
	_	c		- (2 2	> <	t v		7	, a	0	10	7	12	12	14	15

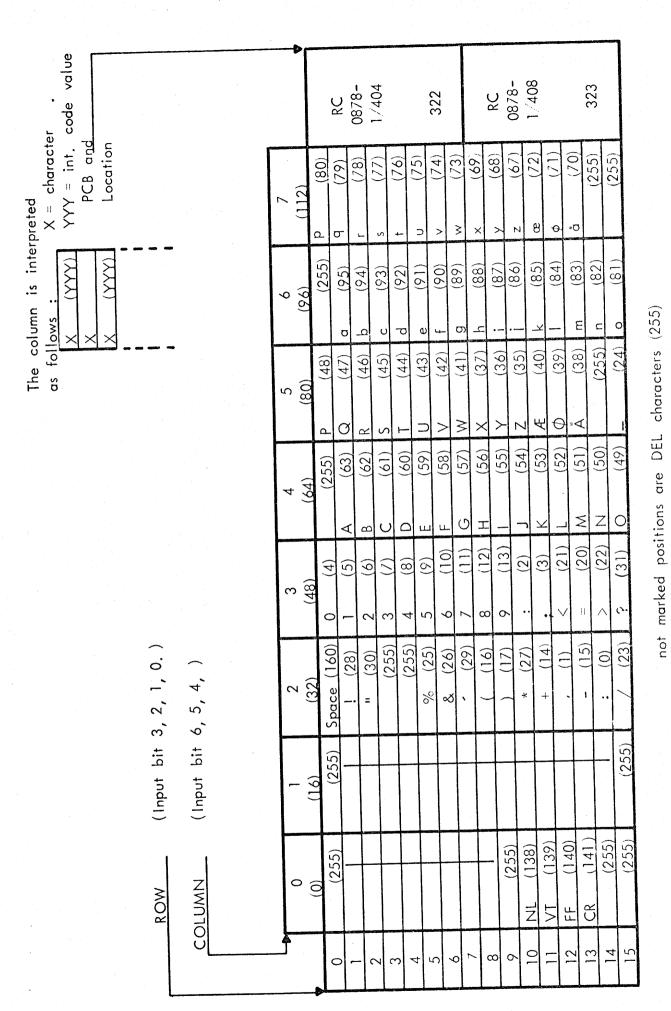
Input code table RC - standard



Input code table
RC - standard incl Options
for
64 char. drum , RC - standard

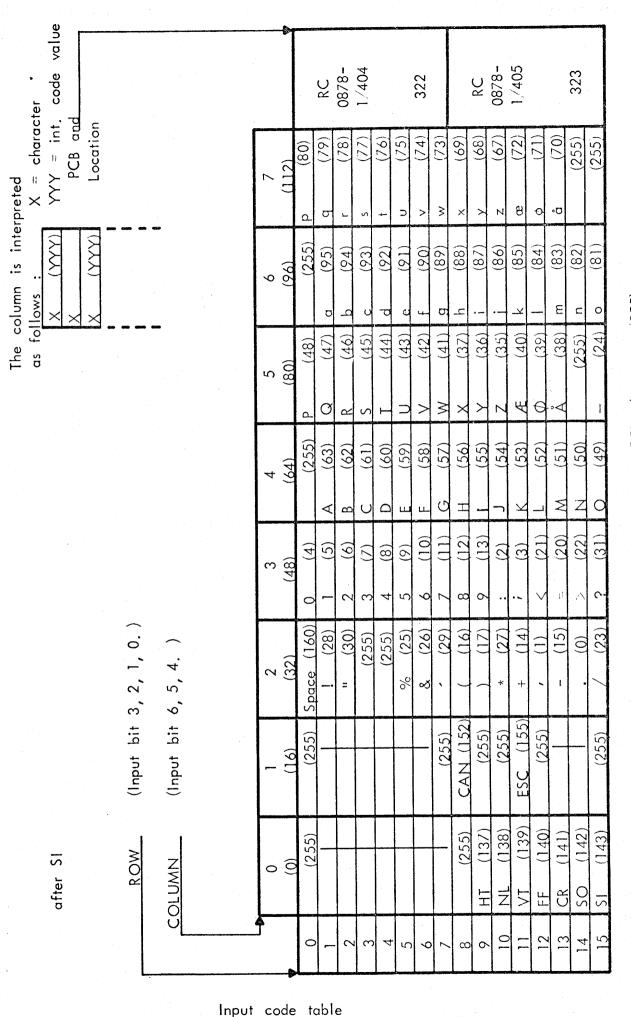


Input code table RC - standard incl. Options for 64 char, drum, RC - standard



Input code table RC - standard for 96 char. drum, RC - standard

13 - 2 -4

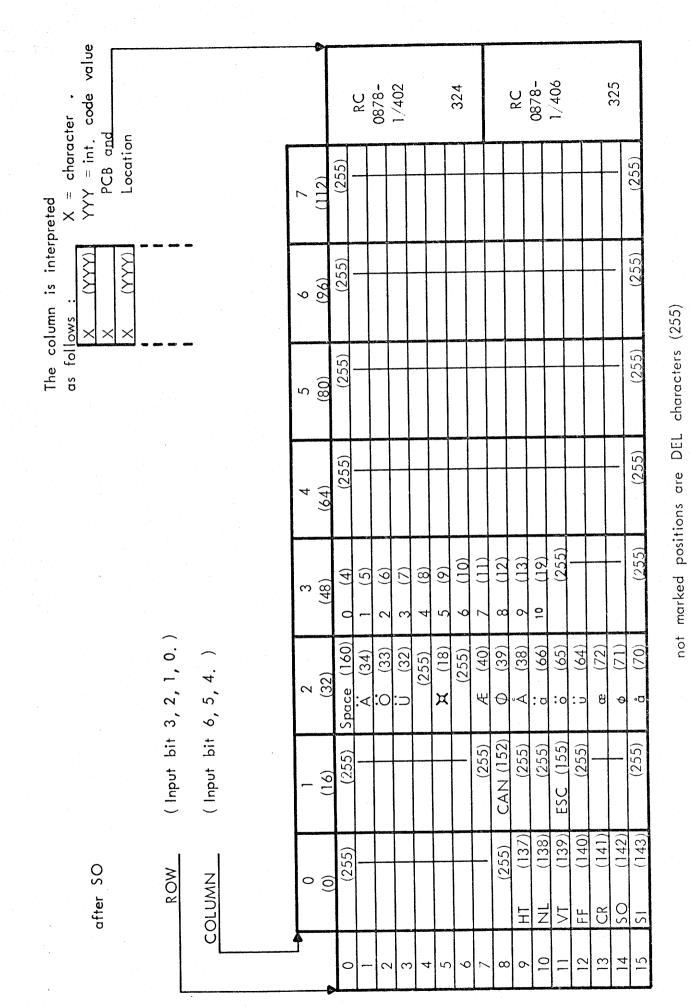


RC - standard incl Options,

RC - standard

96 char. drum,

not marked positions are DEL characters (255)



Input code table
RC - standard incl. Options,
for
96 char. drum, RC - standard

Character converting system.

The seven bit input character is loaded into the seven least significant bits of Reg 1, where the bits have the following weight:

The input character value determines the address in the Read Only Store where the internal character code is loaded (fixed wired). The Read Only Store is a 9-bit 128 (optional 256) words store. After convertion the internal character code is loaded into the nine least significant bits of Reg 1.

Line Buffer

13.6

Logic diagram 31.

The line buffer is a 12-bit 132 columns Shift register for storing one line.

The Shift register bits have the following weight:

SR-(0-6) = 128 graphic characters.

SR-7 = control character indication.

SR-P = parity (odd parity in SR-(0-7, P, M)).

SR-M = mark, indicates that the character has been printed.

SR-ECO

SR-EC1 = two bits for storing numbers of ECHOes detected.

The Line buffer and Reg 1, Reg 2 are coupled to work as a 133 columns cyclic shift register, i.e. 132 graphic characters and the check character.

Parity Check

13.7

Logic diagram 57.

The information stored in REG 1-(0-7, P, M) is checked for odd parity in two (optional three) levels.

PF inp. (optional)

During load of input characters the parity is checked. If a parity error is detected the input character is deleted.

PF con.

After convertion to internal code the parity is checked. If a parity error is detected, the input character is deleted.

PF memory

During the total print period the characters loaded into the line buffer is checked for odd parity. If a parity error is detected in a character the character will be marked, i.e. the character is not to be printed. If the parity error is detected after the character has been printed, the character will be marked too.

Check of Check Character Logic diagram 58.

13.8

Before each new shift period during the total print period the information loaded in REG 2-(0-7, P, M) should be the check character, if not, the check error is detected to indicate that something is wrong in connection with the shift sequence.

The check character has the following code

REG 2 bit 0 1 2 3 4 5 6 7 P M
0 0 0 0 0 0 1 1 1

Mark Logic

13.9

Logic diagram 42.

All columns in the line buffer have a mark bit position. The mark bit indicates if the character stored in the column has been printed. During load of the line all mark bits are cancelled except for the check character.

When coincidence is found in a column, i.e. the character is to be printed, the mark bit is added and the parity bit is inverted. If a parity error is detected during print, the column is marked so that the character will not be printed later on.

During Reload, i.e. loading the line just printed, mark bits will be cancelled, except for the check character and the parity bit will be inverted. Column Counter and Decoding

Logic diagrams 37, 38, 39.

The column counter is an eight bit resetable counter, where counting can be inhibited. The column counter bits have the following weight:

The column counter bits are decoded in two groups.

one for 16-X-decoding lines and one for 16-Y-decoding lines.

The decoding lines are used for addressing the 132 hammer drivers and for some control functions.

Index and Char. Strobe

13.11

Logic diagrams 43, 44, 45.

The character drum is equipped with an Index pin determining the beginning of the character drum, a Character Count wheel, determining the beginning of a new character, and two pick-ups for generating index pulse respectively character pulses.

The pick-up pulses are amplified and fed into the Index and Character Strobe logic (logic diagrams 44, 45).

Character Strobe phasing adjustment can be done at two levels,

- 1. Operators Phase Adjustment
- 2. Technicians Phase Adjustment.

Maximum adjustment for each of the two adjustments will be no more than half the total variation.

Character Counter

13.12

Logic diagram 46.

The character counter is a 7-bit resetable counter.

The character counter bits have the following weight:

Char. count 0 1 2 3 4 5 6 1 2 4 8 16 32 64

The CHAR STR advances the Character Counter by one.

As the Index determines the reset point, the contents of the counter will always be the character number referring to the Index.

Character drums available are

- 1. 64 char. drum, RC-standard
- 2. 96 char. drum, RC-standard

64 char. drum, RC-standard.

D-P art work:

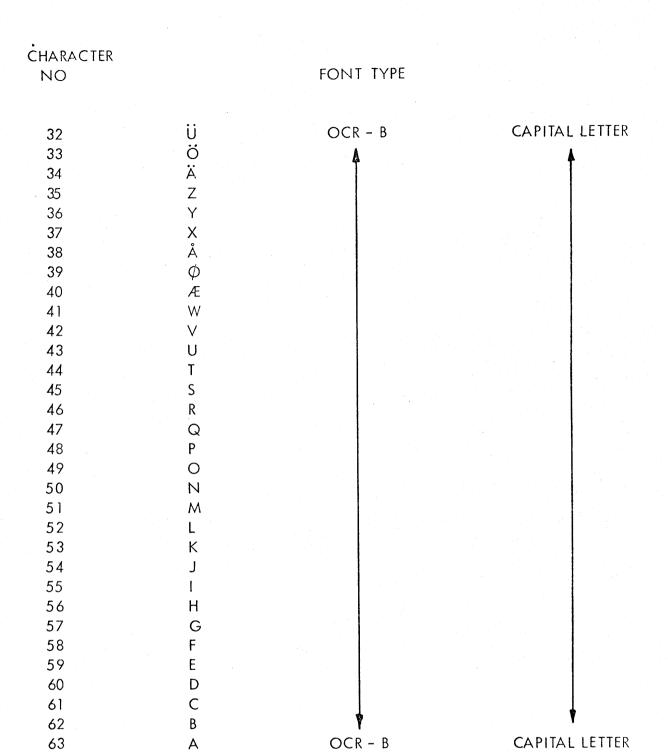
A/W 213440 4300.

FONT TYPE

Except for the 10 (basis of ten) character, all characters are OCR-B FONT TYPE.

The _(underline) character is located on the baseline.

CHARACTER NO		font type	
0	•	OCR – B	period
1			comma
2			colon
3	;		semicolon
4	0		zero
5	1		one
6	2		two
7	3		three
8	4		four
9	5		five
10	6		six
11	7		seven
12	8		eight
13	9		nine
14	+		plus
15	-		minus
16	(open parenthesis
17)	▼	closed parenthesis
18	Ħ ,	OCR - B	currency sign
19	10		basis of ten
20	=	OCR - B	equal
21	<		less than
22	>		great than
23			sl ash
24	_		under line
25	%		percent
26	&		ampersand
27	*		asterisk
28	!		exclamation
29	•		apostrophe
30	II .	V	quotation mark
31	?	OCR - B	question



96 char. drum, RC-standard.
D-P art work:
A/W 213520 4300.

