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RC759
CPU board
Reference Manual

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Abstract:

This paper contains the information necessary to program the RC759.

(56 printed pages)

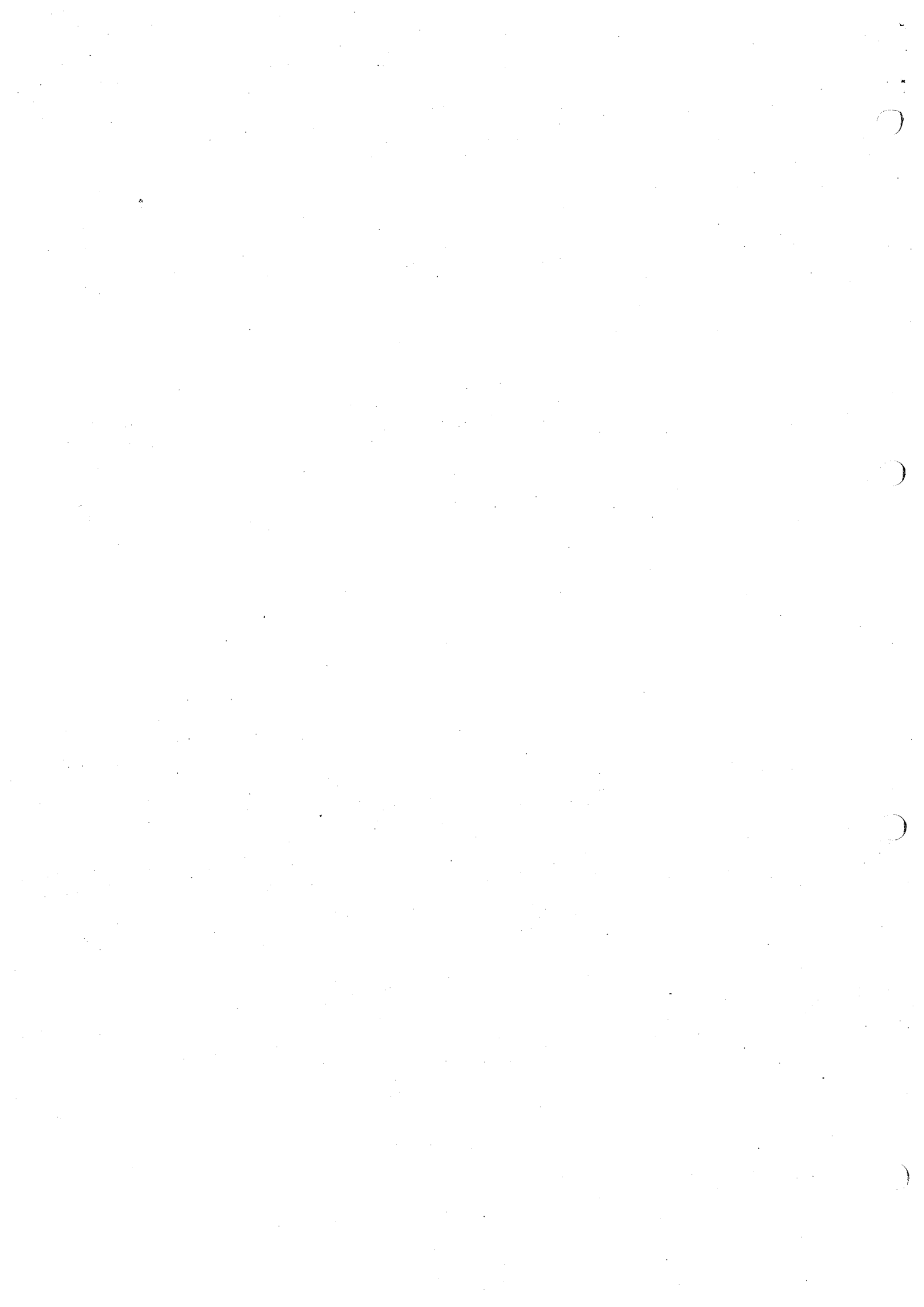
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PREFACE

Additional related information can be found in the following publications:

- IAPX186 Data Sheet
- INTEL Microprocessor and Peripheral Handbook (8255, 8259)
- 82730 CRT Controller Architectural Overview
- INTEL82730 Data Sheet
- Western Digital FD1897 Data Sheet

1. CPU

The system is based on an Intel 80186 single chip CPU. This CPU is described in detail in the Intel Reference Manual.

This section describes how the peripherals and memory are connected to the CPU.

80186 can handle up to 1M bytes of memory. The RC759 CPU board is equipped with 256 Kbytes of general memory, 32 K bytes of memory dedicated to the CRT controller, but accessed by the CPU as normal memory, and finally up to 64 Kbytes of ROM (Read only memory) for autoloader and Comal 80.

The following peripherals are standard.

- CRT control
- local parallel printer interface
- Keyboard input
- Non Volatile Memory
- Real Time Clock
- Sound device
- iSBX connector
- cassette tape
- connector to micronet interface
- connector to adapter for external floppy/printer switch unit

The interconnections of these are shown on the block-diagram fig. 1.

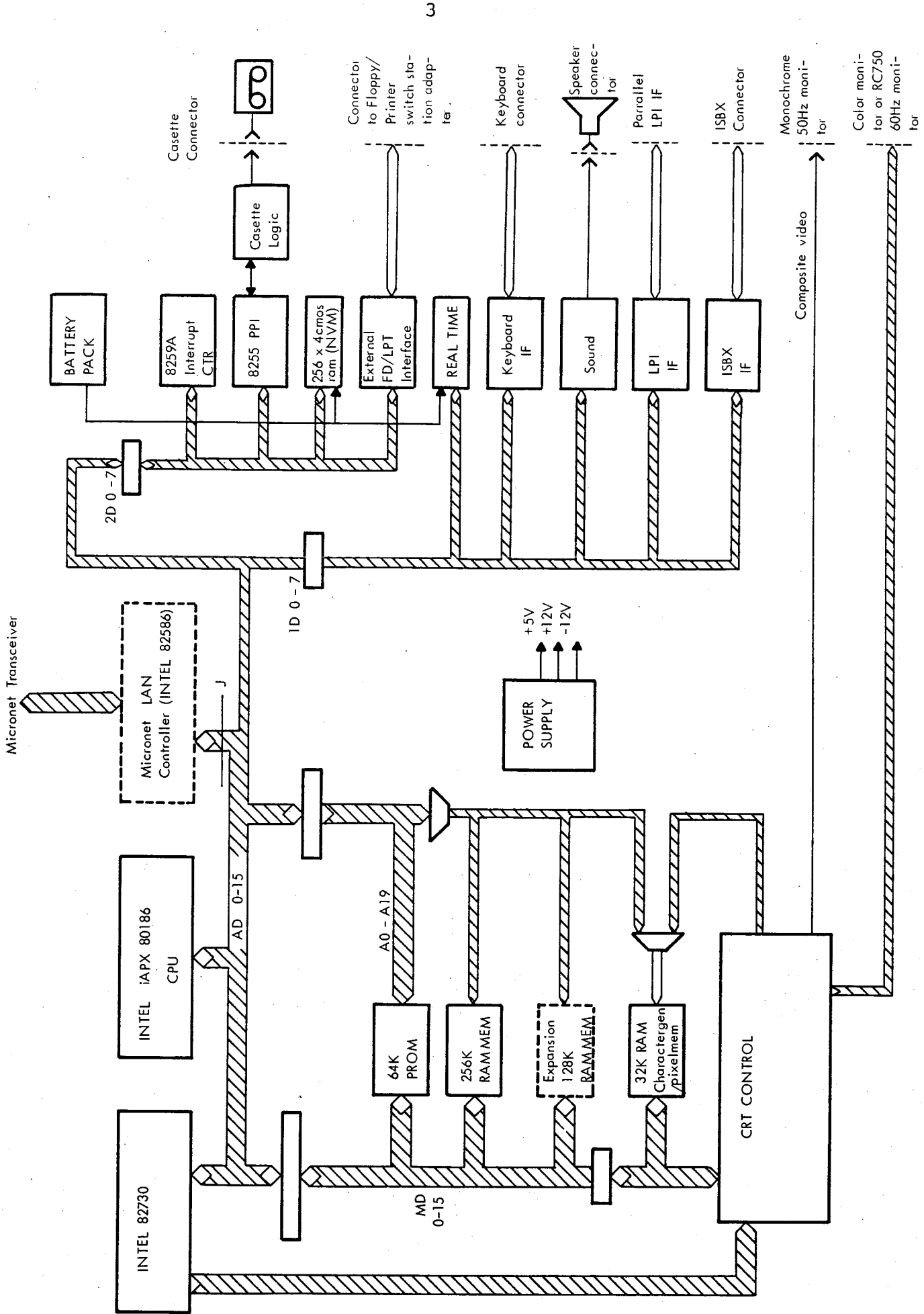


Fig. 1. Piccoline Block Diagram

1.1 Memory

1.1

The memory consists of at least the following parts:

