ID-7o12

4-port Async./sync. communication module

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1. General Description

This module contains 4 communication ports for the ID-7000 microprocessor system on a single PC-board. The 4 ports may individually be used in asynchronous - or synchronous mode by appropriate program initialization. The module contains a programmed frequency divider to generate a large number of clock frequencies for asynchronous operation and for synchronous operation (in applications where a local clock is wanted). Strapping of the baud rate for each port is performed in the top connector of the module.

In addition to the data in/data out connections each port contains the following V24 signals: Transmitter clock input, receiver clock input, clear to send input, data set ready input and request to send output. Signal levels are in accordance with the CCITT V24 standard.

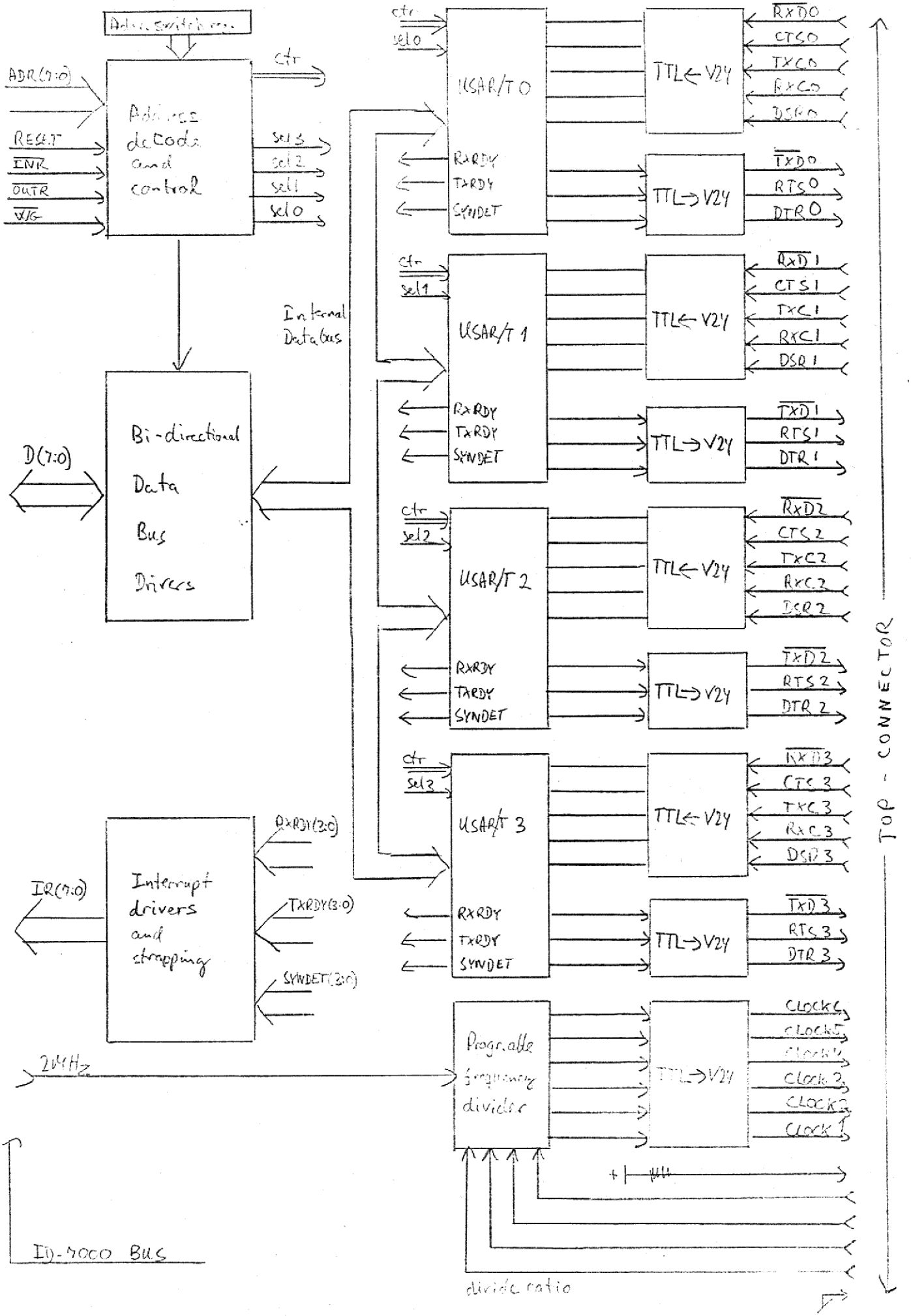
The interrupts from the ports (receiver ready, transmitter ready and sync. detect) may be strapped to any of the 8 interrupt request lines. Also the interrupt conditions may be sensed, allowing several interrupt sources to share the same interrupt request line, or to run the module without use of interrupts at all.

Fig. 1 shows a blocked schematic of the module.

Appendix 1 contains the detailed logic schematic of the module.

Appendix 2 contains a data sheet containing programming information for the LSI chip used in each port of the module.

Navn	Lb. nr.	Dato	Emne	Fag	Afd.	Side
ID-7012. 4-port communication card. Blocked schematic					UDV/OL	2



2. Programming

2.1 Addressing. The communication between the module and the CPU is performed by means of IN- and OUT instructions. The module uses 8 of the 256 I/O-addresses for the 8080. A switch register on the board determines the base address (8 x n, n = 0, 1, 2, ..., 31) of the module. The decoding of ADR(7:0) is performed as follows:

ADR(7:3) selects the module

ADR(2:1) selects one of four communication ports:

ADR(2)	ADR(1)	PORT
0	0	0
0	1	1
1	0	2
1	1	3

ADR(0) determines whether data or control/status are transferred. (ADR(0) = 0: data; ADR(0) = 1: control/status).

Detailled programming information is given in appendix 2 containing the data sheet for the 8251 Universal Synchronous/Asynchronous Receiver/ Transmitter used in each port of the module.

2.2 Interrupts. Each port of the module contains three interrupt sources: Transmitter Ready (TxRDY), Receiver Ready (RxRDY) and SYNC Detect (SYNDET). These interrupt sources which are activated and deactivated according to the rules described in appendix 2, may by connected to the IR(7:0) interrupt request bus of the ID-7000 system by means of a 24 pin strap plugged into a socket on the board as shown in the logic schematic (appendix 1, page 3). The interrupt drivers are open collector, active low, allowing a maximum of 8 interrupt sources sharing the same interrupt request line.

3. Straps and connections

The baud rate strapping and the connections to the communication equipment (data terminals, modems etc.) are performed on the top connector of the module.

Each port has the following connections in the top connector:

inputs:	Received Data	RxD
	Clear to Send	CTS
	Transmitter Clock	TxC x)
	Receiver Clock	RxC x)
	Data Set Ready	DSR
outputs:	Transmitted Data	TxD
	Request To Send	RTS
	Data Terminal Ready	DTR

All inputs and outputs are in accordance with the CCITT V24 standard.

The module contains a programable frequency divider generating 6 different clock frequencies (CLOCK 1 - CLOCK 6) all available in the top connector. The signal levels and drive capacity of these outputs are in accordance with the CCITT V24 standard. The frequencies at the clock output are determined by the count down ratio of a prescaling divide by n (2 n 16) counter. n is determined by the logical signals on the counter input I_D, I_C, I_B, I_A, which can be strapped to logical zero- and one-levels in the top connector. Two basic values of n (13 and 9) yields standard frequencies as follows:

CLOCK	n = 13 ($I_DI_CI_BI_A$ = 0011)	n = 9 ($I_DI_CI_BI_A$) = 0111
6	38400	56320
5	19200	28160
4	9600	14080
3	4800	7040
2	2400	3520
1	1200	1760

x) These inputs should be used in both asynchronous and synchronous data transmission. In synchronous mode these signals are equivalent to the CCITT V24 signals: transmitter signal element timing and receiver signal element timing.

These are the frequencies to be used in synchronous data transmission. When asynchronous data transmission is used, frequencies 64 or 16 times less may also be used by appropriate programmed initialization of the corresponding port.

Table 1 shows the connections to the top of the module.

