

L1BV og L1BH hentes fra Koer.

VOL og V0AR som BESK KM 1001-22.

$$\checkmark V_{A\alpha} AR_v = LIA \cdot \bar{E}_1$$

$$\checkmark V_{A\alpha} IR = LIIR \cdot \bar{E}_1$$

$$\checkmark V_{A\alpha} L = \frac{V_{A\alpha} AR_v + V_{A\alpha} IR + LIB \cdot \bar{E}_1}{V_{A\alpha} AR_v + V_{A\alpha} IR + LIB \cdot \bar{E}_1}$$

$$\checkmark V_{0\alpha} AR_v = LIA \cdot \bar{A}_S \cdot \bar{E}_1$$

$$\checkmark VOL = \overline{V_{0\alpha} AR}$$

$$\checkmark h_{\alpha} AR_v = LIA \cdot E_1 \cdot E_2$$

$$\checkmark h_{\alpha} AR_h = LIA \cdot \bar{E}_4$$

$$\checkmark h_{\alpha} IR = LIIR \cdot E_1$$

$$\checkmark h_{\alpha} L = \frac{h_{\alpha} AR_v + h_{\alpha} AR_h + h_{\alpha} IR + LIB \cdot E_1}{h_{\alpha} AR_v + h_{\alpha} AR_h + h_{\alpha} IR + LIB \cdot E_1}$$

$$\checkmark h_0 AR_v = LIA \cdot \bar{A}_S \cdot E_1 \cdot E_2$$

$$\checkmark h_0 AR_h = LIA \cdot \bar{A}_S \cdot \bar{E}_4$$

$$\checkmark h_0 L = \overline{h_0 AR_v + h_0 AR_h}$$

Styring af katodefølgere:

$$\bar{V} = \tau_1 \cdot \bar{E}_1$$

$$\bar{H} = \tau_2 \cdot E_1$$