1. 256 K bytes of general memory
2. 32 k bytes of Pixel memory used by the CRT
3. 64 K bytes of Read Only Memory

128 K of address space is left for memory extension. The address space is divided into the areas shown on fig. 2.

The CPU runs at 6MHz, which gives rise to a maximum of 2 memory accesses every microsecond. The memory chips used are fast enough to avoid the insertion of wait states. Only access to the CRT-memory may delay the CPU slightly, because of the heavy load the CRT imposes on this memory.

Address (hex)

FFFFF

F8000

F0000

E8000

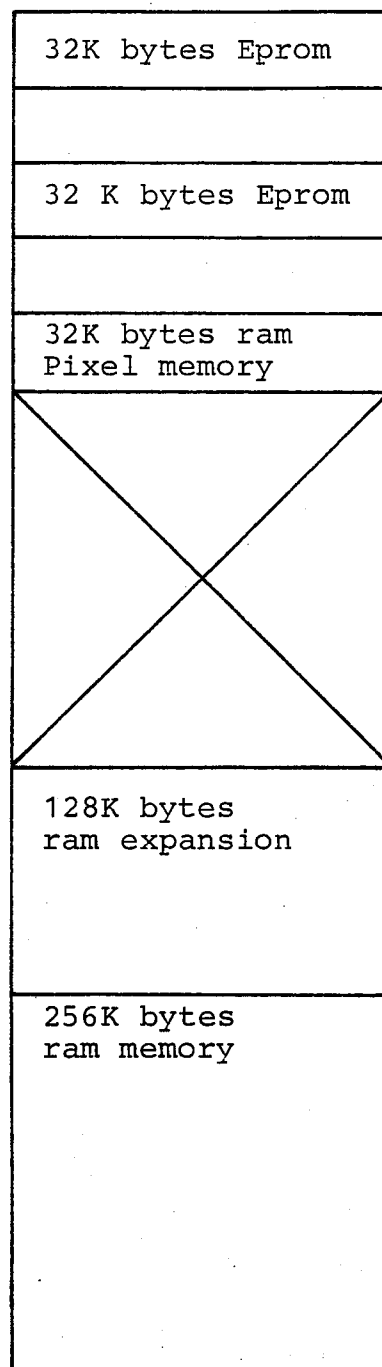
E0000

D0000

60000

40000

0



Expansion of Eprom
area when using
32Kx8 Eproms

Free ares. Can be
used as ram memory,
when 256Kx1 dynamic
chips are available.

Fig. 2. Memory Address Layout

The memory is of dynamic RAM type, and needs periodical refresh cycles. When the CRT controller is initialized, the line sync pulses are used to generate refresh requests. But while the CRT controller is uninitialized, the CPU must maintain refresh of the memory. This can be done by letting one of the DMA channels repeatedly move a block of 256 words (512 bytes) to the same locations.

1.2 Direct Memory Access

1.2

The 80186 has two integrated DMA channels which are connected to the iSBX connector and to the I/O expansion for external Floppy/printer box.

DMA channel 0 is connected to iSBX connector.

DMA channel 1 is connected to I/O expansion connector.

Refer to section 11.0 for details about control of the DMA channels.

1.3 I/O

1.3

The peripherals are addressed via the seven PCS signals generated by the CPU. PCS0 controls eight chip-select signals on the CPU-board: PCS00 to PCS07 selected by means of the address bits A4 to A6.

As the peripherals are connected to the least significant eight bits of the databus, the devices can only be accessed with even addresses. This gives each PCSx 64 addresses, and each PCS0x 8 addresses.

The PCS signals are allocated either I/O space or memory address space by programming a word in the controlblock (see the iAPX186 manuals).

1.4 Interrupt

1.4

The peripherals able to interrupt the CPU are connected to this via a 8259A (Programmable Interrupt Controller). This is programmable via the port controlled by PCS0,0.

The IR inputs are connected as follows:

IR0 : I/O expansion (Floppy)
IR1 : Keyboard
IR2 : I/O expansion (Printer)
IR3 : Real Time Clock
IR4 : CRT
IR5 : NET
IR6 : Parallel printer
IR7 : not used

8259 is connected to the INTO and INTA0 terminal of the CPU in cascade mode.

Programming of the 8259 A takes place via the following addresses:

Initialization command word: I/O base + 0
Operation command word: I/O base + 2

For programming the internal CPU interrupt controller, see the iAPX186 reference manual: Bit 5 (c) in the INTO control registers should be set to 1. Bit 5 (C) in the INT1 control registers should be set to 0.

INT1 and INT3 on the 80186 CPU is connected to the iSBX connector.

2. CRT CONTROL

2.

2.1 General

2.1

The CRT controller is build around an Intel 82730 coprocessor, which fetches characters in memory for display controlled by a channel program.

The characters are stored in a rowbuffer to avoid 10 redundant refetches of the characters in mainmemory. Then the character codes combined with a scanlinenumber generated by the 730 is used to address the character generator/Pixel memory.

The CRT controller should maintain a frame-frequency of about 50 Hz, (option 60 Hz), each frame containing 275 videolines with 560 pixels each.

The controller will perform equally well as a memory mapped pixel graphic display, and a conventional alphanumeric display.

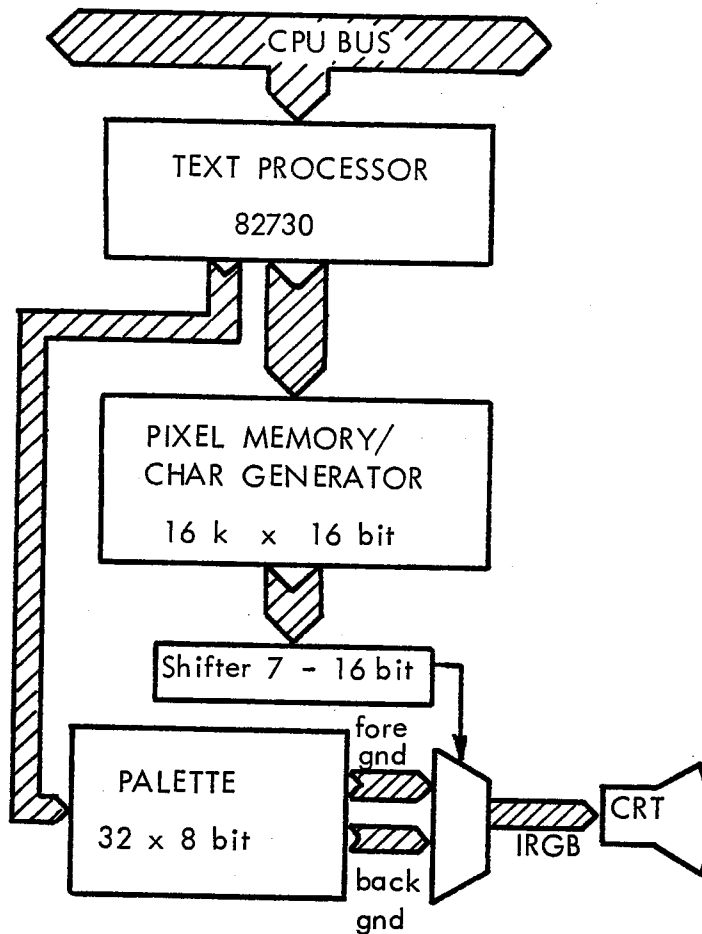


Fig. 3. Blockdiagram of the CRT system

The least significant 10 bits of the character code combined with the scanline address directly address the pixel memory to output a 16 bit "word" of which at least 7 bit and at most all 16 bit are used as a dot pattern, shifted out of the shifter to be used as dot colour selector. In alpha mode, the bits select one of two colours, and in graphics either one out of two or four colours from a palet of 16 colours. If four colours are chosen in graphics mode, the dot frequency (horizontal resolution) is only 6 MHz (280 dots).