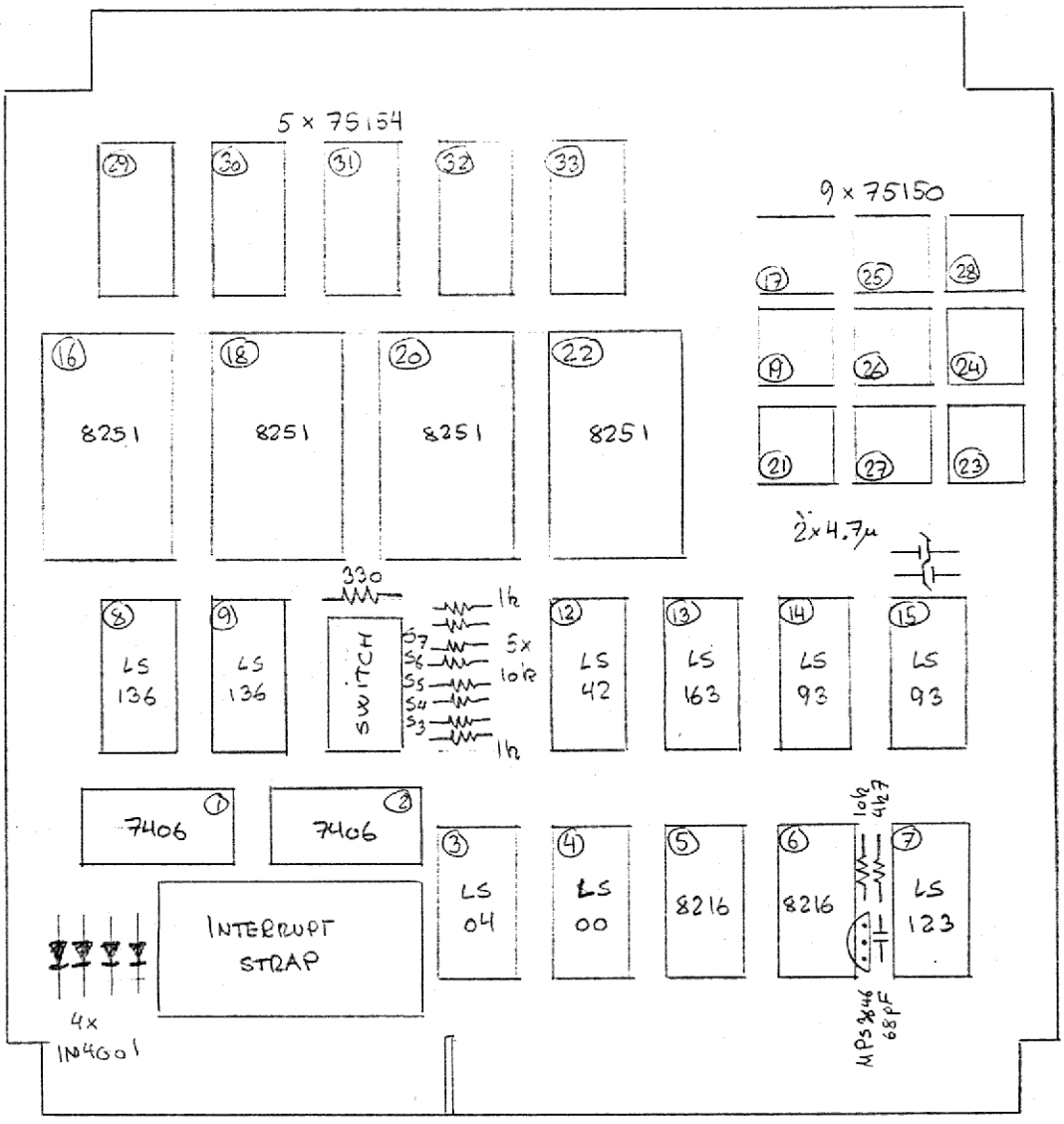
4. Power requirements

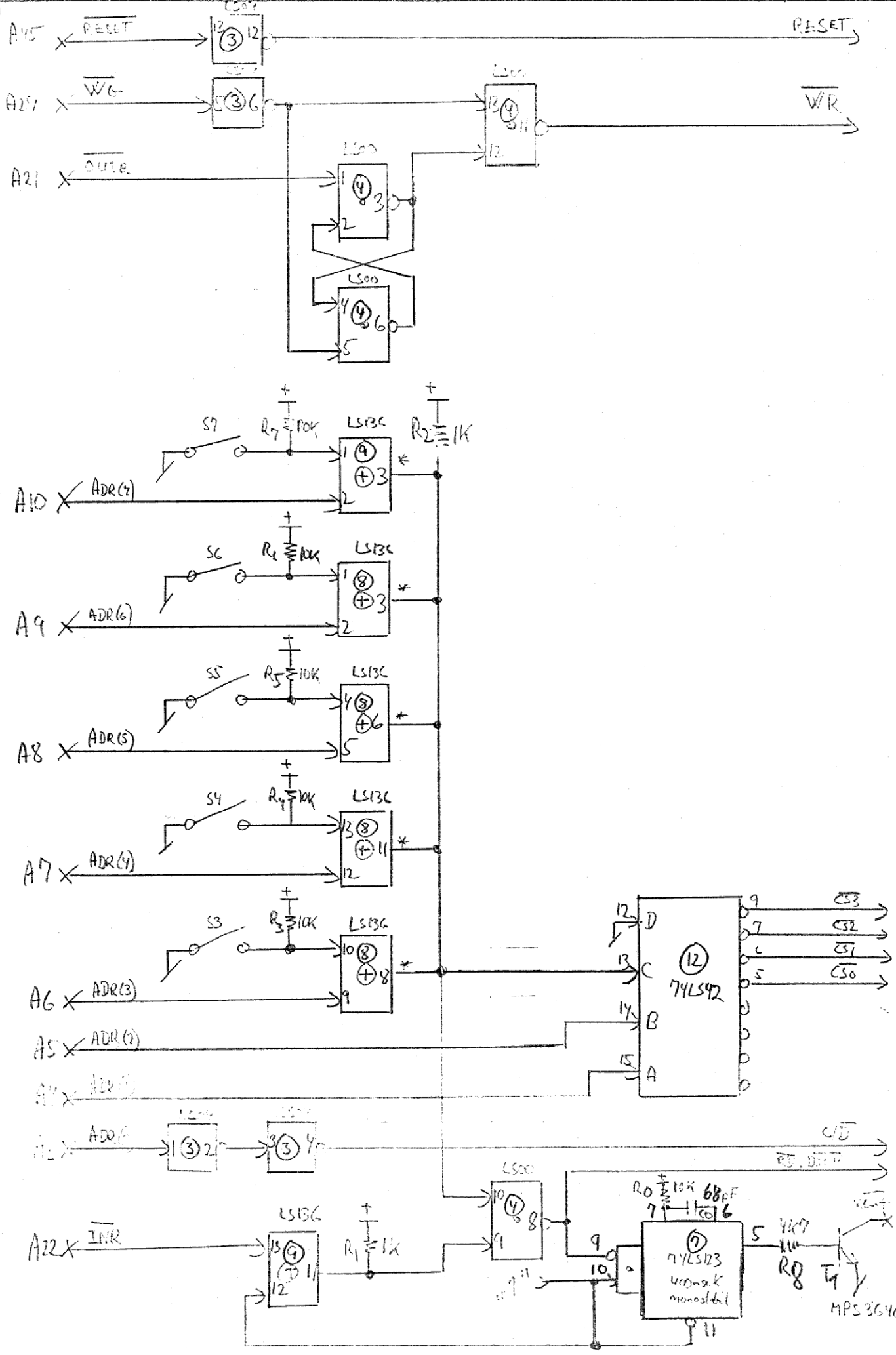
The module uses the standard ± 5V and standard ± 12V supply of the ID-7000 microprocessor system. Furthermore a -12V supply is needed. This voltage is generated from the -15V analog supply rial on pin B9 is the bus. The power requirement from this supply is typically 5omA.

SIDE A, BACK side			SIDE B, Component side		
Pin nr.	Signal name	Description	Pin nr.	Signal name	Description
A	Vcc	+5V ± 0V	1	GND	ground
B	$\overline{RXD0}$	received data 0	2	GND	"
C	TXC0	transmitter clock 0	3	GND	"
D	DSR0	data set ready 0	4	GND	"
E	CTS1	clear to send 1	5	GND	"
F	CTS0	clear to send 0	6	GND	"
H	RXC0	receiver clock 0	7	GND	"
J	$\overline{RXD1}$	received data 1	8	GND	"
K	RXC1	receiver clock 1	9	GND	"
L	$\overline{RXD2}$	received data 2	10	GND	"
M	TXC1	transmitter clock 1	11	GND	"
N	DSR1	data set ready 1	12	GND	"
P	CTS2	clear to send 2	13	GND	"
R	TXC2	transmitter clock 2	14	GND	"
S	DSR2	data set ready 2	15	GND	"
T	RXC2	receiver clock 2	16	GND	"
U	$\overline{RXD3}$	received data 3	17	GND	"
V	TXC3	transmitter clock 3	18	GND	"
W	CTS3	clear to send 3	19	GND	"
X	RXC3	receiver clock 3	20	GND	"
Y	DSR3	data set ready 3	21	GND	"
Z	$\overline{IB}$	counter input B	22	GND	"
a	$\overline{IA}$	counter input A	23	GND	"
b	$\overline{IC}$	counter input C	24	GND	"
c	$\overline{ID}$	counter input D	25	GND	"
d	"1"	logical "one"	26	GND	"
e	$\overline{DTR2}$	data terminal ready 2	27	CLOCK 6	clock output 6
f	$\overline{TXD0}$	transmitted data 0	28	RTS1	request to send 1
h	$\overline{RTS0}$	request to send 0	29	DTR1	data terminal ready 1
j	$\overline{TXD3}$	transmitted data 3	30	CLOCK 5	clock output 5
k	RTS3	request to send 3	31	CLOCK 3	clock output 3
l	DTR0	data terminal ready 0	32	$\overline{TXD2}$	transmitted data 2
m	$\overline{TXD1}$	transmitted data 1	33	RTS2	request to send 2
n	DTR3	data terminal ready 3	34	CLOCK 1	clock output 1
p	CLOCK 2	clock output 2	35	CLOCK 4	clock output 4
r	GND	ground	36	Vcc	+5V ± 0V

Table I: Top connections of ID-7012

Navn	Lb. nr.	Dato	Emne	Fag	Afd.	Side
10-7012-4 COMPONENT LAYOUT		23/8-77				7




A15
RESET
RESET
A23
WR
WR
A21
OUTP.
LS00
LS13C
S7
R7 10K
R2 1K
A10
ADR(7)
S6
R6 10K
A9
ADR(6)
S5
R5 10K
A8
ADR(5)
S4
R4 10K
A7
ADR(4)
S3
R3 10K
A6
ADR(3)
A5
ADR(2)
74LS42
CS3
CS2
CS1
CS0
A22
INTR
R1 1K
R0 10K
68pF
74LS123
monostabil
R8
MPS3646
A20

Emne: ID-7012 ... tion module
Logic schematic: Address ...