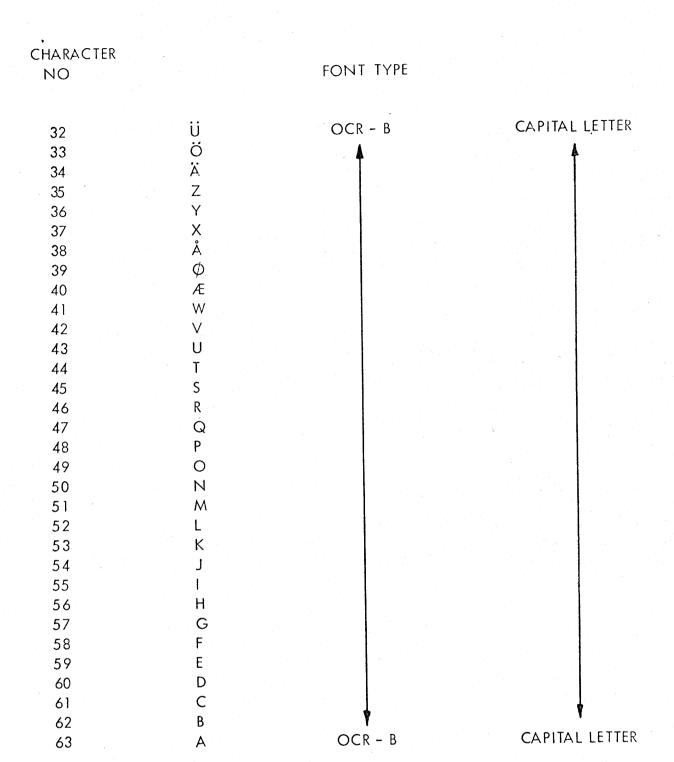
FONT TYPE

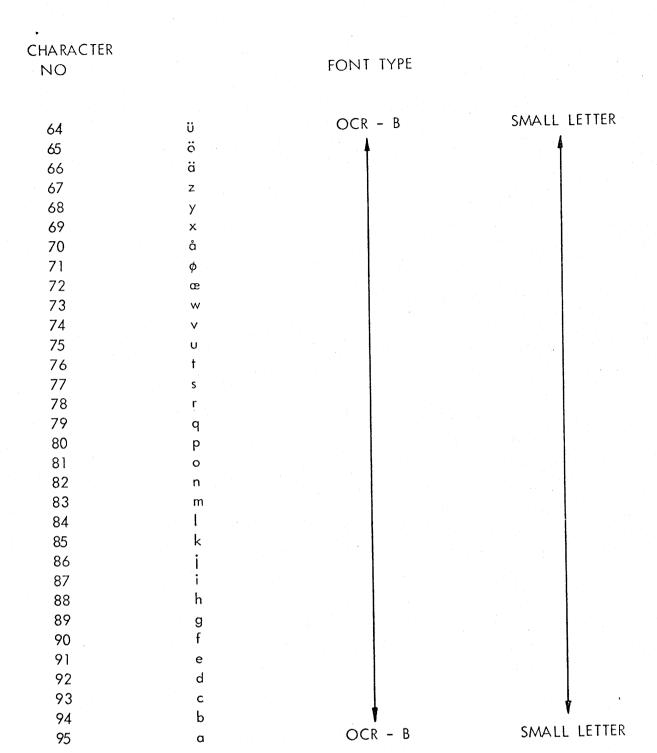
Except for the 10 (basis of ten) character, all characters are OCR-B FONT TYPE.

The _(underline) character is located on the baseline.

NO		F	ONT TYPE	
0	•		OCR – B	period .
. 1			A	comma
2	:			colon
3 3	•			semicolon
4	; 0			zero
5	1			one
6	2			two
7	3			three
. 8	4			four
9	5			five
10	6			six
11	7			seven
12	8			eight
13	9			nine
14	+			plus
15	e de la companya de l			minus
16	(open parenthesis
17)		•	closed parenthesis
18	Ħ		OCR - B	currency sign
19	10			basis of ten
20	=		OCR - B	equal
21	<		A	less than
22	>	**		great than
23	/			slash
24	_			under line
25	%			percent
26	&			ampersand
27	*			asterisk
28	!			exclamation
29	/			apostrophe
30	H		♥	quotation mark
31	?		OCR - B	question
				•

CHARACTER





13.13

Comparator

Logic diagrams 47, 48.

During Print the character counter (CHAR COUNT 0-6) is compared with Line buffer output, SR (0-6), to indicate that printing of the Line buffer character is wanted. However, the coincidence will be inhibited if the Line buffer character is marked or a control character is loaded.

If printing of the character is wanted the COINcidence FF is set to enable the hammer strobe circuits.

Hammer Strobe Generator

13.14

Logic diagram 48.

If no inhibit situation exists the hammer strobe is generated by timing pulse T3.

Note that no hammer strobe is generated if Drum gate is open or Parity error in the Line buffer character or Paper Out.

Hammer Drivers

13.15

Logic diagrams 65, 66, 67, 68.

132 hammer drivers are used, one for each print position on the character drum.

If a hammer driver is selected by the CCX-decoding and CCY-decoding lines and a hammer strobe is present at the input, it means that the hammer is to be activated. When fired the hammer driver will generate an ECHO signal any time the driver is selected, every 940 uSec.

Normally the hammer driver will be fired for app. 1.8 mSec. The hammer drivers generate an output signal HAMMER CURRENT SENSING to indicate how long time the Hammer drivers are on. This signal is supervised for lasting less than 400 mSec. In case of error detecting the power to hammers and paper feed system will be released.

Paper Feed and Hammer Power Supply Figure 9.

13.16

The hammer power supply supplies the hammer drivers, and the hammer bank with +50V DC for driving the hammers. The paper feed power supply supplies the paper feed power amplifier with +35V, -35VDC for driving the paper feed motor.

Hammer Bank Refer to

> MODEL dp/p-4300 INSTRUCTION MANUAL MECHANICS 208716-1 REVISION D SEPT 1967.

NOTE, in the LPE 200 the hammers are numbered 0, 1, 2, 3 129, 130, 131.

Print Control Logic

13.18

Logic diagrams 40, 41, 64.

When, during load of the line, the full-line signal is detected and a print instruction has been loaded, speed check is started to secure that the char. drum is on speed before printing is initiated. If no drum speed error exists the print period will be started at the next character strobe. For detailed information refer to: General Information (Functional Description, section 1). The print period is terminated when all the printable characters have been printed, i.e. all columns with printable characters must include the SR-M bit, and not printable columns must include the SR-7 bit. The logic circuit for storage printed is shown on logic diagram 41.

Termination of the print period will start the Enable Echo Check period (wait for last possible echoes).

Speed

13.19

Logic diagram 58.

The char. drum speed is supervised for correct rotational time. As the character speed, 1070 char./sec = 940 uS/char., is the same for all sizes of character drums the 940 uS/char. is supervised for correct duration. The duration is supervised to be within the following limits:

883,2 uS < Time/char. < 985,6 uSec.

The lower and upper limits are defined by the column counter, values 138 respectively 154.

In case of error the SPEED FF will be set.

Echo

13.20

Logic diagram 62, 63, 64.

During the ECHO CHECK period all columns in the Line buffer are checked for correct ECHO, i.e.

printable columns must have 1 or 2 echoes not printable columns must have 0 echoes.

See logic diagram 64.

Refer to 13.15 (Hammer Drivers) for generation of ECHO signals. Detection of echoes takes place during the print and enable echo check periods. The detection circuits are shown on logic diagram 62.

The echoes detected in a column are stored in the EC(0-1) bits in the Line buffer, i.e. any column in the Line buffer after printing will hold the following information:

SR 0 1 2 3 4 5 6 7 P M ECO EC1

where

SR 0-6 are the character bits.

SR 7 is 0 for printable characters and 1 for not printable character.

SR P is the parity bit.

SR M is 0 for not printed columns and 1 for printed columns.

SR EC(0-1) is the numbers of echoes detected in the column.

On logic diagram 63 the echo counter REG 1-EC(0-1) is shown together with REG 2-EC(0-1).

Data SR-EC(0-1), stored number of echoes, can be transferred to the echo counter REG 1-EC(0-1). The echo counter is advanced by one if an echo is detected, and after this the new number of echoes in the column is stored together with the column information.

Counting in echo counter is inhibited if the REG 1-EC(0-1) = 1,1.

Paper Out and Drum Gate Open Logic diagram 60. 13.21

Paper Feed Control Logic

13.22

Logic diagrams 49, 50.

Loading of parameters for the following paper motion is done during the paper feed signal.

- 1. preset PCR and CNT
- 2. transfer to PCR and TPE/CNT
- 3. generate paper advance signal.

The circuits are shown on logic diagram 49.

The logic for start and stop of paper motion is shown on logic diagram 50 and so is the logic for the HI/IO velocity flip flop. The paper can be fed at two velocities. HI = 35 inch/sec and IO = 20 inch/sec.

The last line in a paper feed motion is always executed at the low velocity.

As the stop time for the paper is app. 5 mS the paper moving signal is needed to secure that no printing can be started until the paper is fully stopped. The logic for paper moving is shown on logic diagram 49.

Paper Control Register

13.23

Logic diagram 51.

In PCR(0-3) the parameter for the following paper motion is loaded.

If tape mode is selected the PCR will hold the number of the selected tape loop channel. Only the three least significant bits are taken into consideration. If count mode is selected, the PCR will hold the number of lines to be stepped, (max. 15 lines). During the count mode the PCR(0-3) is decreased by one for each

During the count mode the PCR(0-3) is decreased by one for each line strobe detected.

Normally the parameters loaded will be

instruction	mode	parameter
CR	CNT=1	PCR=O
NL	CNT=1	PCR=1
FF	TPE=1	PCR=0
٧T	TPE=1	PCR=1

If the ESC option is used the following parameters may be added to the above-mentioned.

instruction mode parameter ESC n NL CNT=1 PCR=n ESC n VT TPE=1 PCR=n

Tape Loop Register

13-12

Logic diagrams 53, 54, 55.

Tape loop register is an 8 bits register, one bit for each channel on the tape loop. The tape loop register will always hold the information from the position on the tape loop just sensed. On logic diagrams 54, 55 the logic for selecting a hole in the specified channel is shown too.

Strobe Generator

13.25

Logic diagrams 43, 44.

The paper feed drive assembly is equipped with a count wheel for line strobe and a pick-up. The pick-up signal is amplified and fed into the LSA and LSB logic on logic diagram 44.

LSA (line strobe A) is the transfer pulse which transfers tape loop information to the Tape Loop register.

LSB (line strobe B) is used in the paper control logic. e.g. timing pulse for Run/Stop, HI/LO, and count pulse for PCR during count mode.

Paper Feed Servo and Power Amplifier Logic diagram 52.

13.26

The Servo amp. input START determines the velocity wanted at the paper feed motion. From this START signal the Servo amp. generates a velocity ramp curve, which is compared with the DC tachometer reflected voltage. The difference between the ramp and the reflected voltage controls the servo output to the paper feed power

The paper feed power amplifier controls the forward reverse current to the paper feed drive motion.

The Servo amplifier output can be inhibited by the brake paper feed signal.

amplifier.

Time Out 13.27

Logic diagram 59.

The time out signal includes:

- Print cycle i.e. a print period has lasted more than app.
 sec.
- 2. Echo too long i.e. one or more echoes have lasted more than app. 3 mS.
- 3. Speed i.e. the char. drum is not on speed.
- 4. Paper feed too long i.e. the paper motion has lasted more than app. 10 sec., or the output to paper feed motor has been positive for more than app. 10 sec., or output to paper feed motor has been too negative for more than app. 10 sec.

Bus Receivers

Logic diagram 1.

For detailed information of the four I/O lines refer to the RC4000 low speed data channel. Section 8 in General information.

DEV. Connected and DEV. Ready

Logic diagram 6.

The Dev. connected signal indicates that all voltages are switched on and o.k.

The Dev. ready signal indicates that the printer is ready to accept input.

Bus Receivers 13.30

Logic diagram 2.

For detailed information on the I/O BUS lines 10-16 refer to the RC4000 low speed data channel. Section 8 in General information.

Command and Address Decoding 13.31

Logic diagrams 4, 5.

The only valid commands to the printer are Write and Sense commands. Only the basic command field is taken into consideration.

The Write and Sense commands are stored in the write and sense command flip flops respectively, for use during the data phase of the I/O operation.

The printer has a fixed wired Dev. number. When this number is present at the input lines 10-17 during the selection phase, the Dev. address decoding indicates that the line printer is addressed. The Sel B signal indicates that an I/O operation is in progress.

Interrupt and Status Logic

13.32

Logic diagram 7.

During remote opereration the printer generates an interrupt signal which indicates that the stored line has been printed and the paper motion has been started.

During Sense operation the printer status information is gated to the I/O BUS lines 0-5, via line transmitters. For detailed information refer to sections 3 and 4 in General information.

Clock and Timing

13.33

Logic diagrams 16, 17.

Clock Circuits

The clock generator is a 5 MHz free running square wave generator. By means of a count flip flop, a 2,5 MHz square wave pulse is derived from the 5 MHz clock pulse.

Timing Circuits

Mainly the timing circuits are designed to generate a sequence of four descrete timing pulses (T1-T4) for use in the printer logic. The timing circuits also generate a clock pulse (PB-CP) specially used in connection with the push-button logic.

For detailed information see Timing diagram TC7.

Basic Control Logic

13.34

Logic diagrams 18, 19, 20, 21.