2.2 Functional Description

2.2

2.2.1 82730 Coprocessor

2.2.1

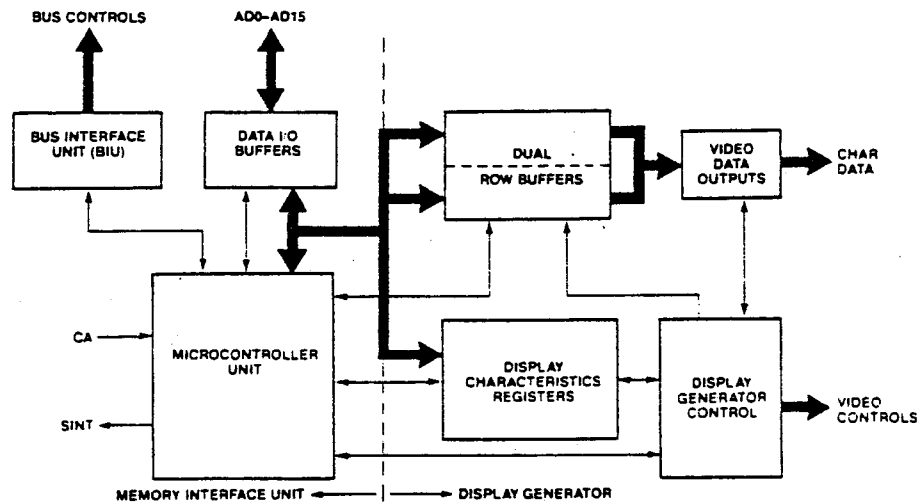


Fig. 4. 82730 Block Diagram

Figure 4 shows a block diagram of the 82730. The chip is divided into two main sections. The Memory Interface Unit (MIU) and the Display Generator (DG). The MIU provides the communication between the 82730 and system processor and memory, while the DG acts on the display data and carries out the display operation.

Communication between the 82730 and the CPU takes place through messages placed in communication blocks in shared memory. The processor issues channel commands by preparing these message blocks and directing the 82730's attention to them by activating a hardware channel attention signal (CA). The MIU fetches and executes these commands. When the display process is activated, the 82730 repeatedly fetches display data and embedded datastream commands from memory utilizing its built-in DMA capability, executes any datastream commands as encountered on the fly, and loads the row buffers with the display data. After executing these commands, the 82730 clears a busy flag in memory, to inform the host CPU that it

is ready for the next command.

The MIU is divided into two sections. The Bus Interface Unit (BIU) and the Micro Controller Unit (MCU). The BIU process the electrical interface to the system bus, and the timing signals required for the MCU operations, making these operations transparent to the MCU. The 82730 can be programmed during initialization to provide 8 or 16 bit data, and 16 or 32 bit addressing.

The MCU contains the microinstruction store and the associated circuitry required for the execution of all channel and datastream commands. It uses the BIU in carrying out its memory access tasks such as loading the row buffers with display data.

The interaction between the MCU and the DG takes place through shared internal storage. The MCU fetches data from memory and writes it in the internal storage, while the DG reads from the internal storage and carries out the display operation. The MCU and DG operate asynchronously with respect to each other. Synchronization is accomplished through communication via internal flags and display timing signals generated by the DG. The internal shared storage consists of Row Buffers which store the display data and internal registers which store display parameters. There are two row buffers each capable of storing up to 200 characters. The data in one row buffer is used by the DG to display one complete character row on the screen, while the MCU is loading the second row buffer with display data fetched from memory. At the end of the row being displayed, the buffers are swapped and the MCU and DG resume their respective tasks.

The Display Characteristics Registers contain all the information used to control every aspect of display characteristics from screen size to blink rates. A major portion of this register sets is the three Content Addressable Memory (CAM) arrays that allow very flexible timing control for row and screen characteristics. The user has the power to set the parameter for the entire screen by invoking a single high level command.

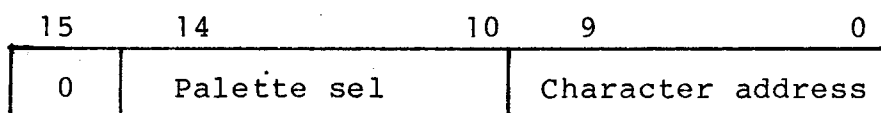
By separating the Video Interface clocks from the Bus Interface clock, the 82730 provides the designer the ability to independently maximize the performance of

the CPU and Video sections of the system.

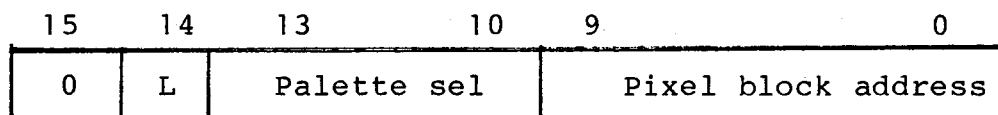
The Video interface consists of two independent clocks: the Reference Clock (RCLK) and the Character Clock (CCLK). While the RCLK controls the raster timing and defines the screen layout, the CCLK independently shifts character and attribute information out of the 82730, which allows proportional spacing to be achieved.

It is this combination of hardware features and high level command interface that makes the 82730 the first VLSI Text Coprocessor which simplifies hardware design and software development.

The characters output from the DG have the following formats in alphanumeric mode:



or in graphic mode:



If bit 15 is 1, the character is a command to the 82730 and it is not output by the DG. The remaining 15 bits are used in the illustrated way, depending on the graphic/nongraphic mode. In both cases, bits 0 to 9 are concatenated to the video linenumbers output by the DG and used as an address into the Character generator/Pixel memory.

In nongraphic mode, bits 10 to 14 are used to select a foreground/background - colourpair from the palette.

In graphic mode, bits 10 to 13 are used to select a colour quartet from the palette. In graphic mode bit 14 selects low resolution if 1.

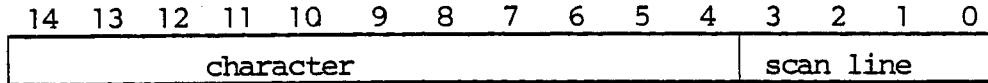
In low resolution two dots are combined to one four state pixel being capable to have any of the four colours selected with bits 10 to 13. In high resolution, each dot being a two state pixel can have one of the two first colours in the quartet.

2.2.2 Pixel Memory

2.2.2

The Pixel memory has the task to supply the dot shifter with information. The address into the Pixel memory consists of 10 bits output from the refresh memory plus 4 bits scan linenumber from the 82730.

Pixel memory address:

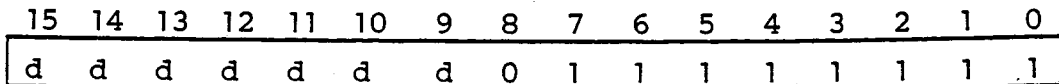


bit 0 is not used, as 16 bit words are addressed.

Pixel memory address = $2 * (\text{video line number} + 16 * \text{character})$.

The output word contains 16 bit and is used in three different ways controlled by the attribut.

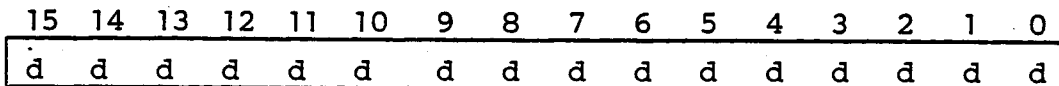
A. character line:



first displayed

One line of a 7 dots wide character is shown. The bits d are the dots of the character in the same order as on the screen (left to right). The zero in bit 8 succeeded by all ones are length designators. The character cannot be narrower than 7 and not wider than 15 dots.