Dok. nr.: Appendix 1

Side 2 ud af sider

Navn: OL

Dato: 28-1-77

BKR 060682

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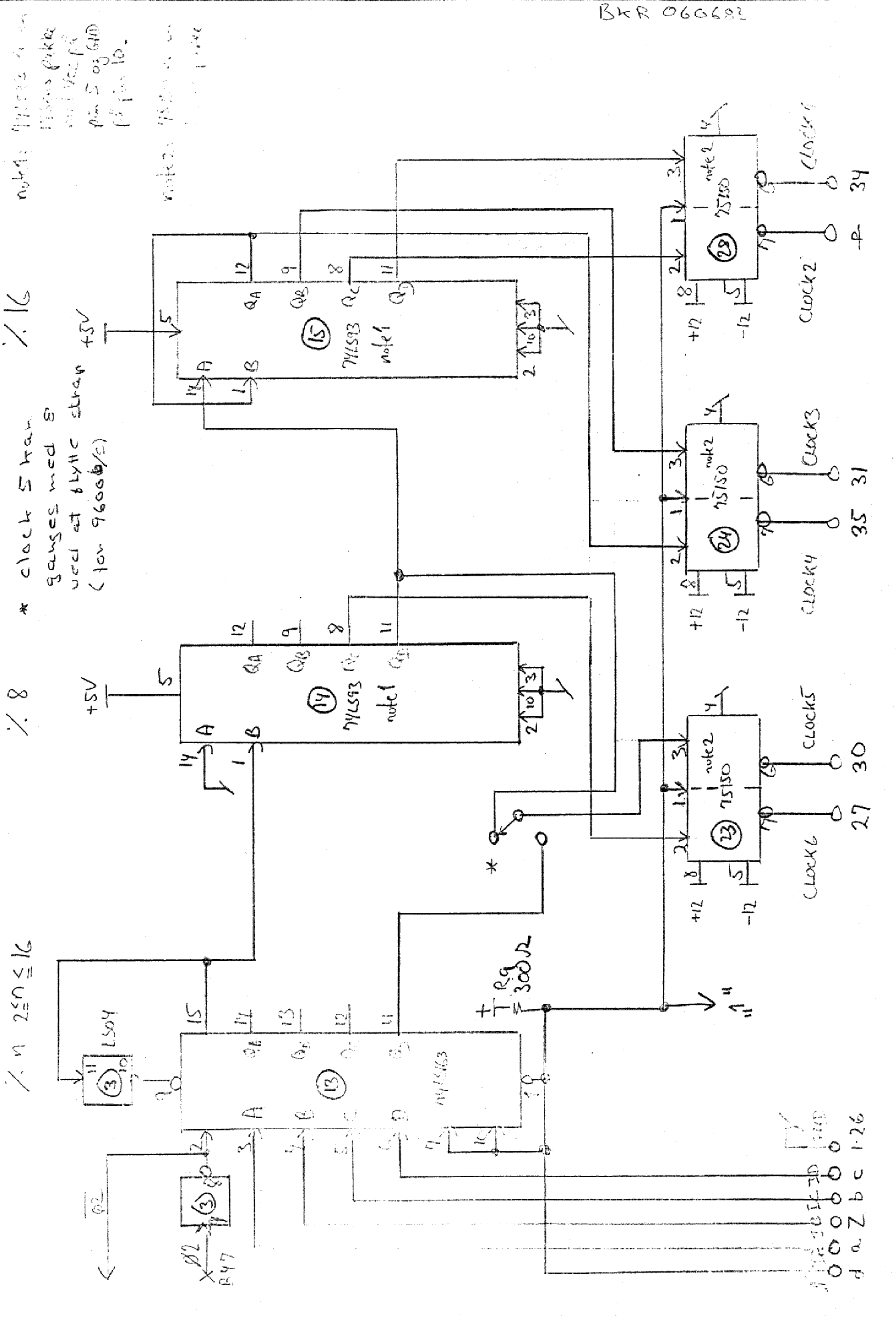

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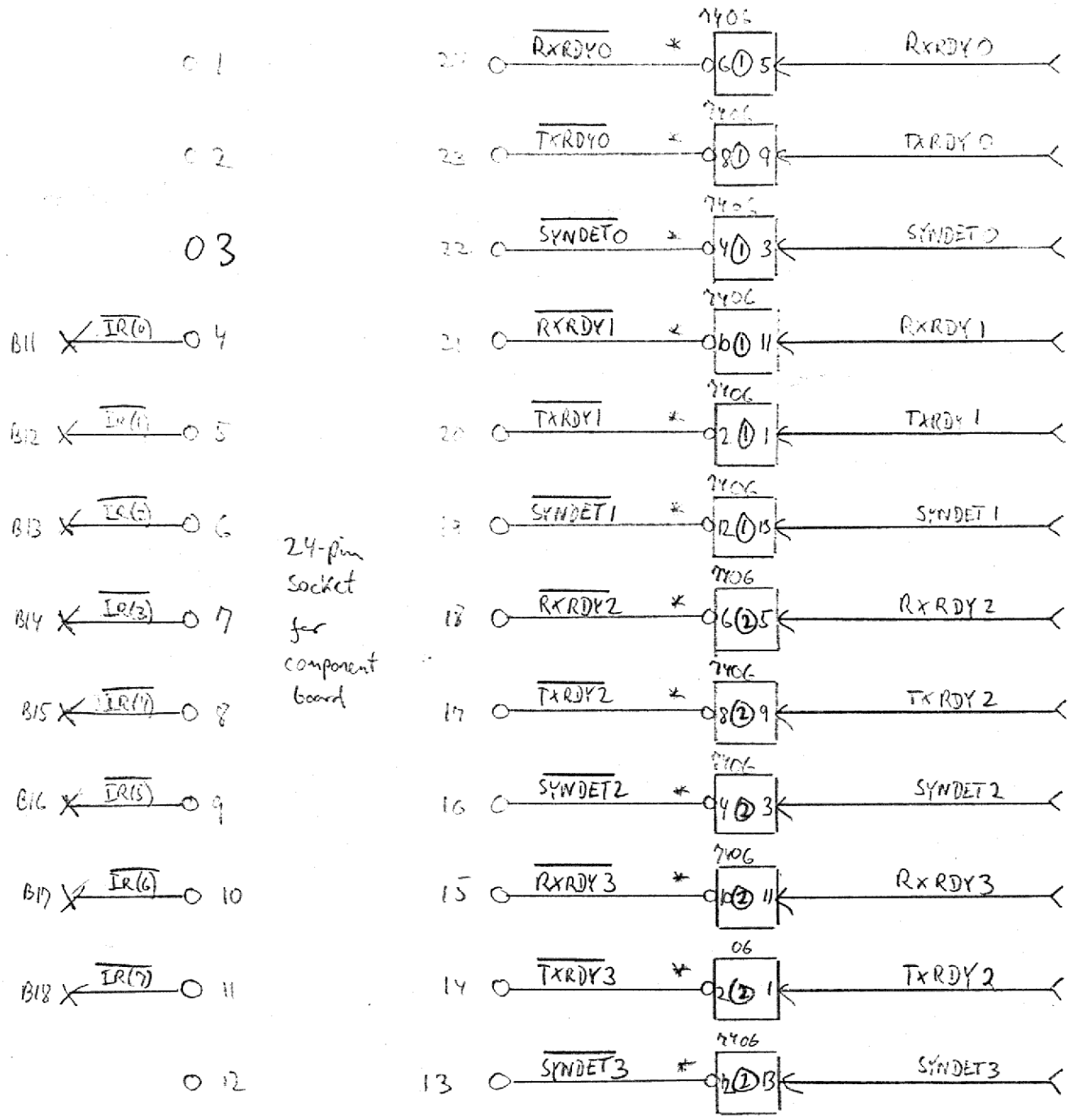
74LS
RXRDY0
TXRDY0
SYNDET0
RXRDY1
TXRDY1
SYNDET1
RXRDY2
TXRDY2
SYNDET2
RXRDY3
TXRDY3
SYNDET3
RXRDY 0
TXRDY 0
SYNDET 0
RXRDY 1
TXRDY 1
SYNDET 1
RXRDY 2
TXRDY 2
SYNDET 2
RXRDY 3
TXRDY 2
SYNDET 3
IR(0)
IR(1)
IR(2)
IR(3)
IR(4)
IR(5)
IR(6)
IR(7)
24-pin Socket for component board