The Basic Control logic can be started either from input or from character drum. On logic diagram 19 the selection is illustrated. During the Enable Timing F. Char. Str. period the control logic is started from the Char. drum. Otherwise it is started from input. Any new start of the control logic is synchronized by means of the SNT (1, 2, and 3) circuits, which resynchronizes the clock and timing circuits.

The synchronizing circuits are illustrated on logic diagram 20. On logic diagram 18 the logic for generating of transfer pulses is shown.

On logic diagram 21 the circuits for generating first char. of new line, Set check character, Char. to load and the End of Load function are shown. For further information refer to List of names.

Control Character Decoding

13.35

Logic diagrams 32, 33, 34, 35, 36.

All control characters are internally represented by their input value plus the 128 bit. The decoding of the 32 control positions is shown on logic diagram 32.

The Delete decoding, also shown on logic diagram 32, is a full decoding of 8 bits.

The NSC logic is shown on logic diagram 33, for further information refer to List of names.

The SO/SI FF on logic diagram 33 indicates if the following characters are to be found either in the Shift out or in the Shift in part of the input code table. Normally the printer only will be equipped with the Shift in part of the input code table. Refer to section 5.1.

On logic diagram 34 the logic circuits for HT and ESC are illustrated. HT and ESC functions are optional, refer to section 5.1. The logic circuits for the four paper instructions are illustrated on logic diagrams 35 and 36.

During character load the paper instruction flip flops are controlled from the control character decoding lines.

During Auto load the paper instruction flip flops are controlled from the Form mode, Line mode.

n-Logic and n-Reg.

13.36

Logic diagrams 18, 26.

The ESC n (NL, VT) function (optional) is described in section 5.1. Before convertion the four least significant bits of the input character are transferred to the n-Reg. The weight of the bits are:

The contents of the n-Reg. is used as parameter for the following paper feed instruction.

The correct structure of the ESC n (NL, VT) function is supervised on logic diagram 18. the n-FF indicates if structure is correct.

Logic diagrams 9, 10, 11, 12, 13.

The logic circuits for Local/Remote and Local Start/Stop switches are illustrated on logic diagrams 9 and 10.

Any time the Local/Remote switch is activated the Remote FF2 will generate one pulse, duration 6,4 uS.

Any time the Local Start/Stop switch is activated the St/St FF2 will generate one pulse, duration 6,4 uS.

The Remote flip flop indicates if the line printer is either in the Remote state or in the Local state. For further information refer to section 4.3.

Stop indicates if:

- a. it is wanted to shift from Remote to Local or
- b. it is wanted to stop the running testprint.

End indicates if:

- a. shifting from Remote to Local can be performed or
- b. terminating of the running testprint can be performed.

Testprint indicates that a testprint operation is in progress.

Paper feed Local indicates that a paper operation is in progress.

Testprint and Paper feed Local are controlled from the operators control panel and the maintenance panel (refer to section 20, OFF line operating).

Operators Control Indicators

13.38

Logic diagrams 14, 15.

The Remote/Local indicators are described in details in section 4.3.

The LOCAL Start/Stop indicators are described in section 4.5. Refer to section 4.6 and 4.7 for the Form mode/Line mode resp. Testprint/Paper feed description.

External Indicator

13.39

Logic diagram 8.

The RC4000 Operator Control panel two indicator lamps are located one for the Remote state and one for the Local state.

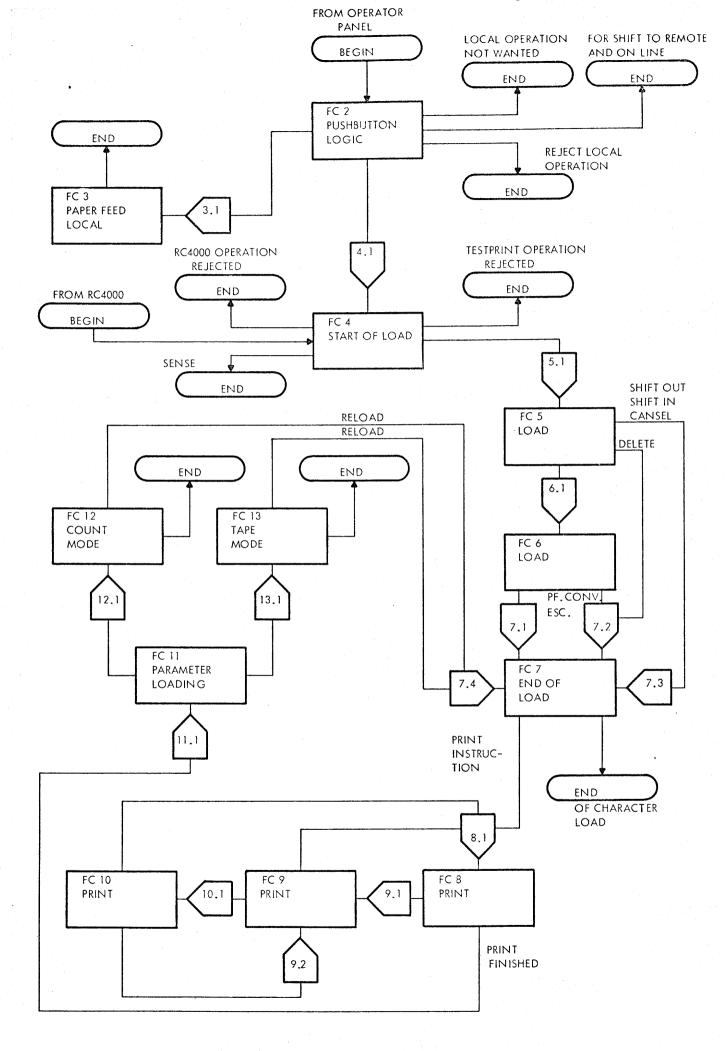
The control and driver circuits are illustrated on logic diagram 8.

13.40

Indicator Logic

Logic diagram 61.

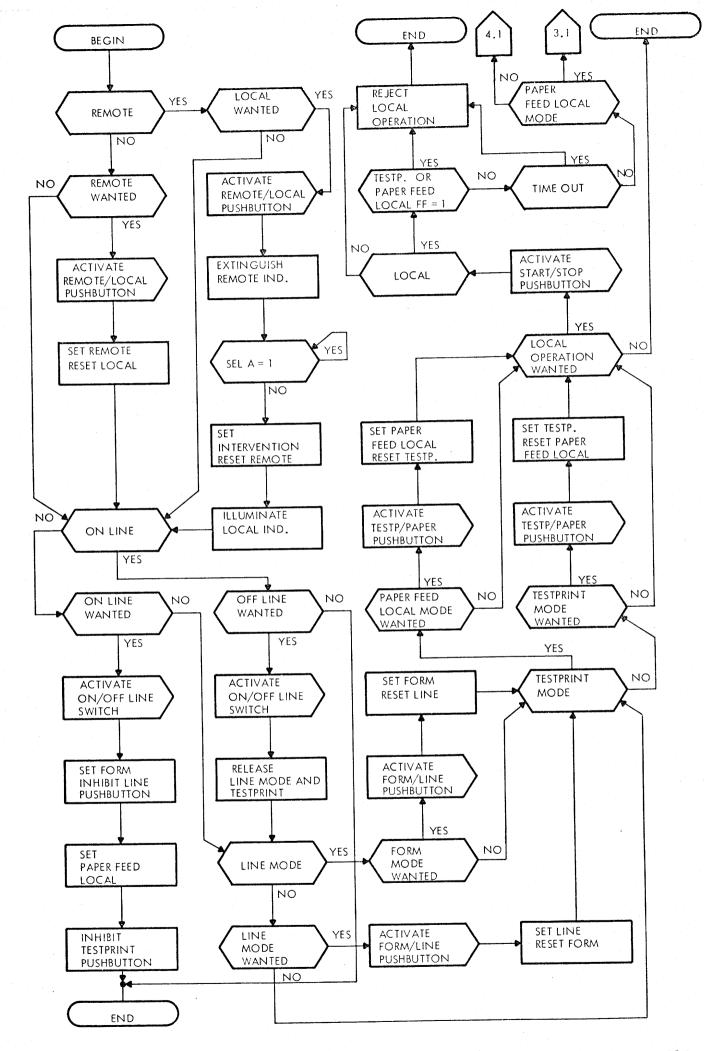
For detailed information of Operable indicator, Paper out indicator, and Parity indicator refer to sections 4.2 and 4.4.