B. High resolution graphic line:



first displayed.

The bits d are all displayed in the indicated sequence. As in the nongraphic mode each d select one of two colours.

C. Low resolution graphic line:

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
C ₁	C ₀	C ₁	C ₀	C ₁	C ₀	C ₁	C ₀	C ₁	C ₀	C ₁	C ₀	C ₁	C ₀	C ₁	C ₀

first displayed

The nipples (C₁, C₀) are displayed in the indicated sequence.

Each pixel occupies the space of two dots on the screen but can select one out of four colours (intensities) from the palette.

The Pixel memory has a size of 16K x 16bit or 32 K bytes and is accessible from the cpu as normal memory in the area D8000 to DFFFF Hex.

In graphic mode accesses to the Pixel memory may cause the CPU to go through a number of wait states before the memory becomes idle, because of the heavy load, the CRT imposes on it.

When nongraphic mode is selected, and narrower characters than 15 dots are displayed, the pixel memory will be busy serving the CRT all other time but during the retraces. This would give very long latencytimes and hence waiting times for the CPU with normal programmed access to the pixel memory, so in this mode it is recommended to access the pixel memory via DMA or with the 82730 stopped.

2.2.3 Palet

2.2.3

The output of the dot shifter is used to select one of two or four colours or intensities from a Palet. The Palet has room for 32 4 bit nibbles. The nibbles has the following meaning:

3	2	1	0
I	R	G	B

if I is set the Intensity is increased.
 (It has no meaning with the normal 50HZ monitor. This signal is only valid with the optional 60 HZ monitor).

if R is set the Red beam is turned on.
 if G is set the Green beam is turned on.
 if B is set the Blue beam is turned on.

this gives the following effects:

value of the colour nipple	colour	intensity (B&W)
IRGB		
0 0000	Black	zero
1 0001	Blue	↑ not defined
2 0010	Green	
3 0011	Cyan	
4 0100	Red	
5 0101	Magenta	↓
6 0110	Brown	
7 0111	Light gray	normal
8 1000	Dark gray	low
9 1001	Light blue	↑ not defined
10 1010	Light green	
11 1011	Light cyan	
12 1100	Light red	
13 1101	Light magenta	↓
14 1110	Yellow	
15 1111	White	high

The palet is written with a white instruction to the area IO Base + 180 to 1BF Hex.

The illustration shows which colour pairs are accessed on which addresses.

The number inside the boxes refer to the identity of the palette cells.

Address	bit	7	6	5	4	3	2	1	0
I/O base + 180			1					0	
182			3					2	
184			5					4	
186			7					6	
188			9					8	
18A			11				10		
18C			13				12		
18E			15				14		
190			17				16		
1B4			53				52		
1B6			55				54		
1B8			57				56		
1BA			29				58		
1BC			61				60		
1BE			63				62		

I R G B I R G B

When accessed by the crt controller, the palet is organized in the following ways:

alphanumeric
attribute

0	1	0
1	3	2
2	5	4
3	7	6
4	9	8
5	11	10
6	13	12
7	15	14
25	51	50
26	53	52
27	55	54
28	57	56
29	59	58
30	61	60
31	63	62

I R G B I R G B
d=1 d=0

Low resolution graphics:

attribute

16	33	32	1	0
17	35	34	3	2
18	37	36	5	4
19	39	38	7	6
27	59	58	27	26
29	61	60	29	28
31	63	62	31	30

I R G B I R G B I R G B I R G B

(C₁, C₀) = 11 10 01 00

Classical attributes as blinking, non displayed, inverse or intensified may be implemented by loading proper colour values into the different palet cells.

E.g. nondisplayed is obtained by having a palette selector selecting a set of palet cells containing some colour in foreground and background (for D=1 and D=0), and a blinking attribute is maintained by changing the foreground five or six times per second.

2.2.4 CRT Timing

2.2.4

The 82730 takes care of the CRT timing i.e. the Vertical and Horizontal sync pulses and the visible picture field. These timing pulses are generated from a 1,25 MHz clock called RCLK (see Intel 82730 manual). Various constant must be programmed into the 82730 at initialization time. These constants indicate duration of a videoline, position and with a sync pulse, start and stop at visible field in terms of RCLK counts.

For a 720 dot per videoline-screen, the visible part of the video line should have a duration of 45 RCLK's.

Mode PARAMETERS to 82730 for a 50Hz, 15.625 KHz monochrome monitor, with 25 x 80 characters and a dotmatrix of 7 x 11.

```

HSYNCSTP = 8
HBRDSTRT = 24
HFLDSTRT = 25
HFLDSTP  = 105
HBRDSTP  = 106
LINELEN  = 114
VSYNCSTP = 3
VFLDSTRT = 27
VFLDSTP  = 309
FRAMELEN = 312

```


2.2.5 Graphic Mode

2.2.5

If bit 6 in the output register C of the 8255 PPI is set to 1 graphic mode is selected. For access of 8255 PPI see chapter 11.

2.2.6 Display Kind Indication

2.2.6

Bit 6 and 5 in port B of the PPI (see chapter 11) are used to indicate which kind of display is connected to the system.

Bit 5 = 0 indicates a colour display is attached.
Bit 5 = 1 indicates a monochrome display.
Bit 6 = 0 indicates a linefrequency of 15,625 KHz
Bit 6 = 1 indicates a linefrequency of 22 KHz

2.2.7 CRT Interrupt

2.2.7

The 82730 may be programmed to generate interrupt on several conditions. Interrupts from 82730 are connected to the Int 4 input of the 8259.

3. KEYBOARD

3.

The keyboard is connected to the system via a special serial port on address IO base + 20 Hex. When a character is received, an interrupt is generated (IR1 activated), and no further characters will arrive before the character is read.

The powersupply to the keyboard is controlled by means of bit 7 in the C register of the PPI (see chapter 11).

If bit 7 is set to 1, the KB power is on.

If bit 7 is set to 0, the KB power is off.

Within 0,5 - 1,0 sec. after power-up, the keyboard must be read in order to initialize the keyboard-receiver circuit.

Approximately 2 sec. after power-up, the keyboard will transmit a self-test-complete code, or 1 to 3 errorcodes. The next transmitted character, will be the character, identifying the version of the keyboard (Nationality code).

4. NON VOLATILE MEMORY

4.

The "NVM" is made up by a 256 by 4 bit CMOS RAM with battery backup.

The NVM is divided into 4 blocks of 64 words by 4 bits each. One of the four blocks is selected by means of bit 4 and 5 in port C of the PPI (see chapter 11).

Inside the selected block, the 64 words are accessible on the even addresses from I/O base+ 80 to I/O base + FE.

The four bits is connected to bits 0 to 3 of the I/O bus.

When accessing the NVM, 3 wait-states must be used, i.e. 3 wait-states must be programmed into the CPU.

5. REAL TIME CLOCK

5.

The Real Time Clock is a CMOS LSI chip with battery backup, which allows the clock to continue the counting when the system is powered down.

The Real Time Clock (RTC) is a very "slow" device, so a special read and write procedure is to be performed.

In the following description of the procedure, A is indicating the internal addresses and the registers and latches containing the time information.

Read the RTC

ADD. I/O BASE +	OPERATION		DATA BUS BIT NO. 76543210	COMMENTS
	WRITE	READ		
5C H	X		100A 4A 3A 2A 1A 0	Put on the address of the desired register or latch
5C H	X		101A 4A 3A 2A 1A 0	Create an internal read-pulse
WAIT FOR 1 μ S (2 internal CPU Cycles)				
5C H		X	RTC DATA	Read data from RTC
5C H	X		100A 4A 3A 2A 1A 0	Remove the internal read-pulse

Write to the RTC

ADD.	OPERATION	DATA BUS	COMMENTS
I/O BASE	WRITE	BIT NO.	
+		76543210	
5 CH	X	000A'4A'3A'2A'1A'0	Put on the address of the desired register or latch
5 CH	X	RTC DATA	Read data to RTC
5 CH	X	010 A'4A'3A'2A'1A'0	Create an internal write-pulse
WAIT FOR 1 μ S (2 internal CPU Cycles)			
5 CH	X	000A'4A'3A'2A'1A'0	Remove the internal write-pulse

The following table is showing the content of the internal registers and latches.