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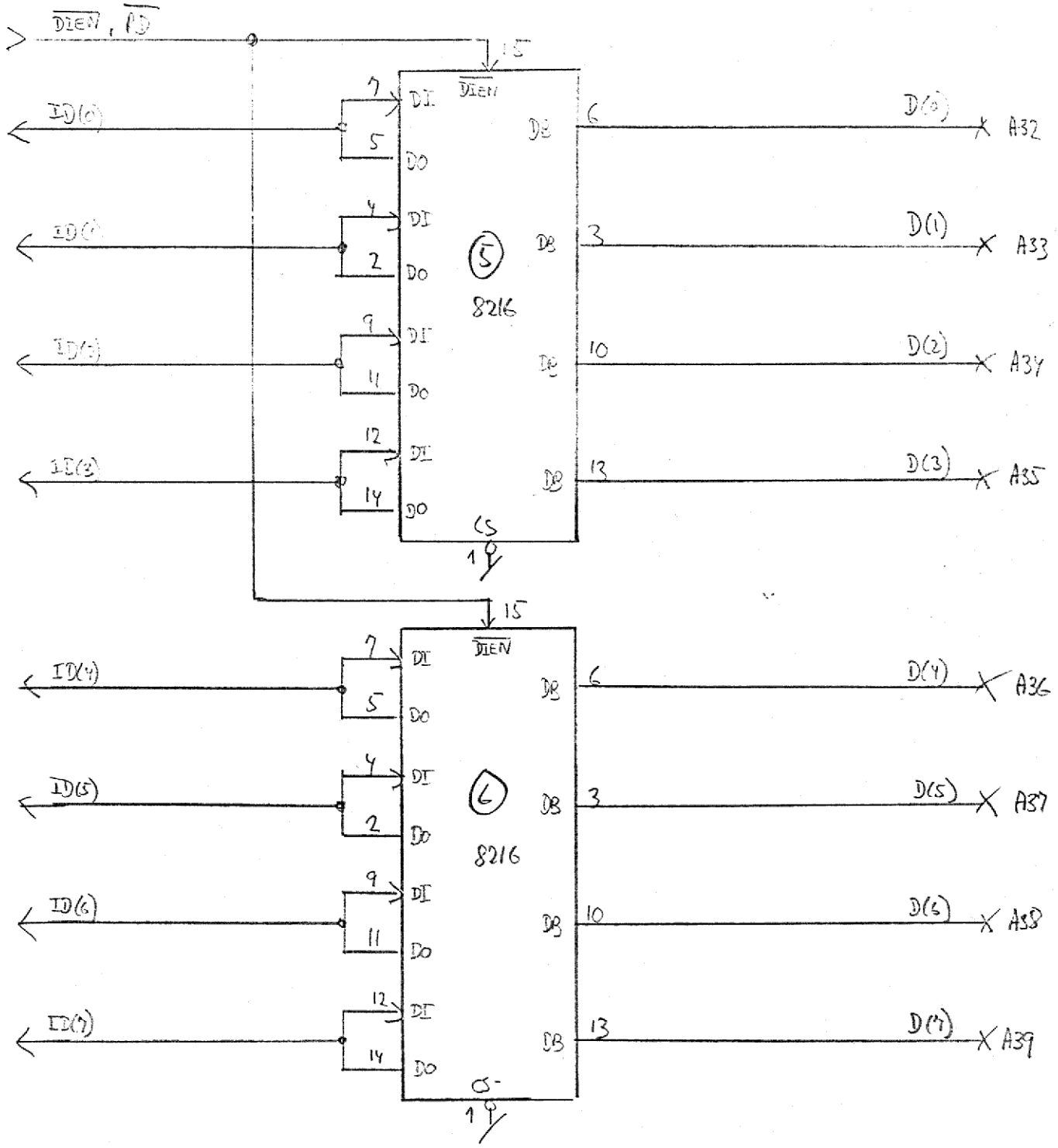
DIEN, RD
15
DIEN
DI
DO
DB
CS
8216
ID(0)
ID(1)
ID(2)
ID(3)
ID(4)
ID(5)
ID(6)
ID(7)
D(0)
D(1)
D(2)
D(3)
D(4)
D(5)
D(6)
D(7)
A32
A33
A34
A35
A36
A37
A38
A39

Emne: module. Logic Schematic: USART C	Dok. nr.: Appendix 1 Navn: OL Dato: 28-1-77	Side 5 ud af sider

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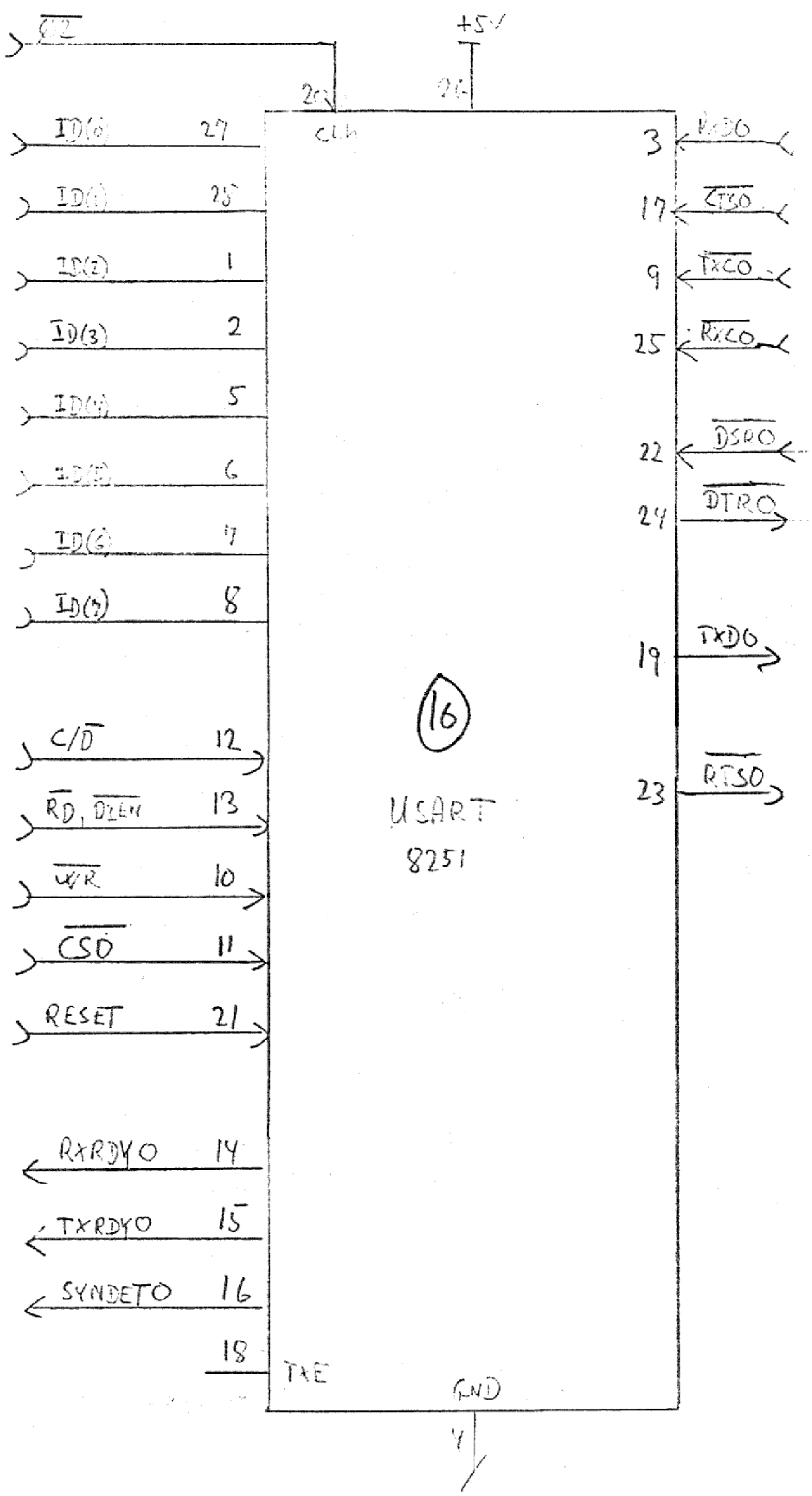