LPE 200

FLOWCHART SURVEY

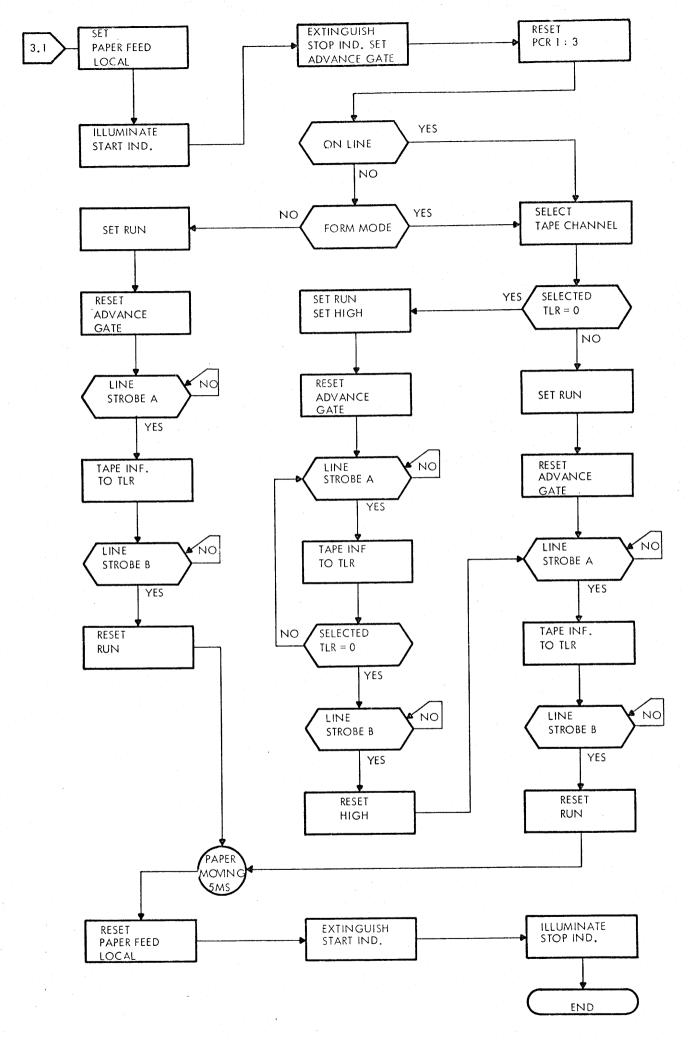
FC 1



LPE 200

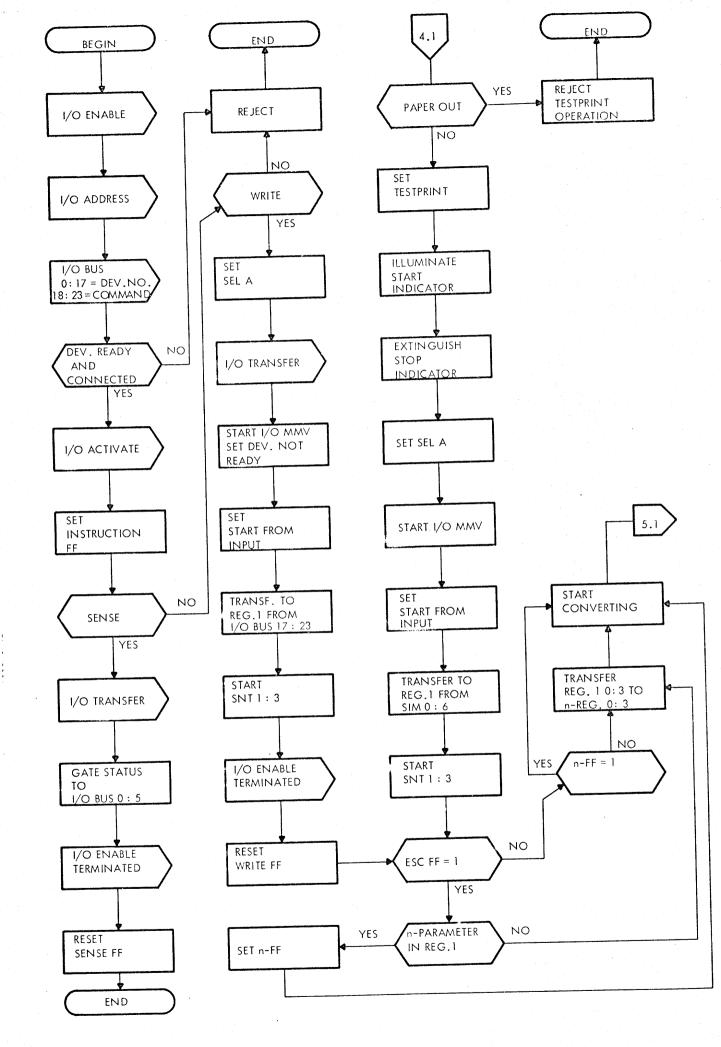
PUSHBUTTON LOGIC

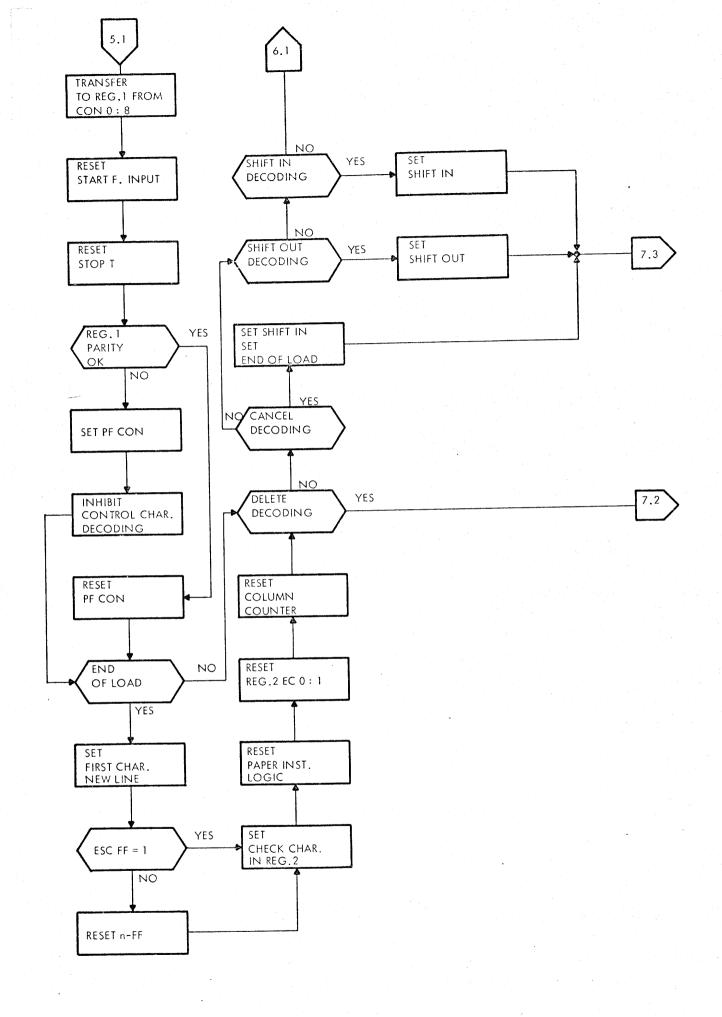
FC 2



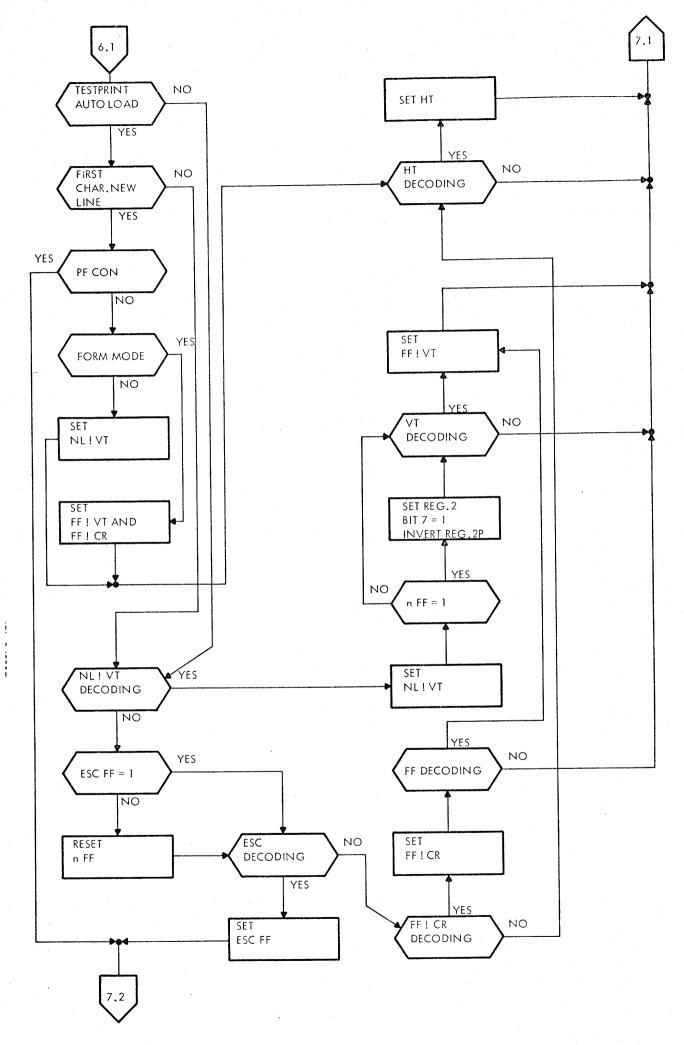
PAPER FEED LOCAL

FC³

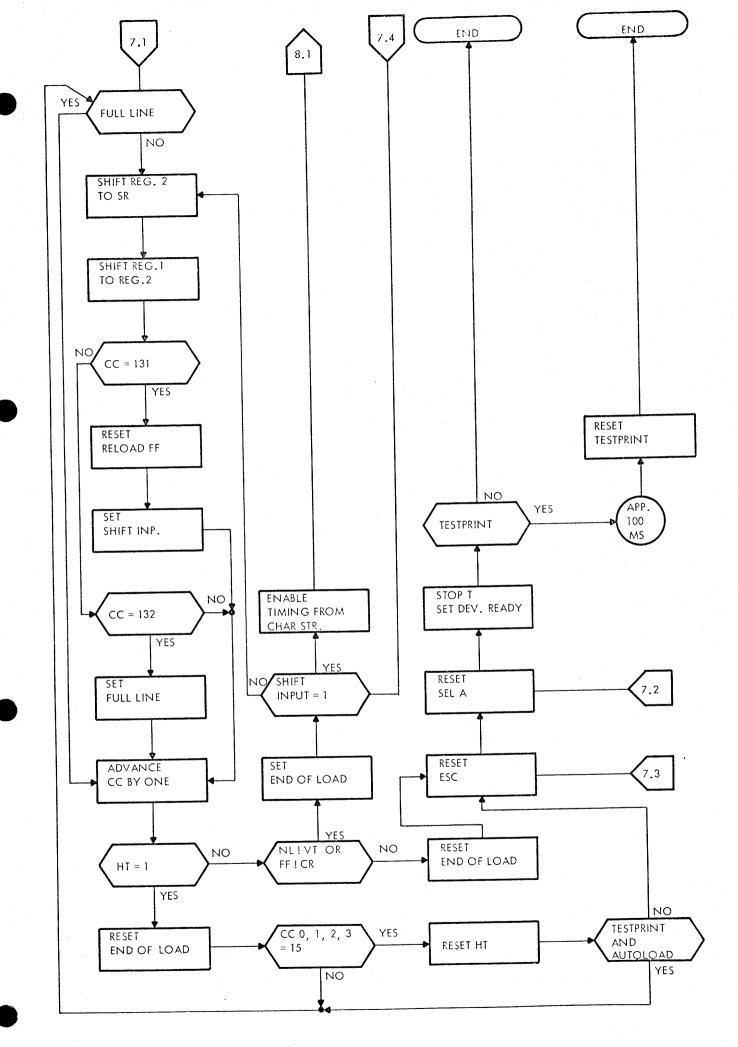




LOAD

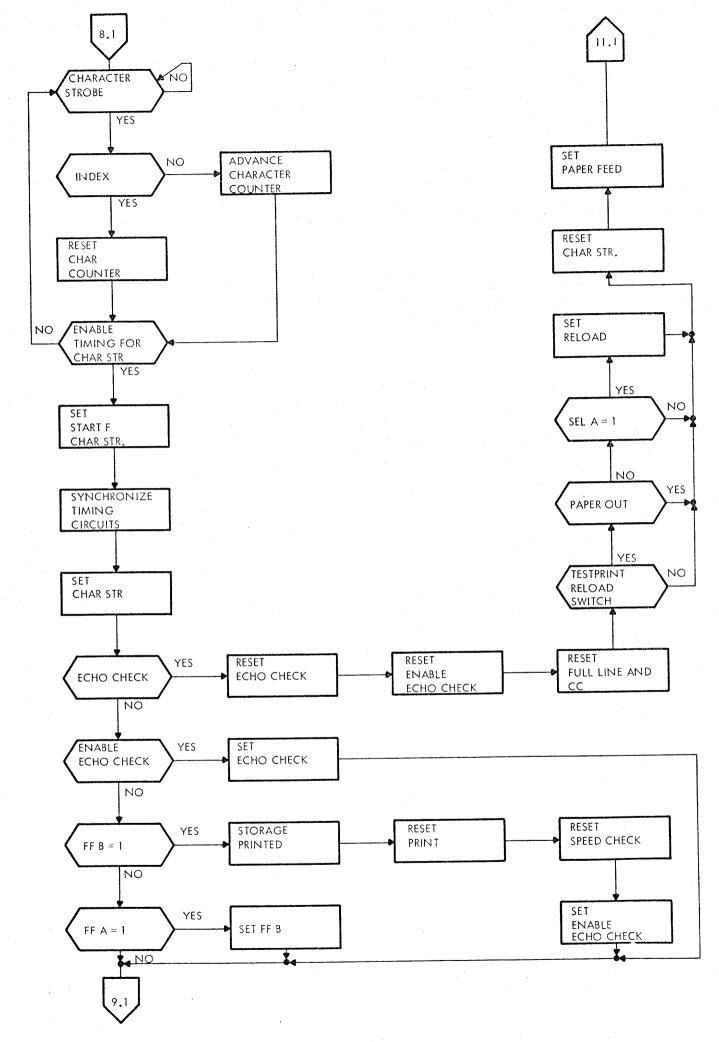


LOAD

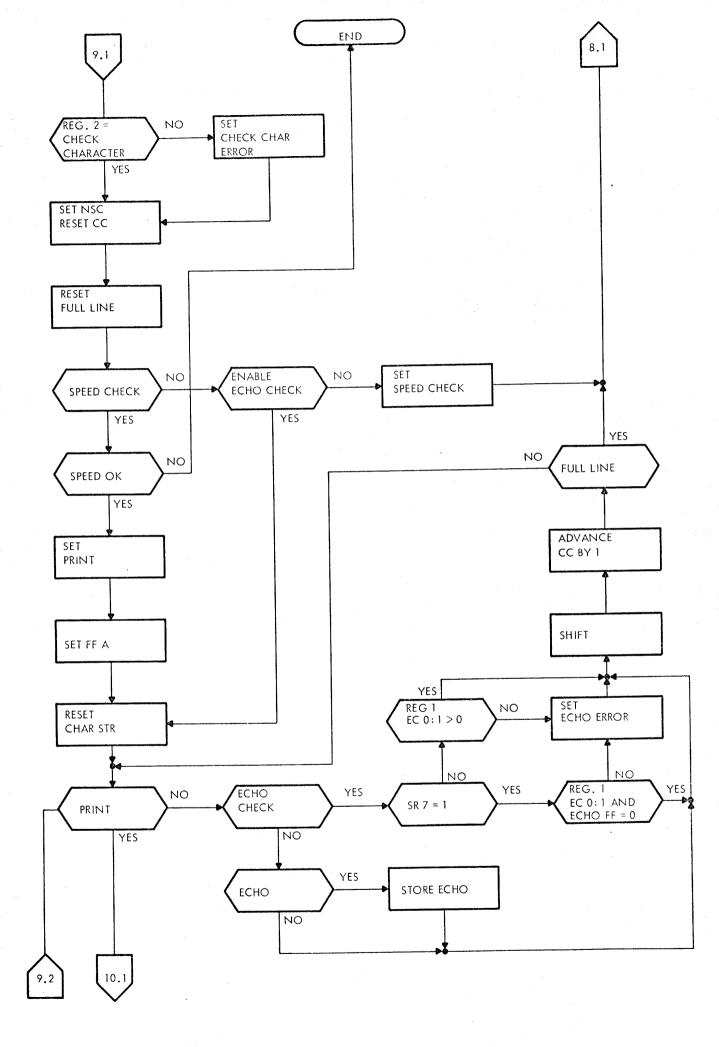


A10535

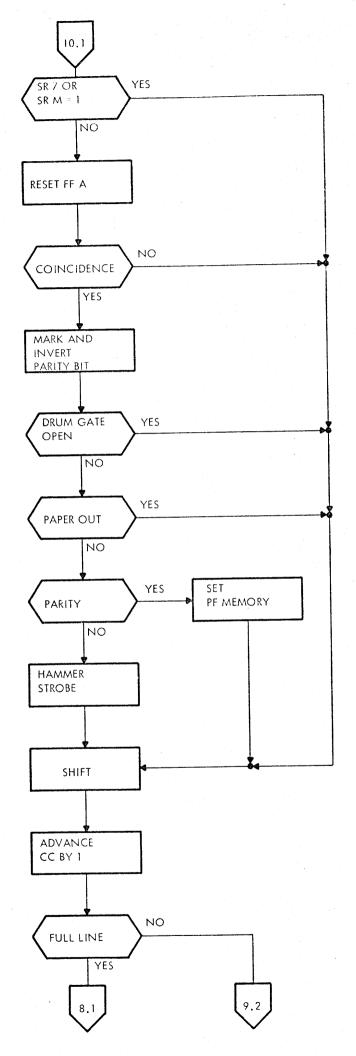
END OF LOAD



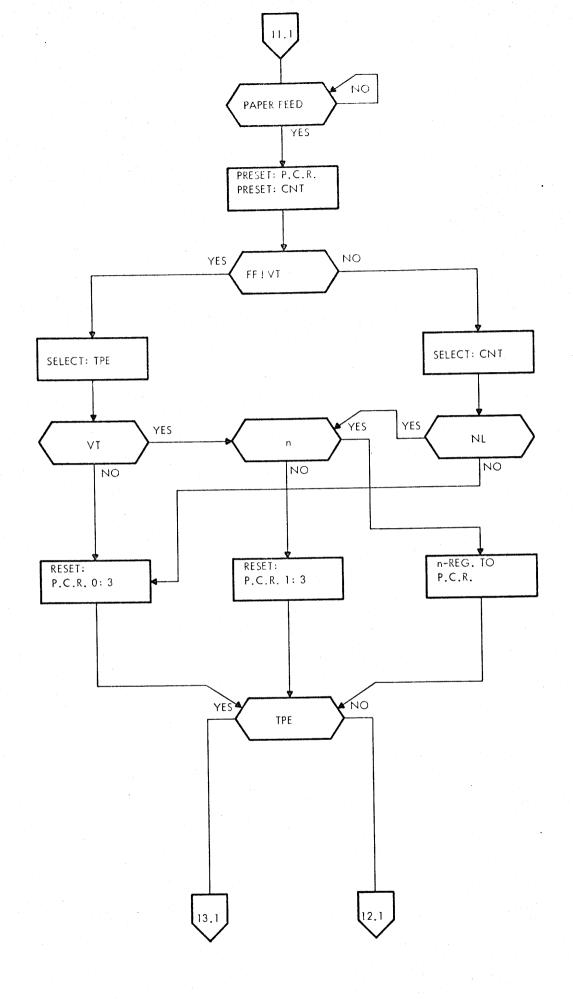