The following table is showing the content of the internal registers and latches.

Internal Addr.						Function	READ
Bit no.					(HEX)		WRITE
A4	A3	A2	A1	A0	(HEX)		
0	0	0	0	0	(00)	C Seconds * 0.0001	R/W
0	1	0	0	0	(08)	L	
0	0	0	0	1	(01)	C Seconds * 0.01	
0	1	0	0	1	(09)	L	
0	0	0	1	0	(02)	C Seconds	
0	1	0	1	0	(0A)	L	
0	0	0	1	1	(03)	C Minutes	
0	1	0	1	1	(0B)	L	
0	0	1	0	0	(04)	C Hours	
0	1	1	0	0	(0C)	L	
0	0	1	0	1	(05)	C Day of week	
0	1	1	0	1	(0D)	L	
0	0	1	1	0	(06)	C Day of month	
0	1	1	1	0	(0E)	L	
0	0	1	1	1	(07)	C Months	
0	1	1	1	1	(0F)	L	
1	0	0	0	0	(10)	Interrupt Status	R
1	0	0	0	1	(11)	Interrupt Control	W
1	0	0	1	0	(12)	C reset	W
1	0	0	1	1	(13)	L reset	W
1	0	1	0	0	(14)	Status bit	R
1	0	1	0	1	(15)	"GO" command	W
1	0	1	1	0	(16)	Standby Interrupt	W
1	1	1	1	1	(1F)	Test mode	

L = latch C = counter.

The clock contains a counter chain counting from the crystal frequency of 32768 Hz down to one/year.

Moreover the clock contains a latch of same length and format as the counter. Both the latch and the counter may be read and loaded at any time.

The counter and latch are constantly compared giving an interrupt (it enabled) when they are equal. This means that you may receive an interrupt on a certain millisecond this year.

Both counter and latch are divided into sections corresponding to normal decimal notation:

1	9	3	9	0	7	2	9	5	9	5	9	9	9	9	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

Month Day of M. Day of W Hour Minute Second S*0.01 S*0.0001

This illustration shows the maximum value of the single BCD digits (four bit groups), not the maximum value of the byte. These are different for

Month : 11
 Day of M. : 31, 30, 29 or 28
 Hour : 23

Three reset commands exist:

Latch reset
 Counter reset and
 "Go" command.

The latch reset and counter reset clear the byte specified by the data in the write command:

Only one bit may be set, and the byte to be cleared is pointed out as follows:

D0 : Sec. * 0.0001
 D1 : Sec. * 0.01
 D2 : Seconds
 D3 : Minutes
 D4 : Hours
 D5 : Day of week
 D6 : Day of month
 D7 : Month

The same is done by writing a zero into the corresponding register.

By means of the "Go" command the second counter, and the "fraction of a second" counters are reset, to enable an exact starting time.

By setting one or more bits in the interrupt control register, interrupt will occur on IR3 on one or more of the following events:

D0 : Counter: = latch
D1 : sec. * 0.1: = 0
D2 : Seconds: = 0
D3 : Minutes: = 0
D4 : Hours: = 0
D5 : Day of week: = 0
D6 : Day of month: = 0
D7 : Month: = 0

(:=) means that the counter rolls over.

By reading of the status register, it can be deduced which of the above mentioned reasons had caused the interrupt.

After the time is read the statusbit in address 14 H should be read also. This bit is gated to D0 and indicates if the counters have changed during the read operation, making the reading unsafe.

When bit no. 1 in the PPI port B "0" the following description of the internal registers and latches will be valid.

Control register

This register controls the following:

Frequency select (B0, B1)
 Start/stop (B2)
 Counter/Latch Control (B3)
 Clock select (B4, B5, B6, B7)

Control register:

B7	B6	B5	B4	B3	B2	B1	B0
----	----	----	----	----	----	----	----

The frequency select bits (B0, B1) must always be 00 (zero). This indicates that the reference frequency used by the RTC will be 32768Hz.

The start/stop bit (B2) starts and stops the RTC. B2 = 1 starts the RTC. B2 = 0 stops the RTC.

The counter/latch control selects the counter or the latch function of a certain register.

B3 = "0" = "Write to counter and disable alarm".
 B3 = "1" = "Write to latch and enable alarm".

If first B3 is set to "0" and then date is written to i.e. the address XX011 then the minutes counter is located. At the same time the alarm is disabled. I.e. that no RTC-interrupt will occur. When the contents of the counters matches the contents of the alarm latches. If the alarm is to be enabled the control register must be accessed and B3 set to "1". When data is written to address XX011 while B3="1" then the minutes alarm latch will be accessed.

The clock select bits (B7, B6, B5, B4) controls the rate of which interrupts occur.

An RTC-interrupt can be generated in two different ways: As described above an interrupt will occur when B3 in the control register is set to "1" and the content of the counters matches the content of the latches.

The second way to generate an RTC-interrupt is to choose a clock-signal (50% duty cycle) as the interrupt source. The following table shows the possible clock-signals.

B7	B6	B5	B4	
0	0	0	0	disable
0	0	0	1	488,2 μ S
0	0	1	0	976,5 μ S
0	0	1	1	1953,1 μ S
0	1	0	0	3906,2 μ S
0	1	0	1	7812,5 μ S
0	1	1	0	15,625 μ S
0	1	1	1	31,25 μ S
1	0	0	0	62,5 μ S
1	0	0	1	125 μ S
1	0	1	0	250 μ S
1	0	1	1	500 μ S
1	1	0	0	Sel.
1	1	0	1	Min.
1	1	1	0	Hour
1	1	1	1	Day

When an RTC-interrupt is detected the Interrupt status register can be read in order to determine the source of the interrupt.

When bit no. 7 (MSB) is set to "1" the interrupt source is the alarm. When bit no. 6 is set to "1" the interrupt source is the clock. Bit no. 0-5 in the Int. Status register will always be zero.

The counters and latches from seconds through months holds the time and alarm information in BCD.

The bit no. 7 (MSB) of the hours counter/latch indicates AM and PM. The bit is set to "0" when AM and set to "1" when PM.

Bit no. 6 at the hours counter/latch determines 12 hours or 24 hours operation. When set to "1" the 12 hours operation is selected. When set to "0" the 24 hours operation is selected. When set to "0" the 24

hours operation is selected.

The bit no. 7 (MSB) of the month counter should be set to "1" when the year is a loop year.

6. SOUND DEVICE

6.

The sound generator creates sound to the loudspeaker located in the RC759 cabinet.

The Sound Generator (SOGE) is a write-only register. A special write-procedure must be performed to ensure that the SOGE accepts the written data.

Write Procedure

ADD. I/O BASE +	OPERATION		DATA BUS BIT NO.	COMMENTS
	WRITE	READ	76543210	
56 H		X		Ignore the read data!
5 CH	X		000XXXXX	Prepare the SOGE to receive data
5 AH	X		DATA TO SOGE	Write data to sound Generator
56 H	X		XXXXXXXX	Create a write-pulse to SOGE

X = dont care

Four of the dividers are ten bit wide, and may be programmed individually to divide a frequency of 62,5 KHz with any integer in the range 1 to 1024. The outputs are square waves with 50% dutycycle, and fed into each their attenuator.

The forth divider divides the 62,5 KHz with 16, 32 or 64 or just takes the output of the third of the above named dividers, and outputs the result into a pseudo random generator creating pink noise. The noise is fed into the fourth attenuator. Each attenuator can damp the input from 0 dB down to -28 dB in steps of 2 dB or turn the input entirely off.

The generator has registers for the control of the above mentioned functions:

register	
0	tone 1
1	tone 2
2	tone 3
3	noise

The frequencies require two bytes for update:

	bit 7	6	5	4	3	2	1	0
First byte	1	tone	0	f3	f2	f1	f0	
Second byte	0	X	f9	f8	f7	f6	f5	f4

Where $(f_0-f_9)+1$ is the modulus for the selected divider.