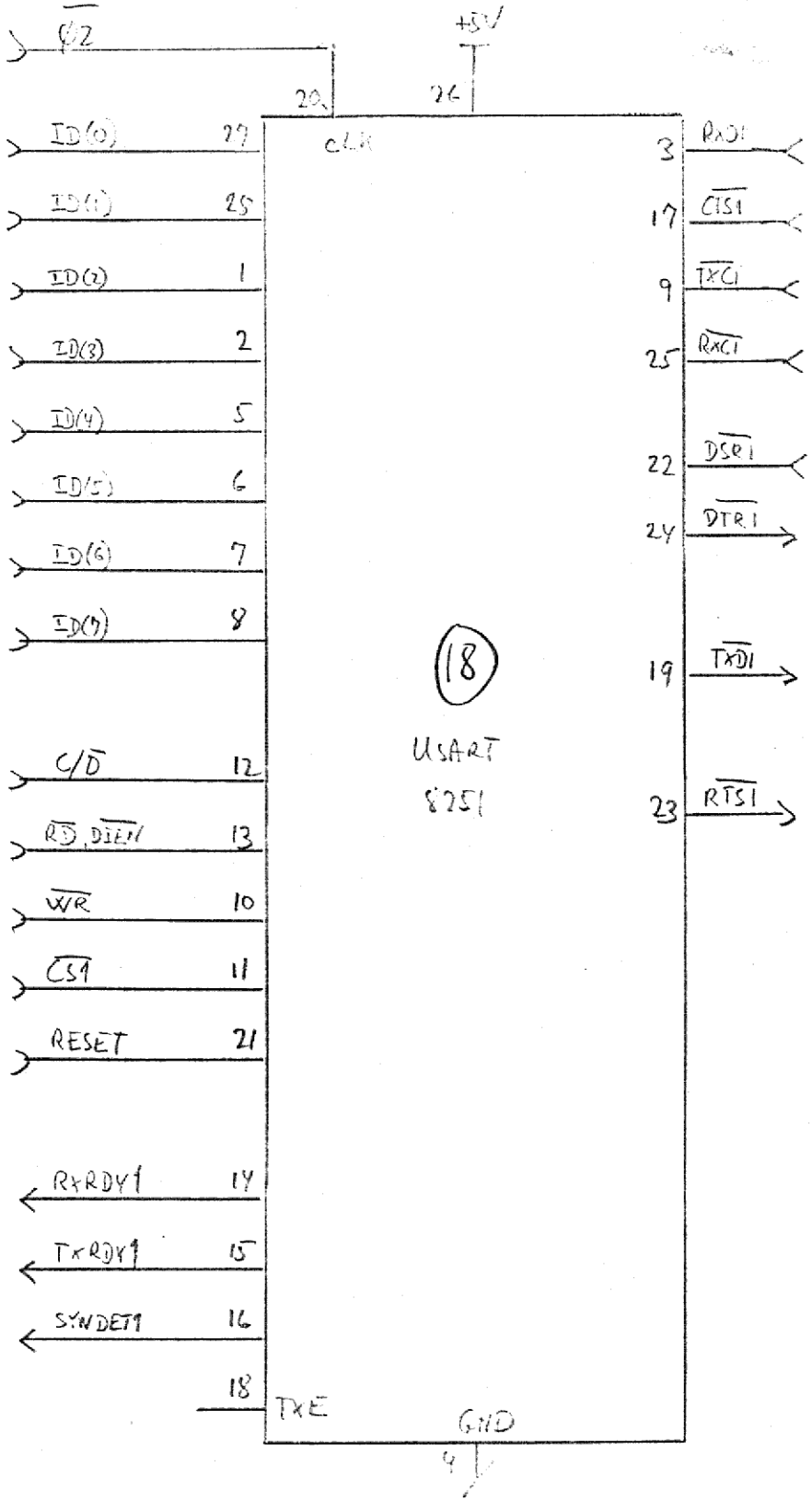
Ø2
+5V
20
26
CLK
ID(0) 27
ID(1) 25
ID(2) 1
ID(3) 2
ID(4) 5
ID(5) 6
ID(6) 7
ID(7) 8
C/D 12
RD, DIEN 13
WR 10
CS1 11
RESET 21
TxRDY1 14
TxRDY1 15
SYNDET1 16
18 TxE
18
USART
8251
GND
4
3 RxD1
17 CTS1
9 TxC1
25 RxC1
22 DSR1
24 DTR1
19 TxD1
23 RTS1

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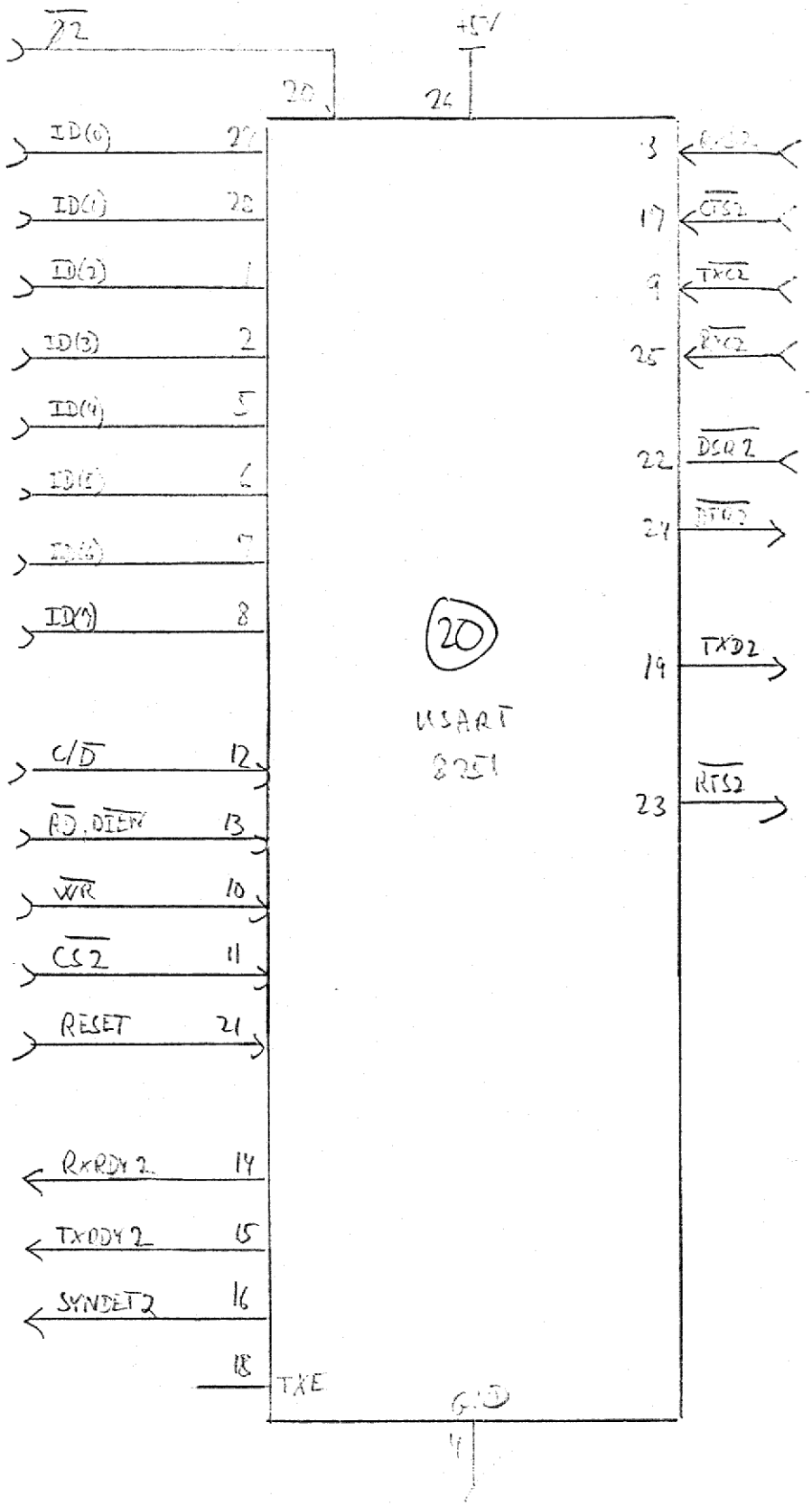
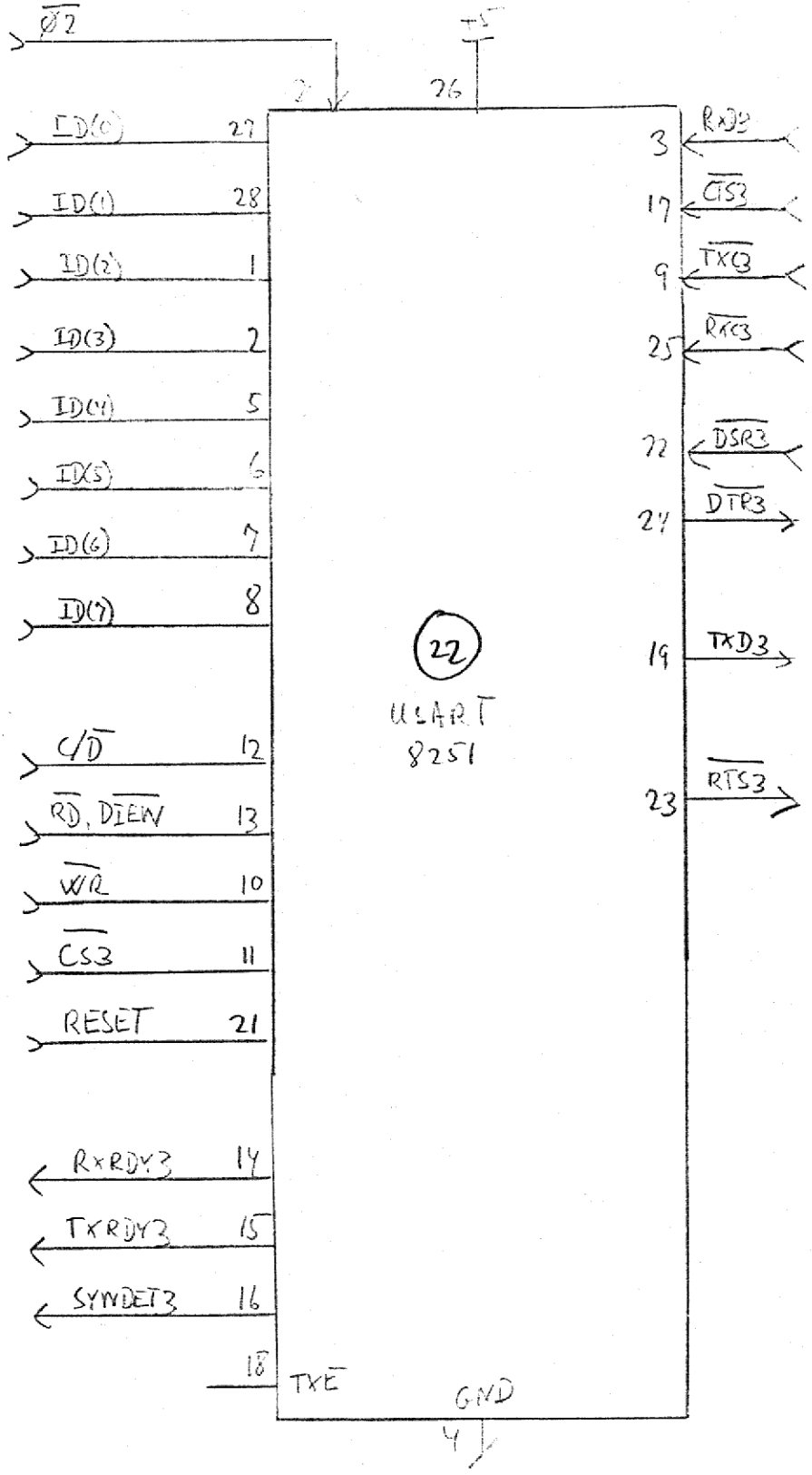