PRINT

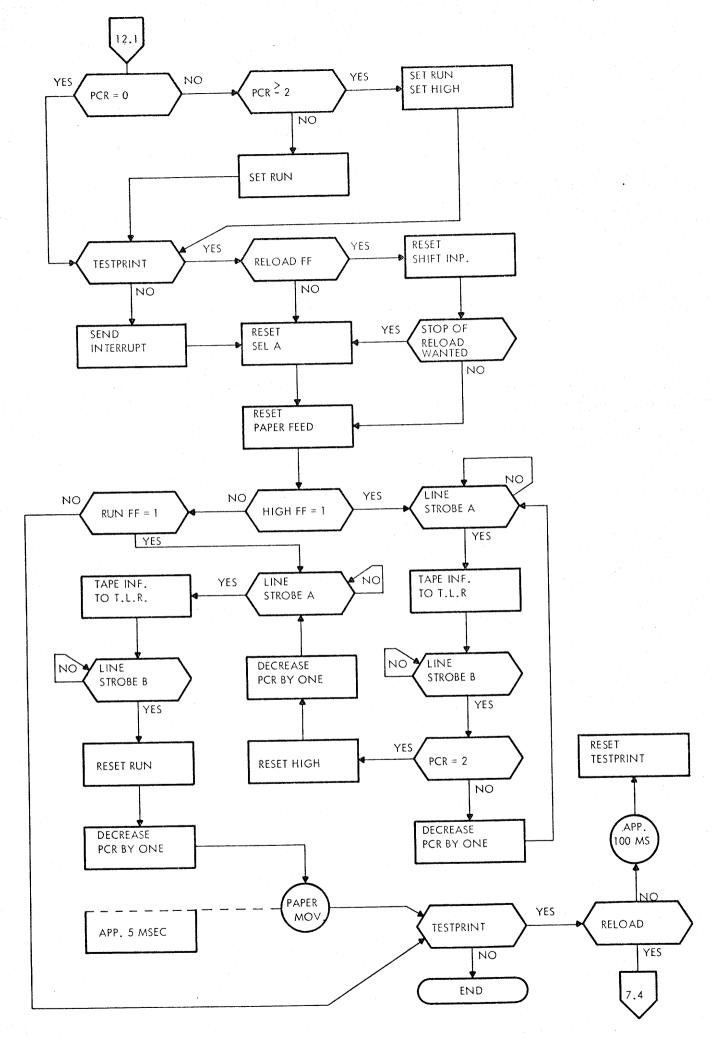


PRINT

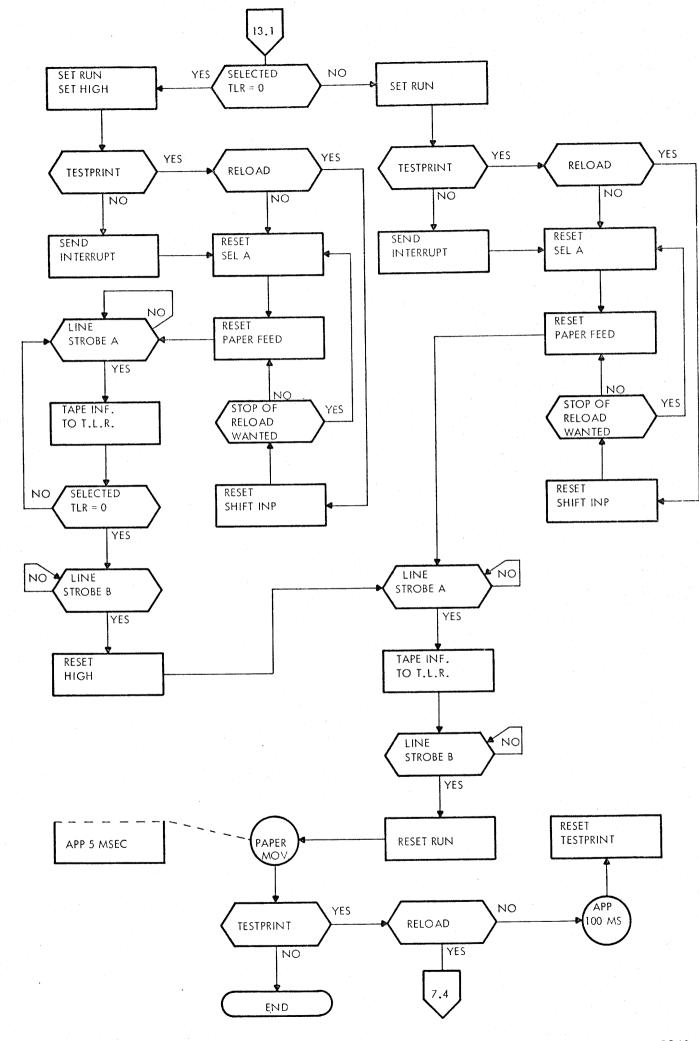


PRINT



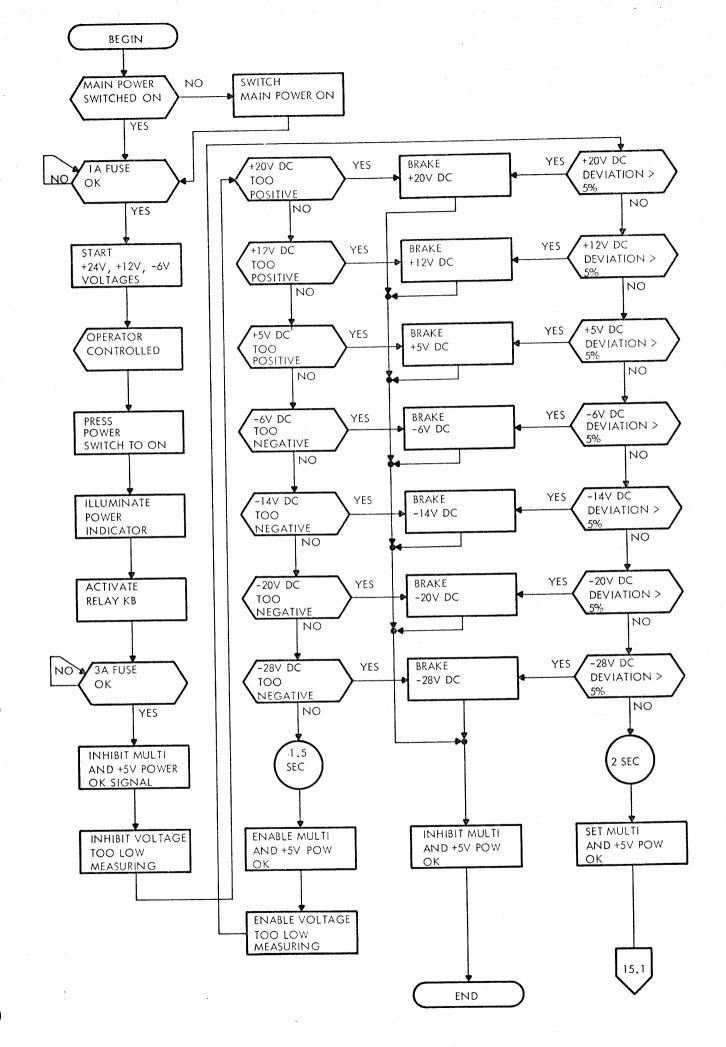


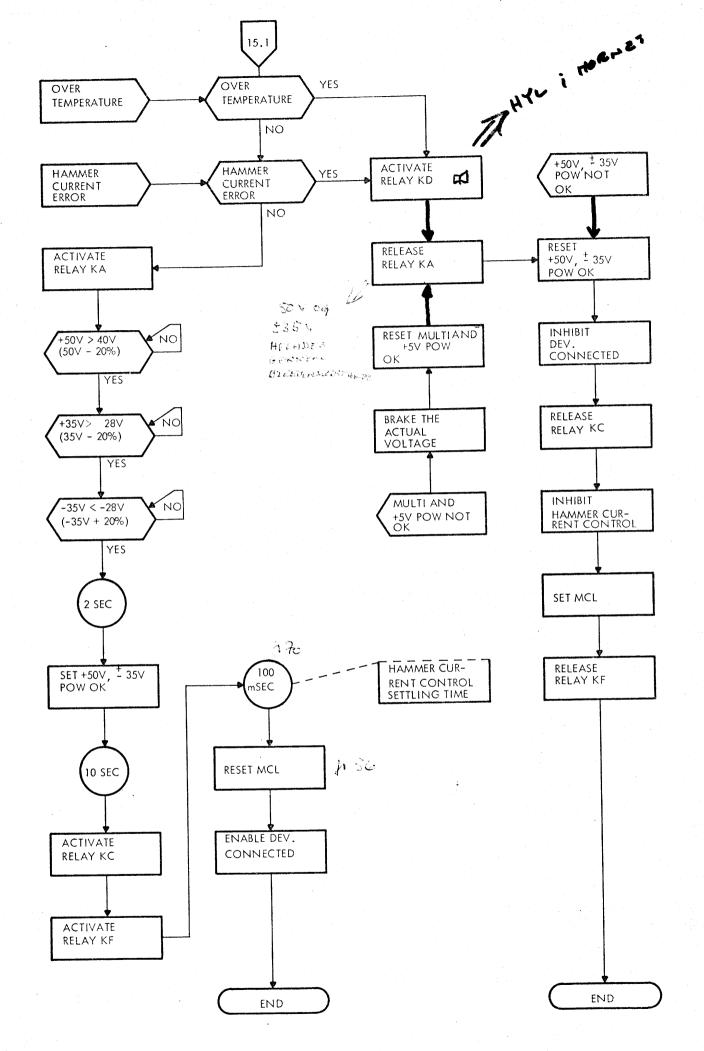
PAPER FEED: COUNT MODE

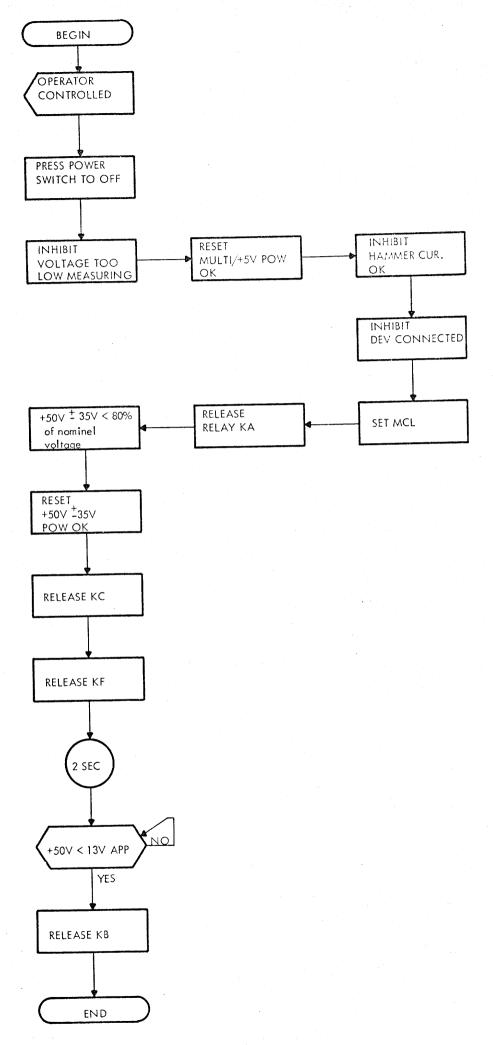


A10541

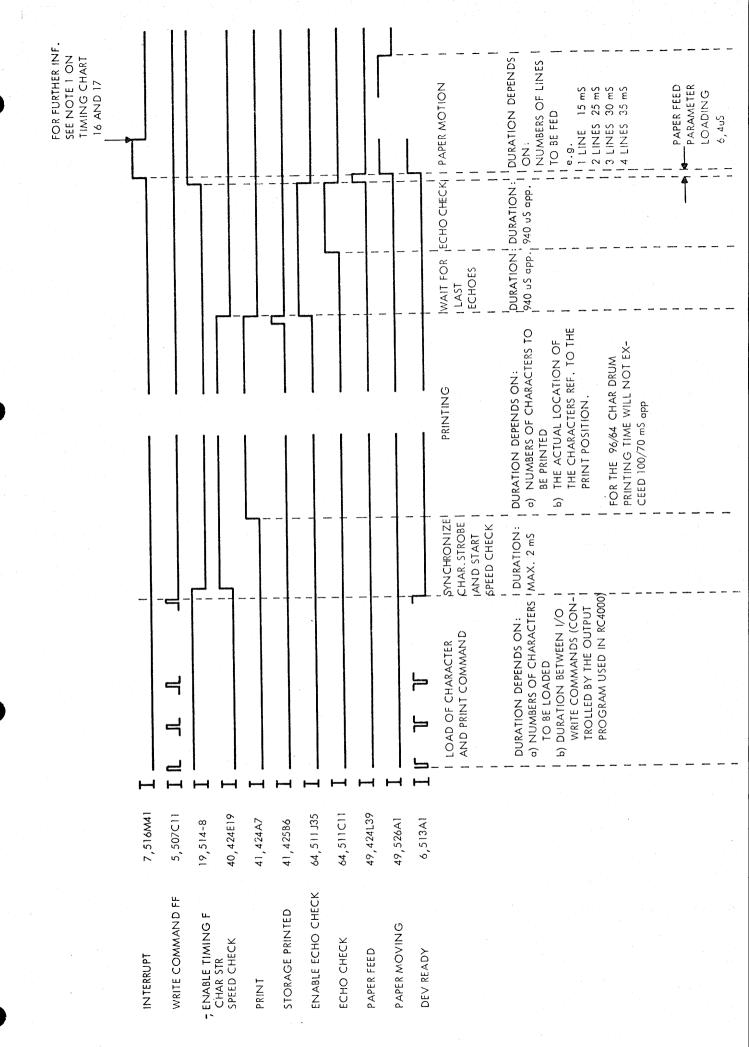
PAPER FEED: TAPE MODE

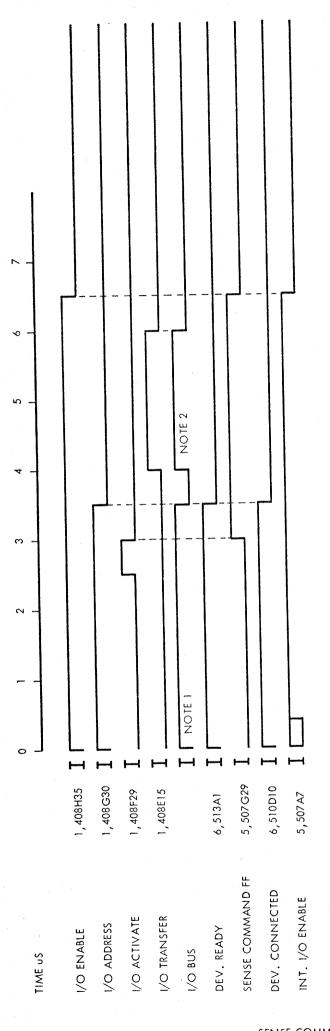






POWER ON/OFF SEQUENCE





NOTE 1: 1/O BUS 0: 17 = DEV. ADDRESS

18: 23 = DEV. COMMAND