The noise generator is programmed with one byte:

bit	7	6	5	4	3	2	1	0
	1	1	1	0	X	FB	NF1	NF0

Where FB selects noise type:

FB = 0: periodic noise
 1: white noise and
 NF selects "noise frequency":
 NF 1,0 =
 00: 3,90 KHz
 01: 1,95 KHz
 10: 0,98 KHz
 11: output from tone 3.

The attenuators are programmed with one byte each:

bit	7	6	5	4	3	2	1	0
	1	generator	1	A3	A2	A1	A0	

A0 to A3 control four stages at attenuation:
 A0 damps 2 dB when 1
 A1 damps 4 dB when 1
 A2 damps 8 dB when 1
 A3 damps 16 dB when 1
 if A0-A3 = 1111 the output is off.

The Sound Generator is a single-source, i.e. that one cannot always be sure on the presence of the Sound generator. To detect whether the SOGE is present or not, the following procedure can be performed.

Present Detection

ADD.	OPERATION		DATA BUS BIT NO.	COMMENTS
	I/O BASE	WRITE		
+			76543210	
5 CH		X	000XXXXX	Prepare the SOGE to receive data
5 AH		X	11111111	Write data to SOGE
56 H		X	XXXXXXXX	Create a write-pulse to the SOGE

X = dont care

Within 10 us after the above described procedure, a read-operation should be performed to PPI port B. If bit no. 2 in the read data is zero (0), then the Sound Generator is present. If the Sound Generator is not present, sound can be made by using the CPU timer no. 1.

7. iSBX CONNECTOR

7.

This connector is supported in accordance to the iSBX bus standard from INTEL. In the following is listed the I/O addresses available to this connector. The iSBX connector is controlled by /PCS 6 (IO Base + 300 H) I/O decode output from the 80186 microprocessor.

I/O device number (Hex)	iSBX function	Direction
IO Base + 300 to IO Base + 30F	} Modul Select /MCS0	} I/O
IO Base + 310 to IOBase + 31F	} Modul Select /MCS1	} I/O
IO Base + 320	DMA Acknowledge /MDACK	I/O
IO Base + 330	Terminal Count + TC	0

INTR 0 from iSBX is connected to INT1 of 80186.
 INTR 1 from iSBX is connected to INT3 of 80186.
 OPTION 0 from iSBX is read from PPI port A bit 2.
 OPTION1 from iSBX is read from PPI port A bit 3.
 Bit 1 of PPI port A is zero if an iSBX module is inserted in the connector.

8. CASSETTE INTERFACE

8.

The cassette interface control is implemented in software. Timer 0 output from 80186 is used to control the data to the cassette recorder. Timer 0 is enabled by bit 0 in PPI port C. The cassette input data is read by PPI port A bit 0. Software algorithms are used to generate and read cassette data. The cassette drive motor is controlled (ON/OFF) by PPI port C bit 1 (0/1). In the following is described the Cassette Write and read procedures.

8.1 Cassette Write

8.1

The WRITE BLOCK routine writes a tape block on the cassette. The tape block is described in Data Record Architecture page (fig. 6).

The WRITE BLOCK routine turns on the cassette motor and a synchronization bit (0) and then writes 256 bytes of all ones, the leader, to the tape. Next, one or more data blocks are written. After each data block of 256 bytes, a two byte CRC is written.

The WRITE BYTE routine disassembles the byte and writes it a bit a time to the cassette. The method used is to set TIMER 0 to the period of the desired data bit. The timer is set to a period of 1.0 millisecond for a one bit and 0.5 millisecond for a zero bit.

The timer is set to output a square wave with period given by its count register. The timer's period is changed on the fly for each data bit to be written to the cassette. If the number of data bytes to be written is not an integral multiple of 256, then after the last desired data byte from memory has been written, the data block will be extended to 256 bytes by writing multiples of the last data byte. The last block will be closed with two CRC bytes as usual. After the last data block, a trailer consisting of four bytes of all one bits will be written. Finally, the motor will be turned off.

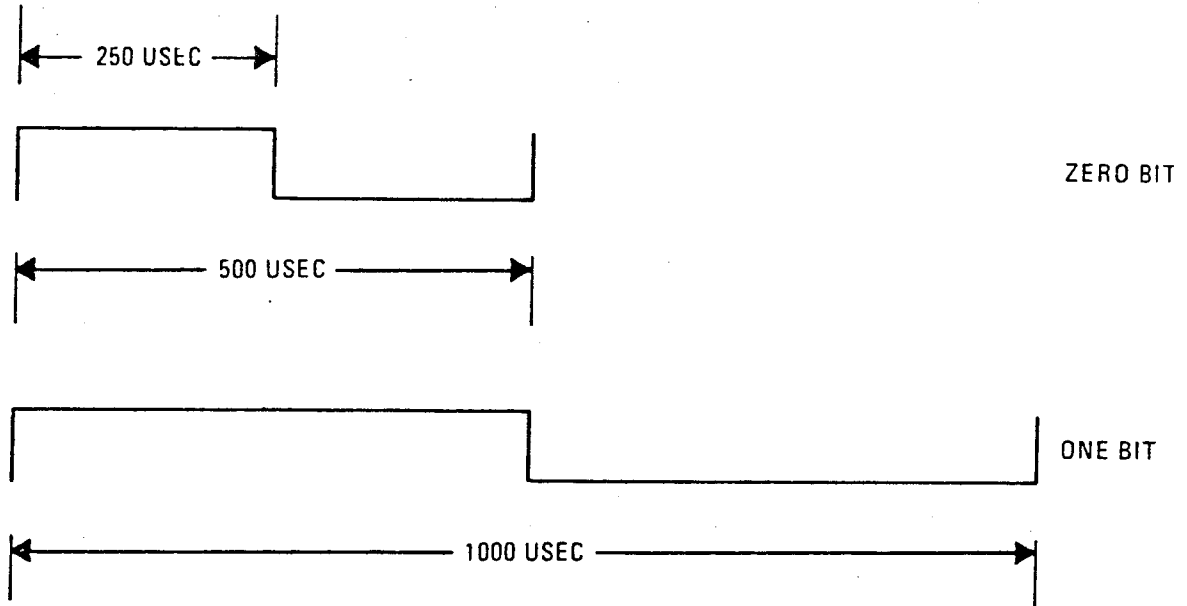


Fig. 5.

8.2 Cassette Read

8.2

The READ BLOCK routine turns on the cassette motor and then delays for approximately 0,5 secs for it to come up to speed.

The READ BLOCK routine then searches for leader and must detect all one bits for approximately 1/4 of leader length before it can look for the sync byte. If a correct sync byte (X'16') is not found, the routine goes back and searches for leader again. The data is read a bit at a time and assembled into bytes. After each byte is assembled it is written into memory.

After each multiple of 256 data bytes are read, the CRC is read and compared to the CRC generated.

8.3 Data Record Architecture

8.3

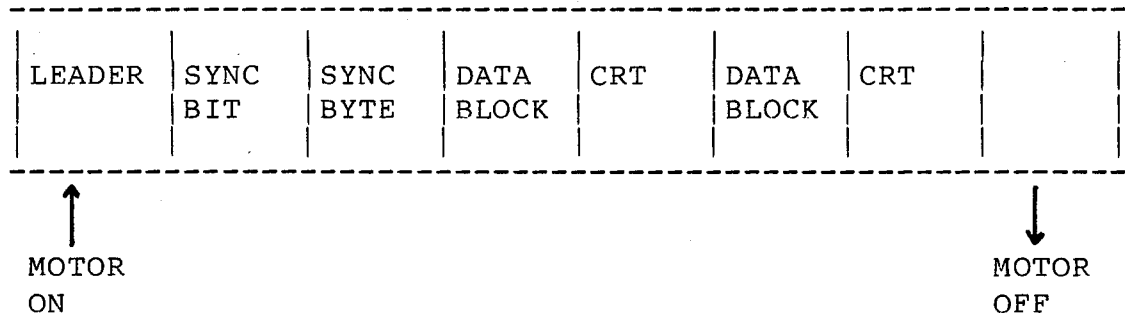


Fig. 6.