RD2
+5V
20
24
ID(0) 22
ID(1) 28
ID(2) 1
ID(3) 2
ID(4) 5
ID(5) 6
ID(6) 7
ID(7) 8
C/D 12
RD, DBEN 13
WR 10
CS2 11
RESET 21
RxRDY2 14
TxRDY2 15
SYNDET2 16
18 TXE
3
CTS2 17
TXC2 9
RXC2 25
DSR2 22
DTR2 24
TXD2 19
RTS2 23
20
USART
8251
GND
4

Un 04-653


Ø2
+5
2
26
ID(0) 27
ID(1) 28
ID(2) 1
ID(3) 2
ID(4) 5
ID(5) 6
ID(6) 7
ID(7) 8
C/D 12
RD, DIEN 13
WR 10
CS3 11
RESET 21
RXRDY3 14
TXRDY3 15
SYNDET3 16
18 TXE
RXD3 3
CTS3 17
TXC3 9
RXC3 25
DSR3 22
DTR3 24
TXD3 19
RTS3 23
22
USART
8251
GND
4

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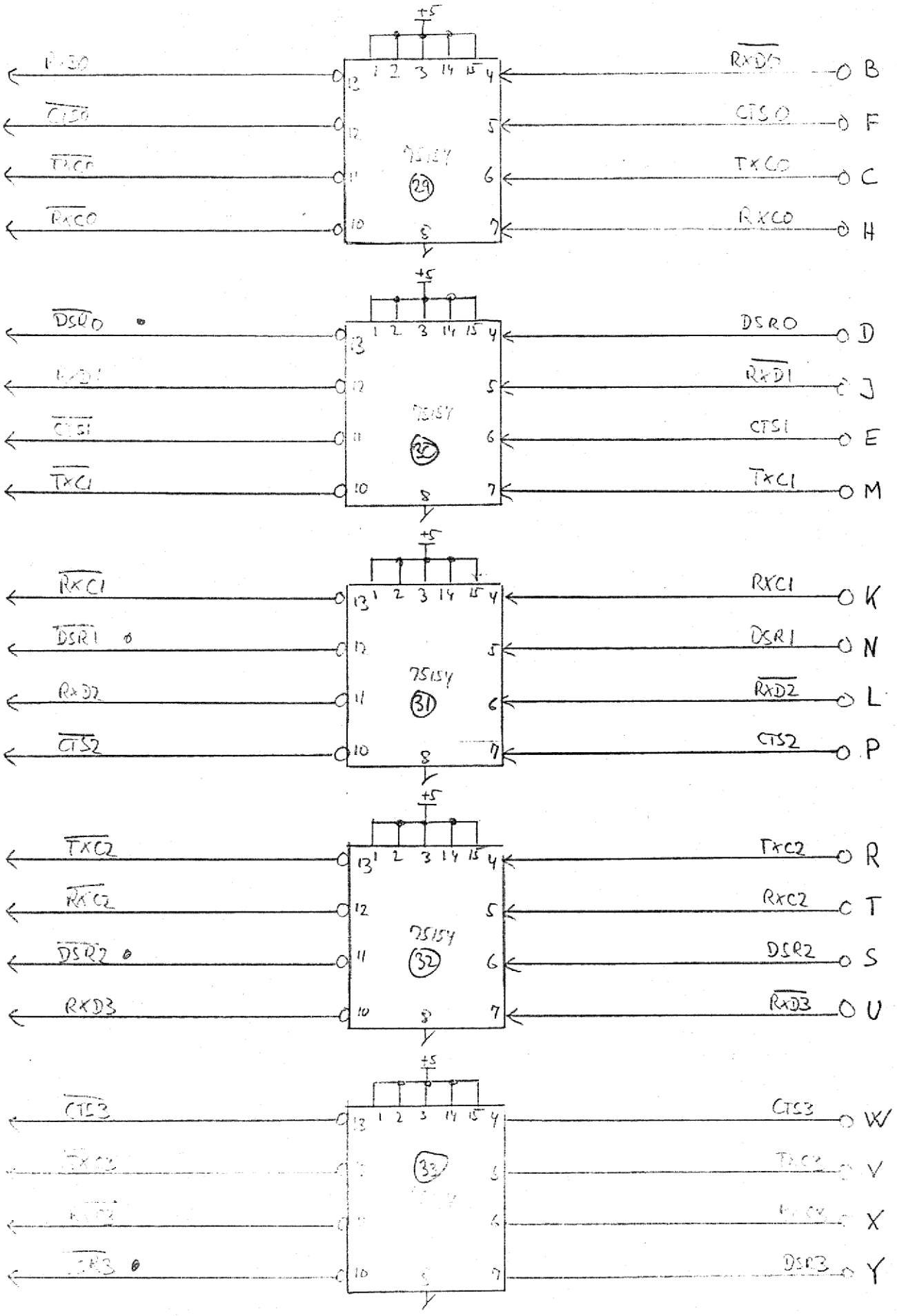
+5
75154
(29)
(30)
(31)
(32)
(33)
1 2 3 14 15
RXD0
CTS0
TXC0
RXC0
DSR0
RXD1
CTS1
TXC1
RXC1
DSR1
RXD2
CTS2
TXC2
RXC2
DSR2
RXD3
CTS3
DSR3
B
F
C
H
D
J
E
M
K
N
L
P
R
T
S
U
W
V
X
Y

Emne:	ID-7012 4-port Async/Sync communication module Logic Schematic. TTL → V24 interface.	Dok. nr.: Appendix 1	Side 10
		Navn: OC	ud af
		Dato: 28-1-77	sider