NOTE 2: 1/O BUS 0: 5 = DEV, STATUS INFORMATION

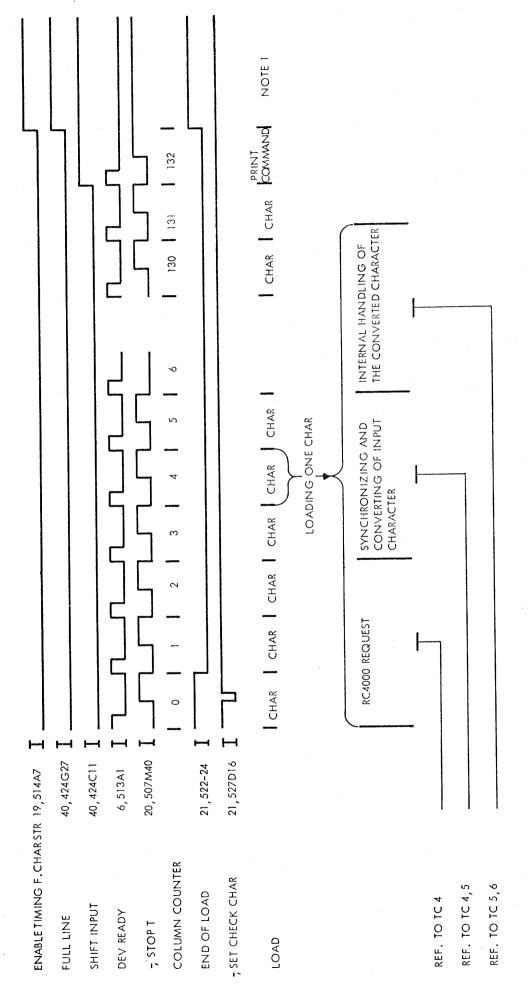
7,406F33 1/O BUS 0 = INTERVENTION

7,406E4 - 1 = PARITY

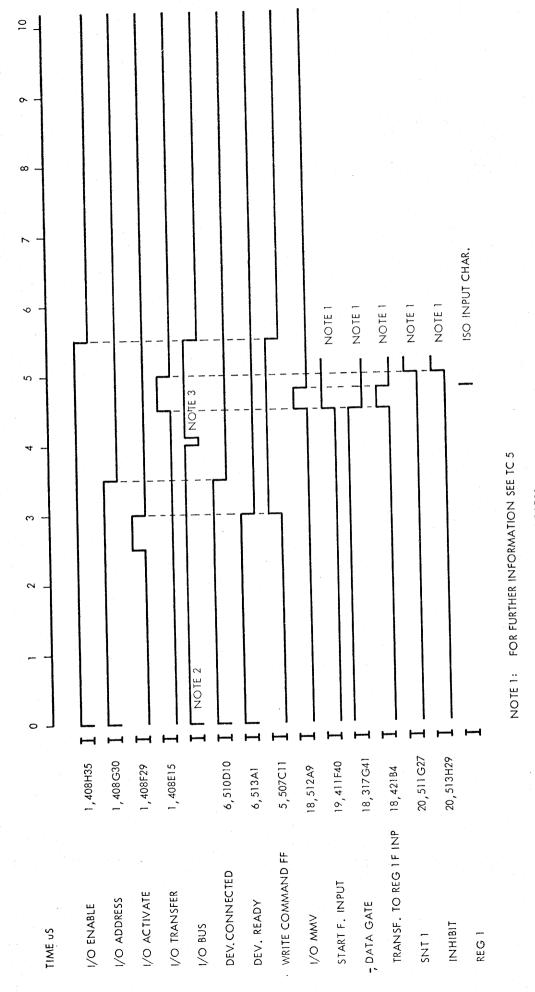
7,406D1 - 2 = TIME OUT

7,406D1 - 2 = TIME OUT

7,406A10 - 5 = INTERVENTION REQUIRED

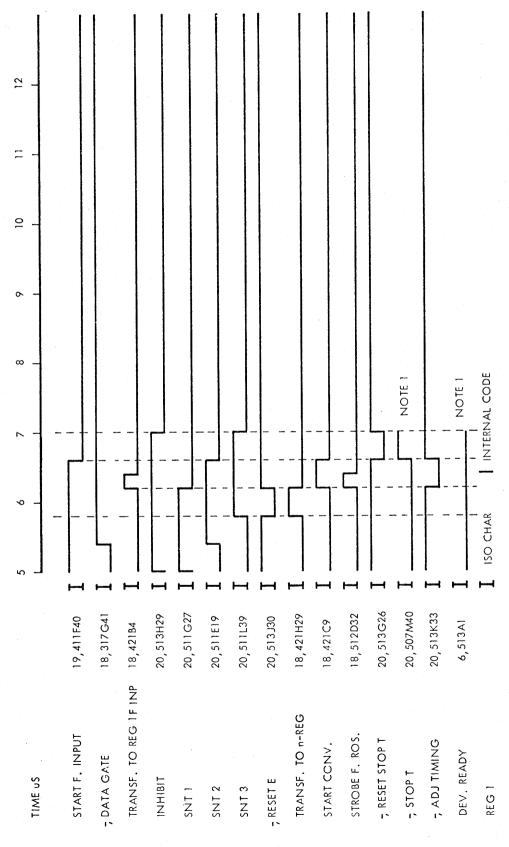


NOTE 1: SEE TC 9 FOR START OF PRINTING

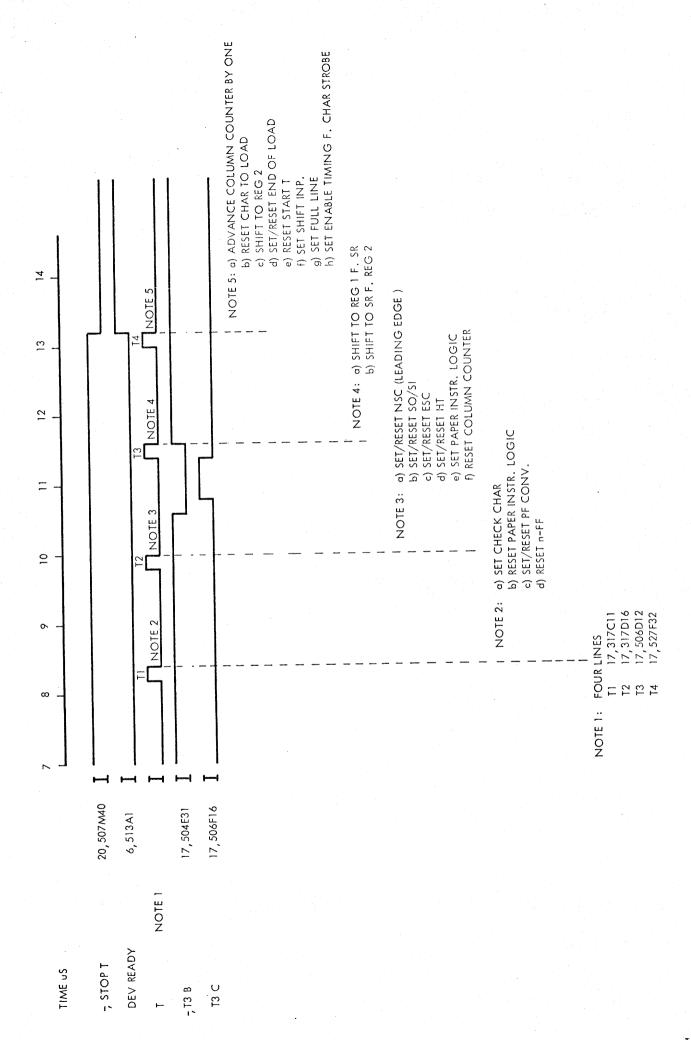


NOTE 2: 1/O BUS 0: 17 = DEV. ADDRESS 18: 23 = DEV. COMMAND

NOTE 3: 1/O BUS 17: 23 = 150 INPUT CHAR.