1. Leader 256 bytes (of ones)
2. Sync byte ASCII Sync Char (X'16')
3. Sync byte (X'16')
4. Data Blocks 256 bytes
5. CRC -- 2 bytes -- for each data block

ERROR RECOVERY

Error recovery is handled by software. A cyclic redundancy check (CRC) is used to detect errors. The polynomial used is:

Which is the polynomial used by the SDLC interface. Essentially, as bits are written/read from tape, they are passed through the CRC-register in software. After a block of data is written, the complemented value of the calculated CRC-register is written on tape. On reading the cassette data, the CRC bytes are read and compared to the generated CRC value.

9. Floppy/Printer Connector

9.

This connector is used to control an external box with a Floppy interface + drive and a parallel printer interface. This floppy and printer can be shared by 4 Piccoline's, so the Floppy or Printer has to be reserved before use. After the reservation is acknowledged the unit is owned by the current Piccoline until released again. In the following is listed the I/O device groups used to control the external floppy/printer unit.

I/O device (HEX)	Direction	Description
IOBASE +280	I/O	Addresses to the Floppy Controller refer to section 9.1.
+282	I/O	
+284	I/O	
+286	I/O	
+288	0	
		Floppy drive kind select Refer to section 9.1.
+28A	I/O	Printer Data } refer to section 9.2.
28C	I/O	
+28E	0	Reserve Floppy
+290	0	Release Floppy
+28E	I	Bus 7=1 means Reserve Ack of Floppy Bus 7=0 means wait upon Floppy.
+292	0	Reserve Printer
+294	0	Release Printer
+292	I	Bus 7=1 means Reserve Ack of Printer. Bus 7=0 means wait upon Printer.

The Floppy controller is connected to DMA channel 1 on the 80186 microprocessor. Interrupt from the Floppy connector is connected to IRO of the 8259 interrupt controller. Interrupt from the Printer connector is connected to IR2 of the 8259 interrupt controller.

9.1 Floppy Disc Controller

9.1

The floppy disc controller is based on the WD 1797/WD2797 controller chip and supports the following.

- Up to two 5 1/4 inch drives connected in daisy chain
- Data transfer by DMA
- 8" compatible 5 1/4 inch drives
- Dual Side/Single Density 125 kbps, FM
- Dual Side/Dual Density 250 kbps, MFM
- Dual Side/Quadruple Density 250 kbps, MFM
- Dual/Side/Dual Density 500 kbps, MFM
- Multisector transfer capability
- Programmable Write Precompensation

9.1.1 FDC/CPU I/O Interface

9.1.1

The floppy disc controller (FDC) and an external control register (FCR) (for clock selection, precompensation, motor on/off and drive select) are accessed by I/O commands as follows:

I/O Base Addr.

offset (HEX)	I/O	FUNCTION
280	I	Read FDC Status Register
	O	Write Control Command.
282	I	Read FDC TRACK Register
	O	Write FDC TRACK Register
284	I	Read Sector Register
	O	Write Sector Register
286	I	Read Data Register
	O	Write Data Register
288	O	Write FCR Register
	I	Not defined

For further information on programming the registers on addr. 280-286 refer to Western Digital data sheet on WD1797.

9.1.2 FDC/DMA Interface

9.1.2

The floppy disc controller is normally initialized to transfer data in DMA-mode and then requires a DMA channel to be allocated (DMA channel 1).

The FCR register has the following layout:

Bit-No

(0 = LSB)	Name	Description
0	Drive sel.	Selects between drives, a 0 selects drive 0. a drive is only selected if its motor is on.
1	Motor 0.	
2	Motor 1	0: Motor OFF, 1: Motor ON.
3	Precomp Enable Write	precompensation 0: Disabled 1: Enabled
4	Precompensation.	125 nsec 250 nsec
5	-, DD	0: Dual density 1: Single density
6	2 MHz	WD 1797 Clock select 0: 1 MHz (5 1/4") 1: 2 MHz (8")
7	READY CONTROL	0: Ready from drive 1: Ready always set

Precompensation is only used in MFM-mode and is normally applied in the following way together with LOW CURRENT:

CYLINDER NO PRECOMPENSATION

0-43	125 nsec.
44-77	250 nsec.

This control sceme may be refined as required by the actual drives.

9.2 External Printer Controller

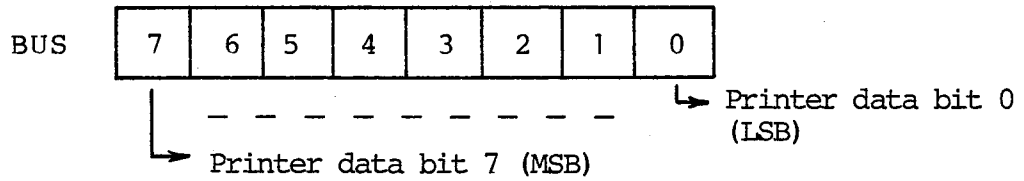
9.2

This parallel printer interface ("Centronic compatible") is controlled by programmed I/O instruction.

9.2.1 Set Printer Data

9.2.1

Output to device <IOBASE + 28A> puts the contents of the microprocessor bus into the printer data register.



9.2.2 Read Printer Data

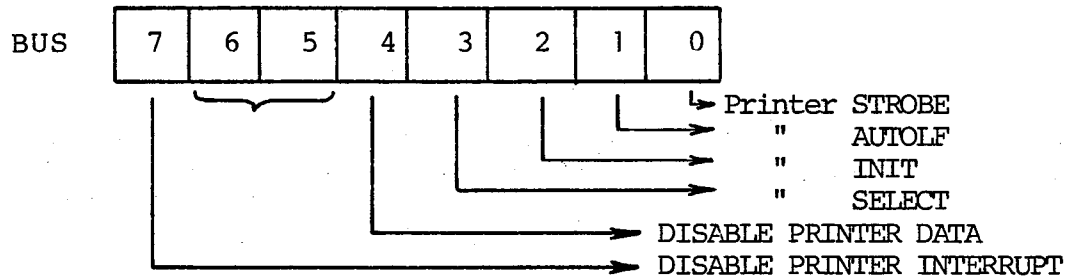
9.2.2

Input from device <IOBASE + 28 A> reads the contents of the Printer Data Register back to the microprocessor.

9.2.3 Set Printer Control

9.2.3

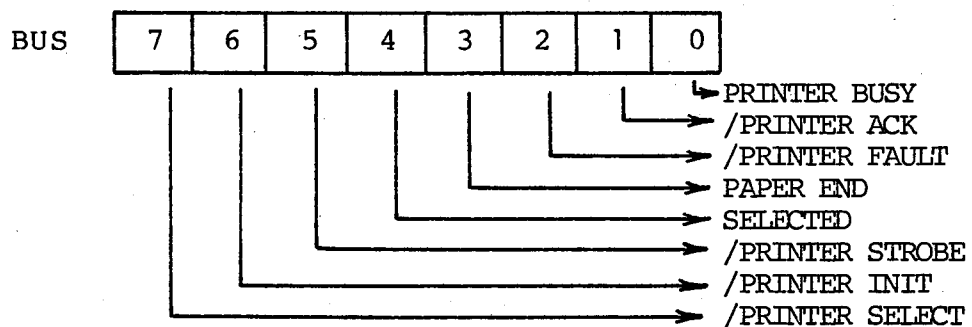
Output to device <IOBASE + 28 C> sets the printer control register.



9.2.4 Read Printer Status

9.2.4

Input from device <IOBASE + 28C>



Status bit 7 - 5 is the inverted signals from the Control register bit 3, 2 and 0 (set in section 9.2.3). Status bit 4 - 0 represents the printer status.

When the printer shifts from BUSY to NOT BUSY status, an interrupt is generated (IR2 to the 8259 controller).

10. LOCAL PRINTER CONTROLLER

10.

This parallel printer interface ("Centronic compatible") is identical to that described in section 9.2, but controlled by I/O instructions to different device numbers.