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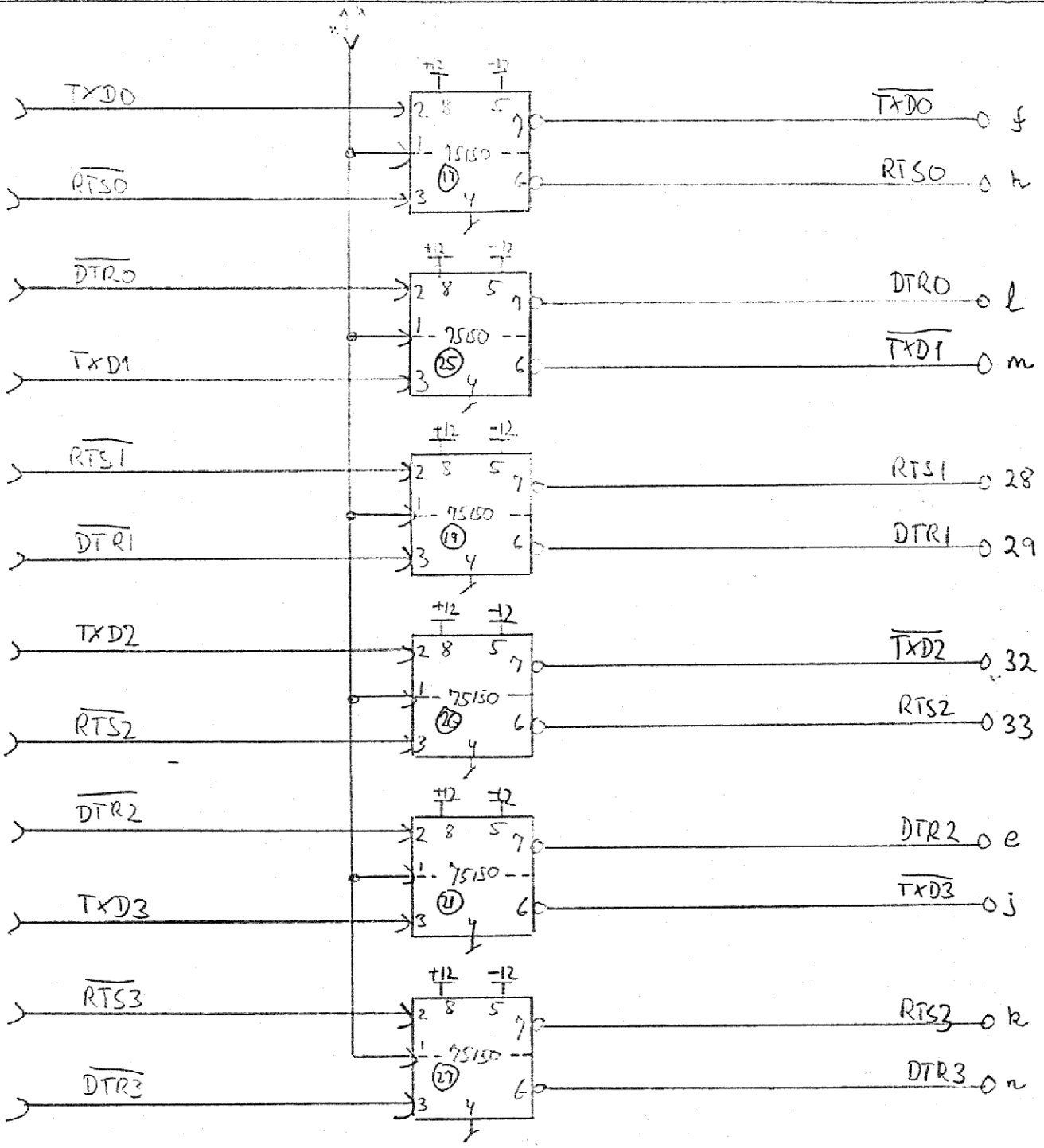
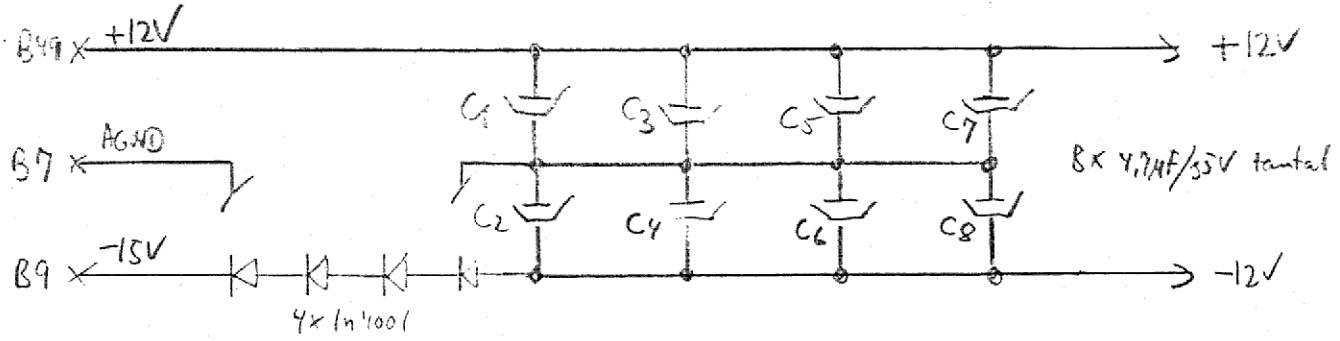




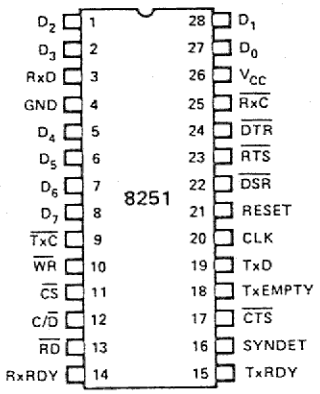
Silicon Gate MOS 8251

PROGRAMMABLE COMMUNICATION INTERFACE

- Synchronous and Asynchronous Operation
  - Synchronous:
    - 5-8 Bit Characters
    - Internal or External Character Synchronization
    - Automatic Sync Insertion
  - Asynchronous:
    - 5-8 Bit Characters
    - Clock Rate — 1, 16 or 64 Times Baud Rate
    - Break Character Generation
    - 1, 1½, or 2 Stop Bits
    - False Start Bit Detection
- Baud Rate — DC to 56k Baud (Sync Mode)
  DC to 9.6k Baud (Async Mode)
- Full Duplex, Double Buffered, Transmitter and Receiver
- Error Detection — Parity, Overrun, and Framing
- Fully Compatible with 8080 CPU
- 28-Pin DIP Package
- All Inputs and Outputs Are TTL Compatible
- Single 5 Volt Supply
- Single TTL Clock

The 8251 is a Universal Synchronous/Asynchronous Receiver/Transmitter (USART) Chip designed for data communications in microcomputer systems. The USART is used as a peripheral device and is programmed by the CPU to operate using virtually any serial data transmission technique presently in use (including IBM Bi-Sync). The USART accepts data characters from the CPU in parallel format and then converts them into a continuous serial data stream for transmission. Simultaneously it can receive serial data streams and convert them into parallel data characters for the CPU. The USART will signal the CPU whenever it can accept a new character for transmission or whenever it has received a character for the CPU. The CPU can read the complete status of the USART at any time. These include data transmission errors and control signals such as SYNDET, TxEMPT. The chip is constructed using N-channel silicon gate technology.

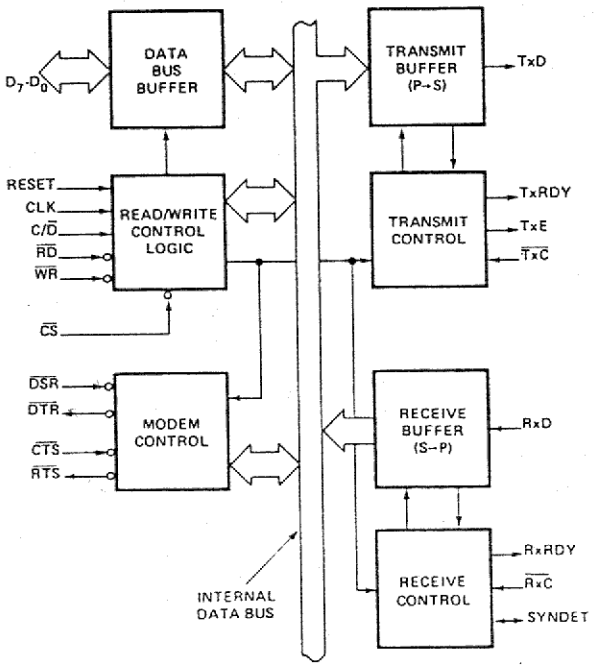
PIN CONFIGURATION



Pin Name	Pin Function
D_7-D_0	Data Bus (8 bits)
C/D	Control or Data is to be Written or Read
$\overline{RD}$	Read Data Command
$\overline{WR}$	Write Data or Control Command
$\overline{CS}$	Chip Enable
CLK	Clock Pulse (TTL)
RESET	Reset
$\overline{TxC}$	Transmitter Clock
TxD	Transmitter Data
$\overline{RxC}$	Receiver Clock
RxD	Receiver Data
RxRDY	Receiver Ready (has character for 8080)
TxRDY	Transmitter Ready (ready for char. from 8080)

Pin Name	Pin Function
$\overline{DSR}$	Data Set Ready
$\overline{DTR}$	Data Terminal Ready
SYNDET	Sync Detect
$\overline{RTS}$	Request to Send Data
$\overline{CTS}$	Clear to Send Data
TxE	Transmitter Empty
V_{CC}	+5 Volt Supply
GND	Ground

BLOCK DIAGRAM



8251 BASIC FUNCTIONAL DESCRIPTION

General

The 8251 is a Universal Synchronous/Asynchronous Receiver/Transmitter designed specifically for the 8080 Microcomputer System. Like other I/O devices in the 8080 Microcomputer System its functional configuration is programmed by the systems software for maximum flexibility. The 8251 can support virtually any serial data technique currently in use (including IBM "bi-sync").