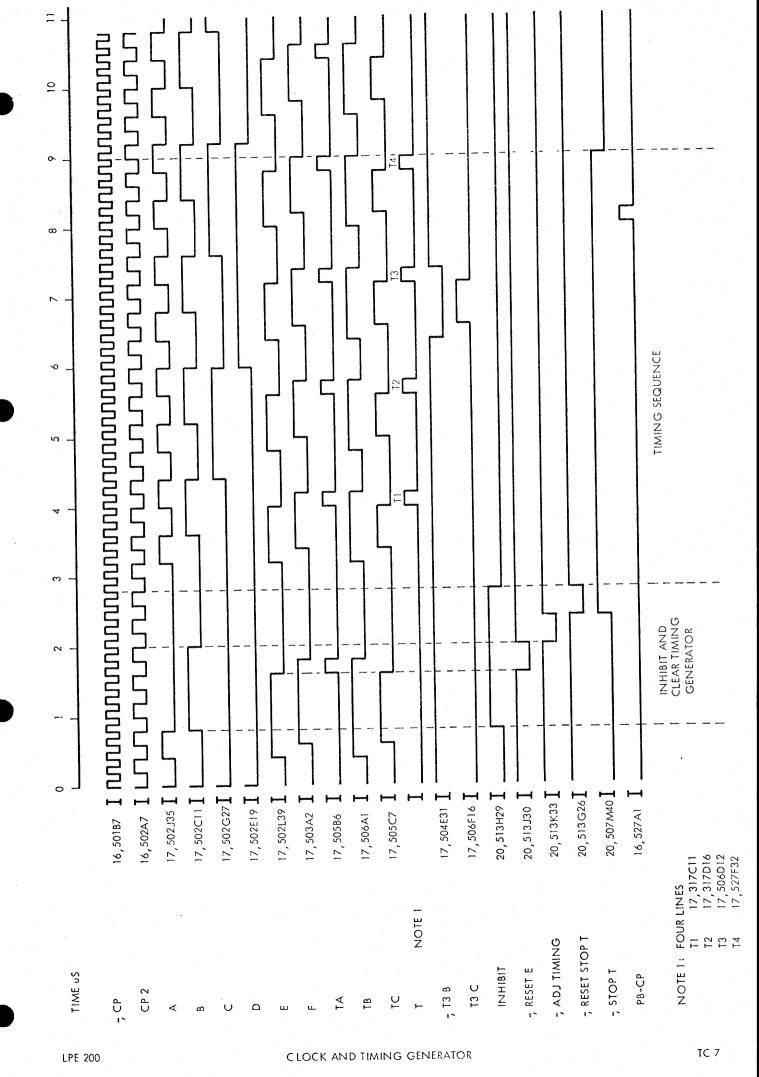


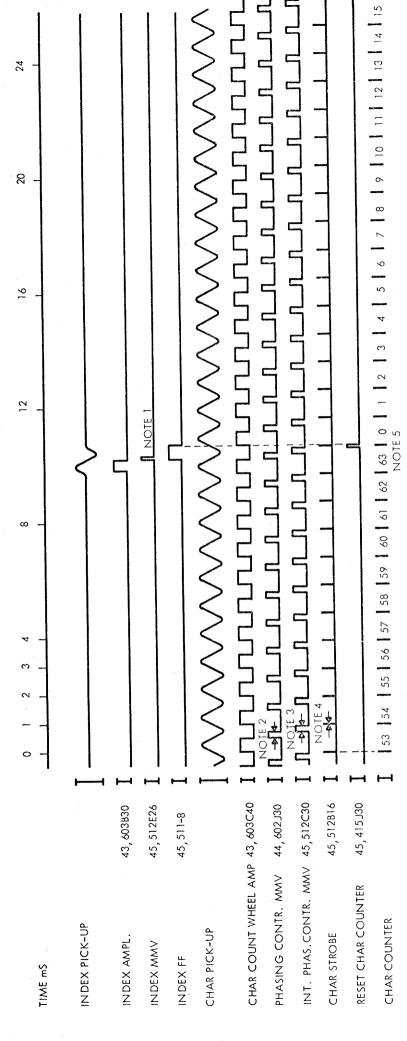
NOTE 1: FOR FURTHER INFORMATION SEE TC 6.



I/O WRITE COMMAND, CONTINUED

TC 6



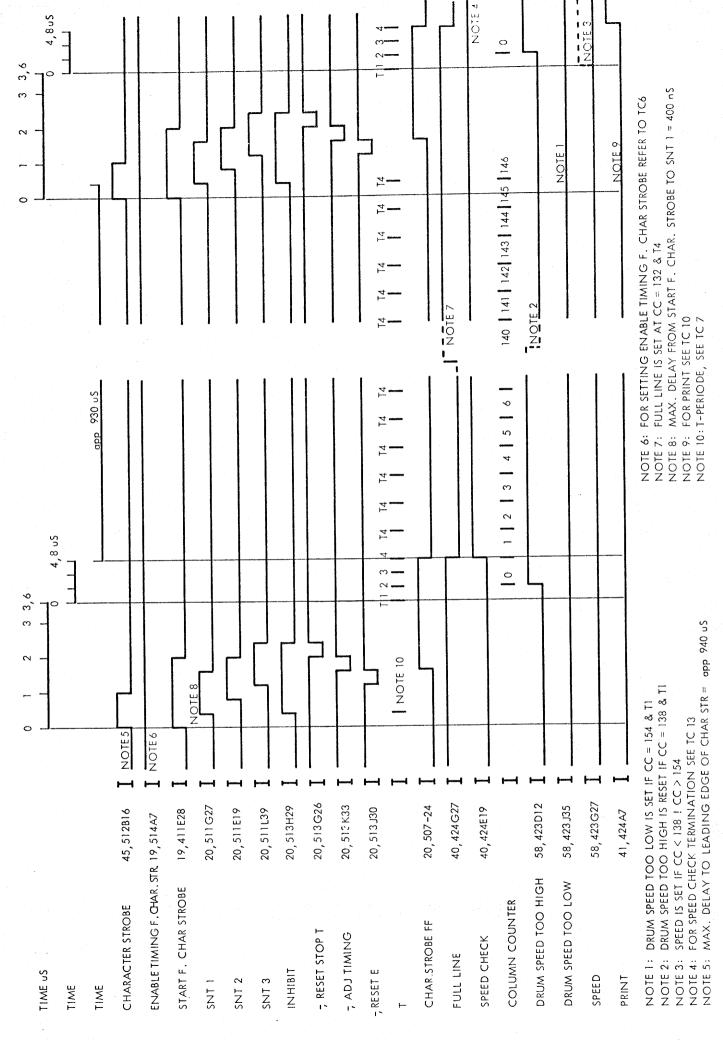


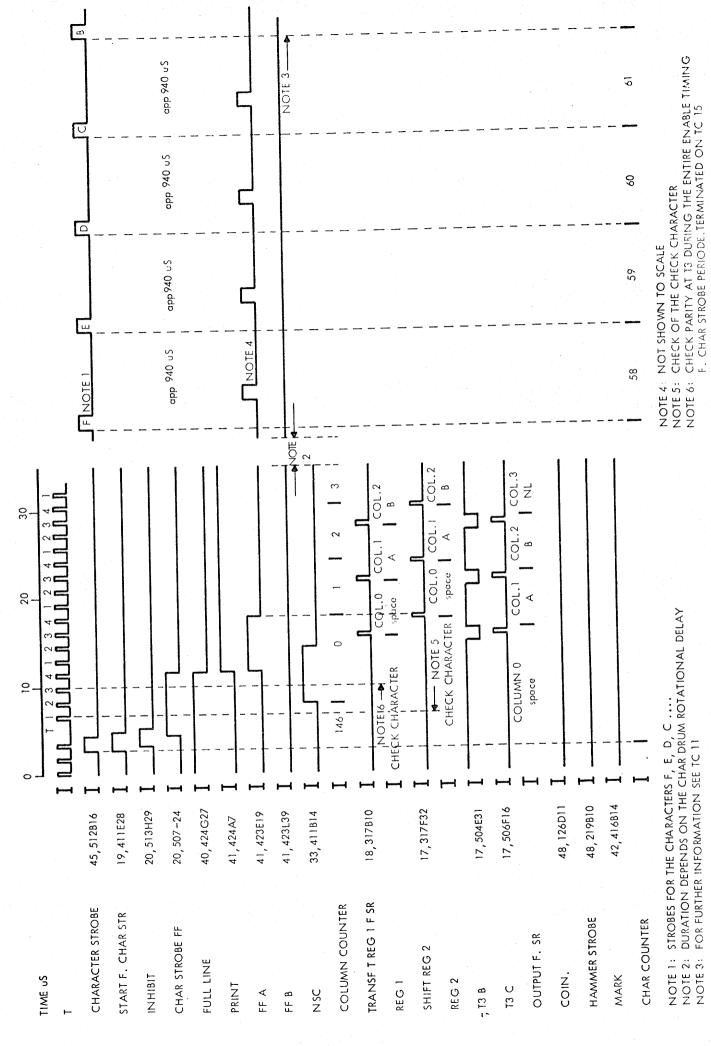
NOTE 1: INDEX MMV ADJUSTED TO 1,5 uS

NOTE 2: PHASING CONTROL MMV NOMINAL DURATION = 230 uS, ADJUSTABLE FROM 50 uS TO 455 uS NOTE 3: INT. PHASING CONTROL MMV NOMINAL DURATION = 230 uS, ADJUSTABLE FROM 50 uS TO 455 uS

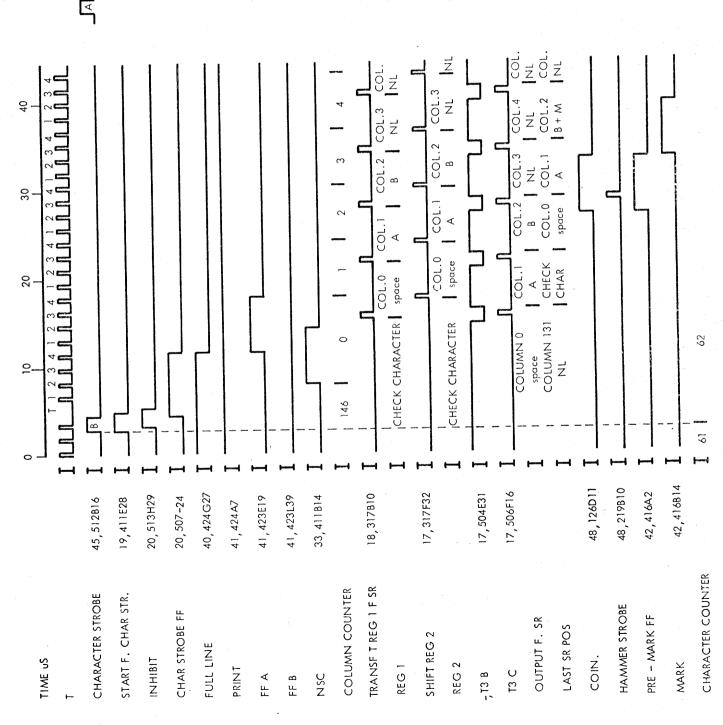
CHAR STROBE NOMINAL DURATION = 1 uS ADJUSTABLE FROM 0,6 uS TO 1,2 uS NOTE 4:

note 5: char counter termination value depends on char drum here shown for 64 char.





START PRINTING (Space A B NL) Timing Chart TC 10

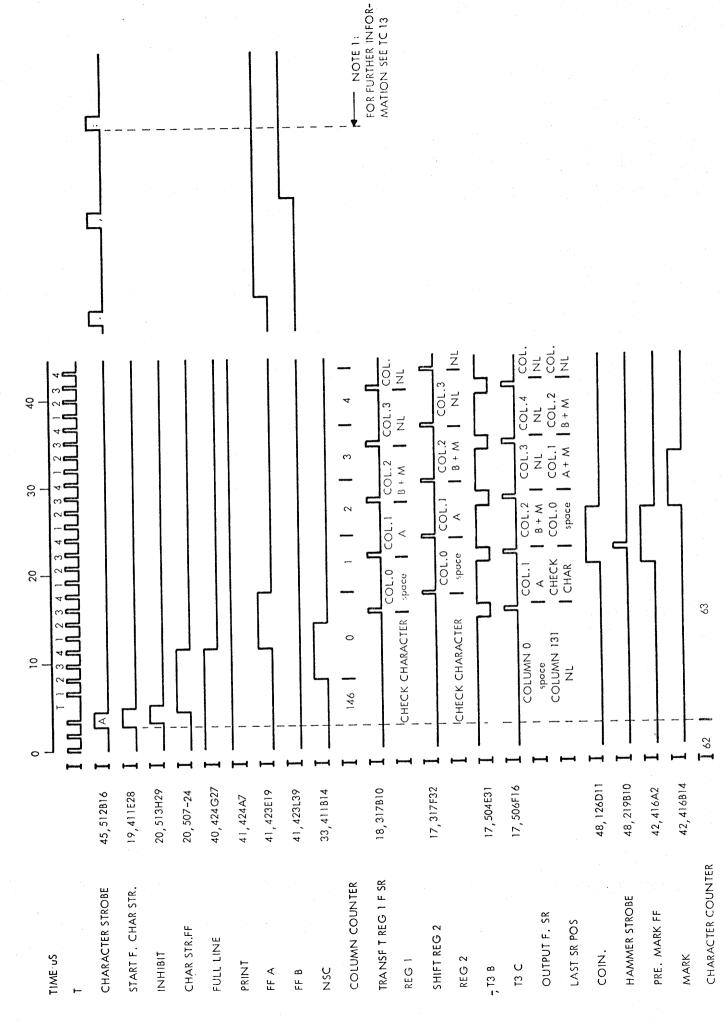


PRINTING CONTINUED

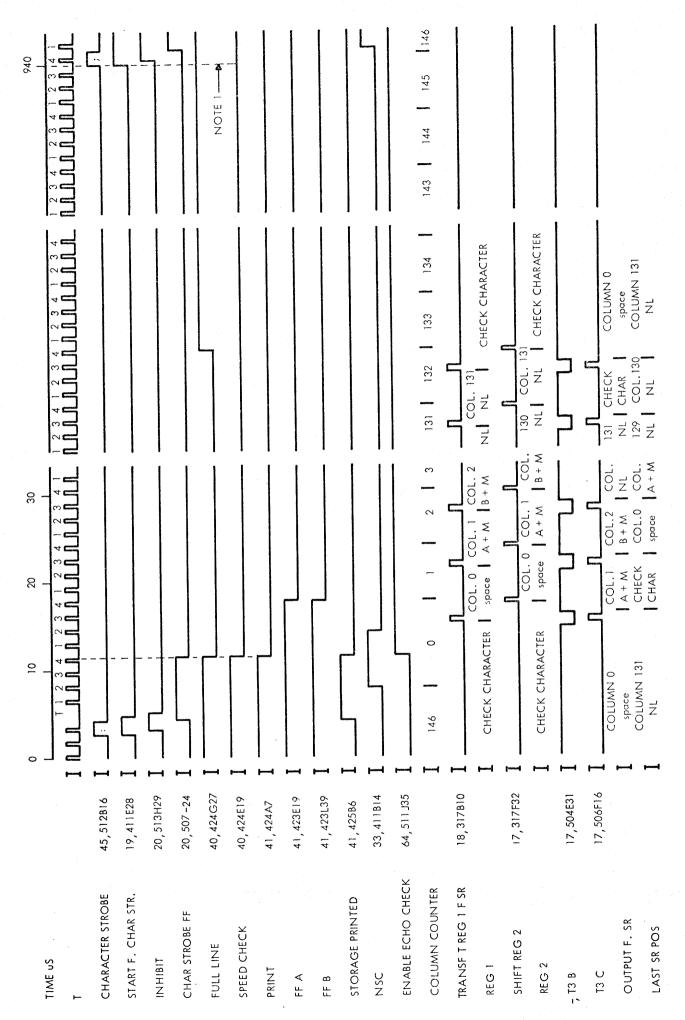
(PRINTING THE B IN COLUMN 2)