I/O device

number (hex)	Direction	Function
IOBASE + 250	0	Set printer Data Register
+ 250	I	Read Printer Data Register
+ 260	0	Set Printer Control
+ 260	I	Read Printer Status

The printer interrupt (BUSY → NOT BUSY) is connected to IR6 on the 8259 interrupt controller.

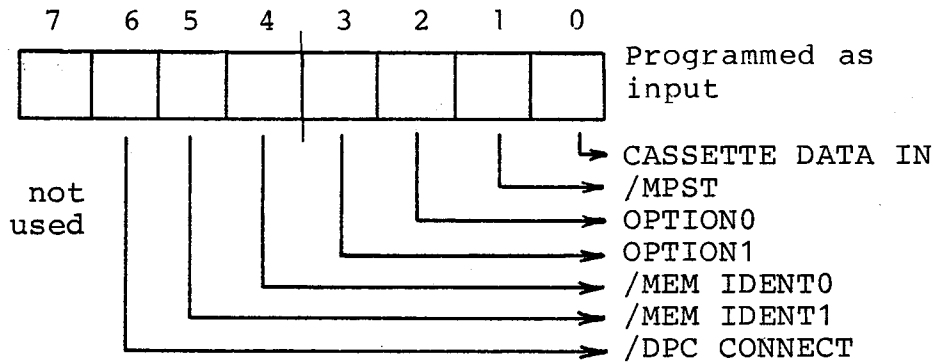
11. PPI 8255

11.

The parallel ports in the 8255, connected to the addresses IOBASE + 70 to IOBASE + 76 are used in the following way:

11.1 Port A (IOBASE + 70)

11.1



- CASSETTE DATA IN contains the serial data stream from the cassette tape.
- /MPST is zero if an iSBX module is installed.
- OPTION 0 (1) are optional status signals from iSBX modules. The function of these signals depends on the used iSBX module.
- /MEM IDENT 0 (1) defines the memory configuration.

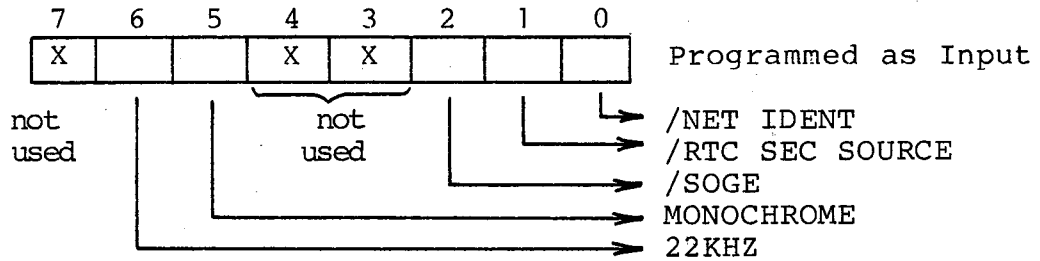
/MEM IDENT 0	/MEM IDENT 1	RAM memory size
1	1	256 kbytes
1	0	256 + 128 kbytes
0	1	256 + 512 K (using 256 k x 1 bit chip)
0	0	640 K

The shown ram size is excl. the 32 kbytes pixel memory,

- /DPC CONNECT is zero, if connection to external Floppy/printer box is installed.

11.2 PORT B (IOBASE + 72)

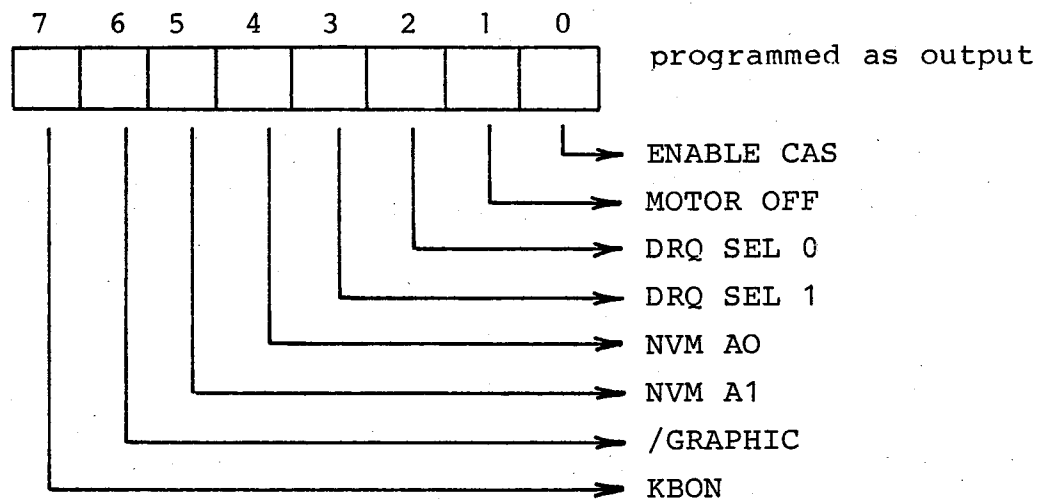
11.2



- /NET IDENT is zero if the MICRONET controller is present in the RC PICCOLINE
- /RTC SEC SOURCE is zero if the second source real time clock chip (RCA CDP1879) is used.
- /SOGE is used to detect presence of the sound generator as described in section 6.0.
- MONOCHROME is one if a monochrome CRT monitor is connected.
- 22kHz is one if a CRT monitor with a linefrequency of 22kHz is used.

11.3 PORT C (IOBASE + 74)

11.3



- ENABLE CAS enables output from the 80186 timer generating the bitstream to the cassette tape. and the ram memory.
- MOTOR OFF, if one stops the cassette tape motor.
- DROSEL 0(1) selects the source for the 2 dma channels in the 80186 microprocessor.

DROSEL 0 - 1	DMA 0 SOURCE	DMA 1 SOURCE
0 0	iSBX	DPC (external Floppy)
0 1	0	0
1 0	0	1
1 1	1	0

NVMA0 (1) gives the block address to the non volatile memory as described in section 4.0.

/GRAPHIC controls the mode of the CRT logic. If zero, graphic mode is selected.

KBON controls the power to the keyboard. If KBON = 1 the keyboard is supplied with power.

11.4 Control word (IOBASE + 76)

11.4

This register is used to define the mode of the 8255 PPI. This register should initially be loaded with the following contents.

IOBASE + 76 : 1 0 0 1 0 0 1 0 (or 92 H)

The bits in port C may be set/reset in the following way:

IOBASE + 76 : 7 6 5 4 3 2 1 0
o o o o bit no. v

The value of V is loaded into part c (bit no).

12. ADDRESSES

12.

<u>IO area</u>	<u>Peripheral</u>	<u>Direction</u>	<u>Interrupt</u>	<u>DMA Request</u>
IO base + 0	8259 Interrupt crt			
IO base + 20	Keyboard	I	1	
IO base + 50	Sound + real time clock	0	3	
IO base + 60	CRT control	0	4	3
IO base + 70	PPI Port A	I		
IO base + 72	PPI Port B	I		
IO base + 74	PPI Port C	0		
IO base + 76	Control for 70-74	0		
IO base + 80	to FE NVM	I/O		
IO base + 100	Ch. AH to NET			
IO base + 180	to 19F Palet	0		
IO base + 280	Floppy control	I/O	0	0
IO base + 282	track			
IO base + 284	sector			
IO base + 286	data			
IO base + 288	Floppy control	0		
IO base + 230	Reset Int CRT			
IO base + 240	Ch. Att.			
IO base + 28A	ext.printer data	I/O		
IO base + 28C	- - control	I/O	2	
IO base + 28E	Reserve Floppy	0		
+ 290	Release -	0		

IO base + 28E	Test Floppy	I		
IO base + 292	Reserve Printer	0		
+ 294	Release -	0		
IO base + 292	Test Printer	I		
IO base + 250	local Printer data	I/O	6	
+ 260	- - control	I/O		
IO base + 300	iSBX	I/O	INT1	0
to + 30F			(80186)	
IO base + 310	iSBX	I/O	INT3	0
to + 31F			(80186)	
IO base + 320	DMA ACK to iSBX	0		
IO base + 330	TC to iSBX	0		

A. INDICES

A.

A.1 Survey of Figures

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Reference Manual

RCSL No.: 99- 0 00825

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