Timing Chart

TC 11

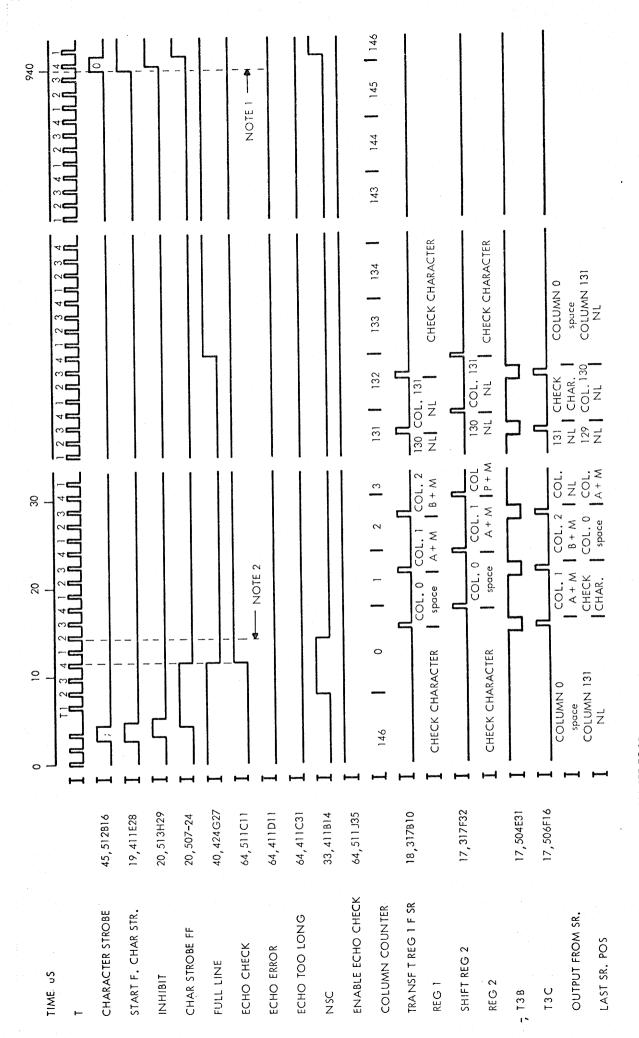


PRINTING CONTINUED (PRINTING THE A IN COLUMN 1) Timing Chart



NOTE 1: FOR FURTHER INFORMATION SEE TC 14

TC 13

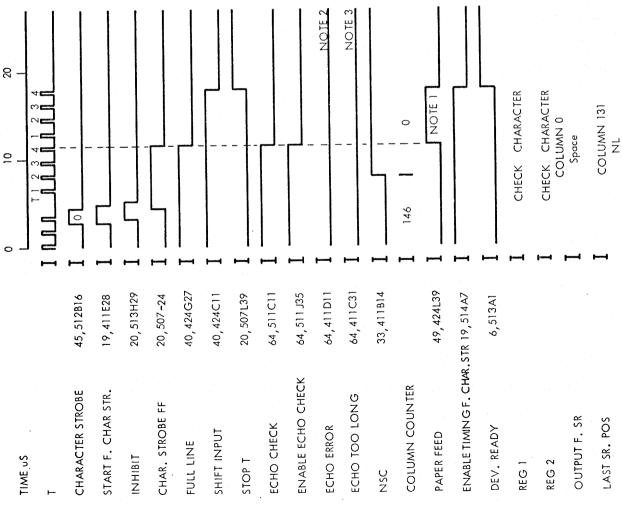


NOTE 1: FOR FURTHER INFORMATION SEE TC 15 NOTE 2: T2 DETERMINES THE CHECK TIME DURING THE INTIRE ECHO CHECK PERIOD

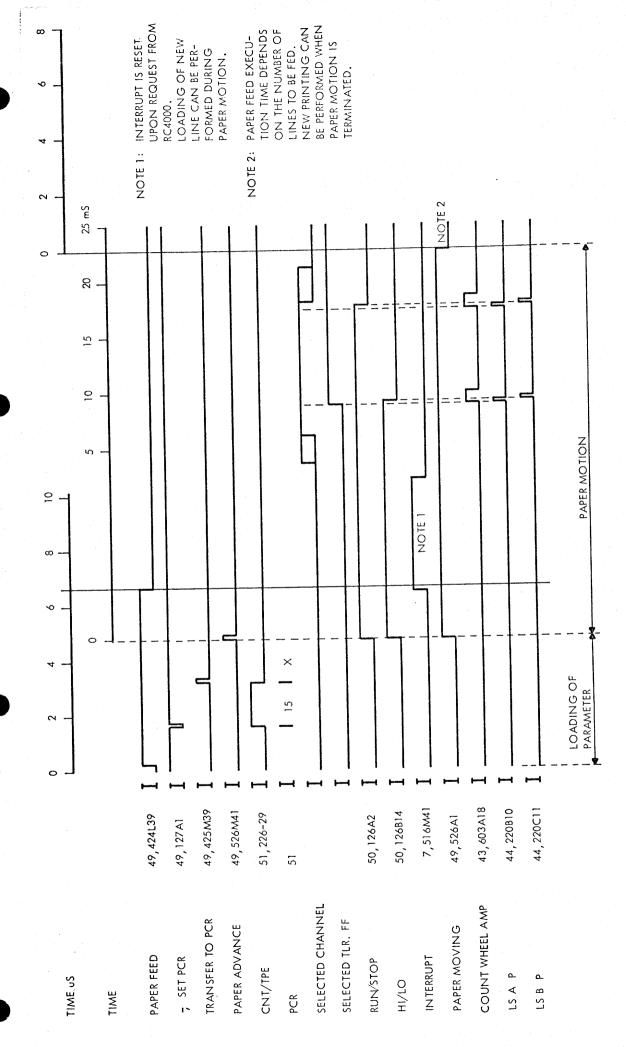
NOTE 1: FOR FURTHER INFORMATION SEE TC 16

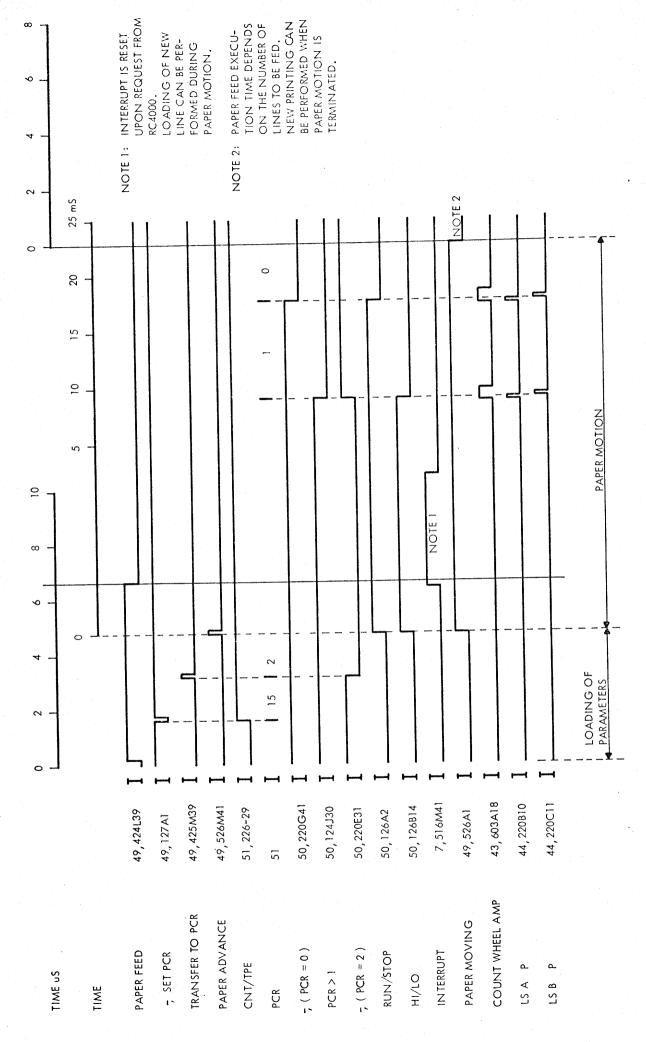
NOTE 2: IN CASE OF ECHO ERROR, THE ERROR FF WILL BE RESET
BY THE NEXT I/O WRITE COMMAND.

NOTE 3: IN CASE OF ECHO TOO LONG, THE ECHO TOO LONG
FF IS ONLY RESETABLE BY MASTER CLEAR.

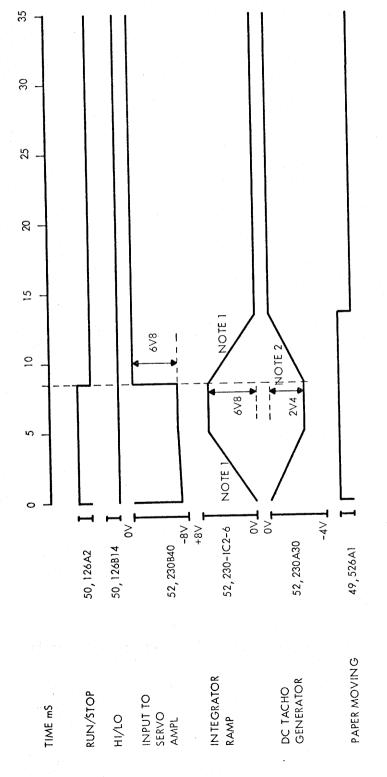


Timing Chart

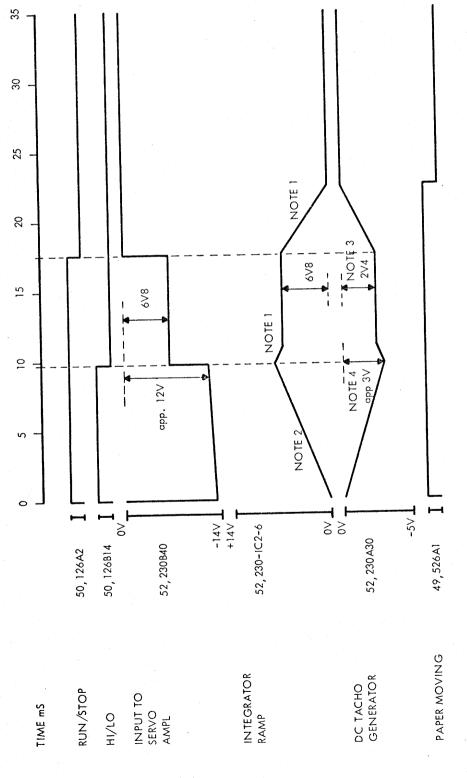




COUNT MODE PAPER FEED 2 LINES Timing Chart



NOTE 1: SLOPE 1V36 per mS (FASTE RISE) NOTE 2: 2V4 corresponds to 370 rpm corresponds to 20 ips paper speed.

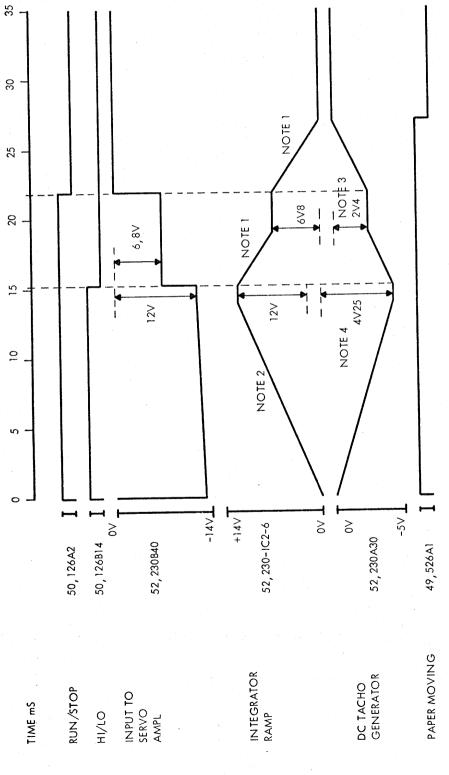


NOTE 1: SLOPE 1V36 per mS (FAST RISE)
NOTE 2: SLOPE 0V86 per mS (SLOW RISE)
NOTE 3: 2V4 corresponds to 370 rpm corresponds to 20 ips paper speed
NOTE 4: 3V - - - 460 - - - 25 - - -

TWO LINE STEPPING

LPE 200 A10492

Timing Chart



NOTE 1: SLOPE 1V36 per mS (FAST RISE)
NOTE 2: SLOPE 0V86 per mS (SLOW RISE)
NOTE 3: 2V4 corresponds to 370 rpm corresponds to 20 ips paper speed
NOTE 4: 4V25 - - - 660 - - 35 - - -