In a communication environment an interface device must convert parallel format system data into serial format for transmission and convert incoming serial format data into parallel system data for reception. The interface device must also delete or insert bits or characters that are functionally unique to the communication technique. In essence, the interface should appear "transparent" to the CPU, a simple input or output of byte-oriented system data.

Data Bus Buffer

This 3-state, bi-directional, 8-bit buffer is used to interface the 8251 to the 8080 system Data Bus. Data is transmitted or received by the buffer upon execution of INput or OUTput instructions of the 8080 CPU. Control words, Command words and Status information are also transferred through the Data Bus Buffer.

Read/Write Control Logic

This functional block accepts inputs from the 8080 Control bus and generates control signals for overall device operation. It contains the Control Word Register and Command Word Register that store the various control formats for device functional definition.

RESET (Reset)

A "high" on this input forces the 8251 into an "Idle" mode. The device will remain at "Idle" until a new set of control words is written into the 8251 to program its functional definition.

CLK (Clock)

The CLK input is used to generate internal device timing and is normally connected to the Phase 2 (TTL) output of the 8224 Clock Generator. No external inputs or outputs are referenced to CLK but the frequency of CLK must be greater than 30 times the Receiver or Transmitter clock inputs for synchronous mode (4.5 times for asynchronous mode).

$\overline{WR}$ (Write)

A "low" on this input informs the 8251 that the CPU is outputting data or control words, in essence, the CPU is writing out to the 8251.

$\overline{RD}$ (Read)

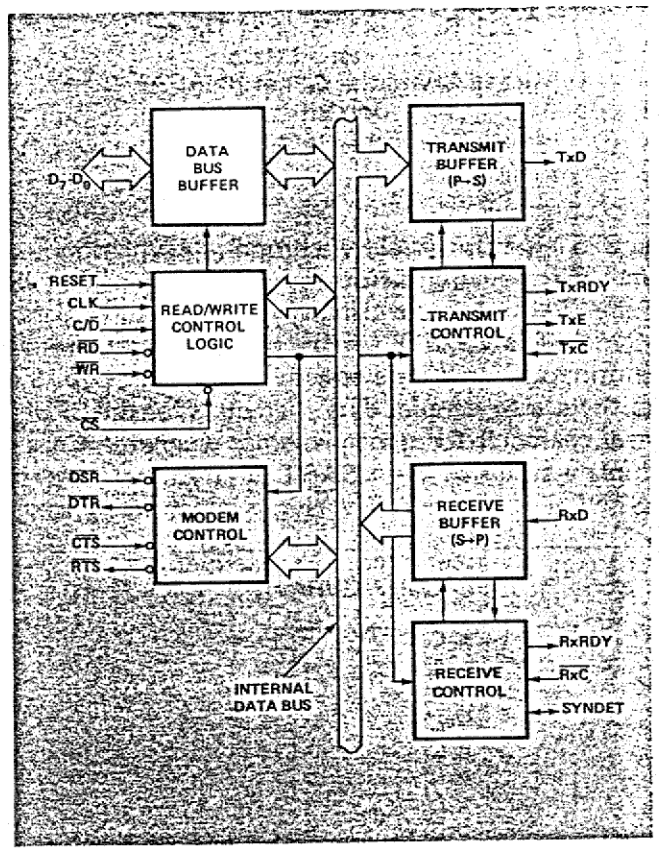
A "low" on this input informs the 8251 that the CPU is inputting data or status information, in essence, the CPU is reading from the 8251.

C/$\overline{D}$ (Control/Data)

This input, in conjunction with the $\overline{WR}$ and $\overline{RD}$ inputs informs the 8251 that the word on the Data Bus is either a data character, control word or status information.
1 = CONTROL 0 = DATA

$\overline{CS}$ (Chip Select)

A "low" on this input enables the 8251. No reading or writing will occur unless the device is selected.



C/$\overline{D}$	$\overline{RD}$	$\overline{WR}$	$\overline{CS}$	
0	0	1	0	8251 ⇒ DATA BUS
0	1	0	0	DATA BUS ⇒ 8251
1	0	1	0	STATUS ⇒ DATA BUS
1	1	0	0	DATA BUS ⇒ CONTROL
X	X	X	1	DATA BUS ⇒ 3-STATE

Modem Control

The 8251 has a set of control inputs and outputs that can be used to simplify the interface to almost any Modem. The modem control signals are general purpose in nature and can be used for functions other than Modem control, if necessary.

$\overline{DSR}$ (Data Set Ready)

The $\overline{DSR}$ input signal is general purpose in nature. Its condition can be tested by the CPU using a Status Read operation. The $\overline{DSR}$ input is normally used to test Modem conditions such as Data Set Ready.

$\overline{DTR}$ (Data Terminal Ready)

The $\overline{DTR}$ output signal is general purpose in nature. It can be set "low" by programming the appropriate bit in the Command Instruction word. The $\overline{DTR}$ output signal is normally used for Modem control such as Data Terminal Ready or Rate Select.

$\overline{RTS}$ (Request to Send)

The $\overline{RTS}$ output signal is general purpose in nature. It can be set "low" by programming the appropriate bit in the Command Instruction word. The $\overline{RTS}$ output signal is normally used for Modem control such as Request to Send.

$\overline{CTS}$ (Clear to Send)

A "low" on this input enables the 8251 to transmit data (serial) if the Tx EN bit in the Command byte is set to a "one."

Transmitter Buffer

The Transmitter Buffer accepts parallel data from the Data Bus Buffer, converts it to a serial bit stream, inserts the appropriate characters or bits (based on the communication technique) and outputs a composite serial stream of data on the TxD output pin.

Transmitter Control

The Transmitter Control manages all activities associated with the transmission of serial data. It accepts and issues signals both externally and internally to accomplish this function.

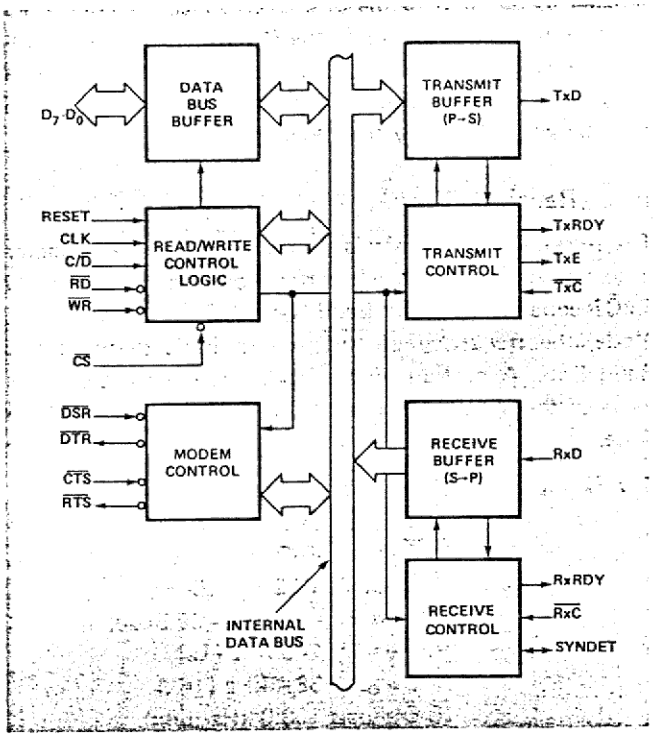
TxRDY (Transmitter Ready)

This output signals the CPU that the transmitter is ready to accept a data character. It can be used as an interrupt to the system or for the Polled operation the CPU can check TxRDY using a status read operation. TxRDY is automatically reset when a character is loaded from the CPU.

TxE (Transmitter Empty)

When the 8251 has no characters to transmit, the TxE output will go "high". It resets automatically upon receiving a character from the CPU. TxE can be used to indicate the end of a transmission mode, so that the CPU "knows" when to "turn the line around" in the half-duplexed operational mode.

In SYNChronous mode, a "high" on this output indicates that a character has not been loaded and the SYNC character or characters are about to be transmitted automatically as "fillers".



$\overline{TxC}$ (Transmitter Clock)

The Transmitter Clock controls the rate at which the character is to be transmitted. In the Synchronous transmission mode, the frequency of $\overline{TxC}$ is equal to the actual Baud Rate (1X). In Asynchronous transmission mode, the frequency of $\overline{TxC}$ is a multiple of the actual Baud Rate. A portion of the mode instruction selects the value of the multiplier; it can be 1x, 16x or 64x the Baud Rate.

For Example:

If Baud Rate equals 110 Baud,
$\overline{TxC}$ equals 110 Hz (1x)
$\overline{TxC}$ equals 1.76 kHz (16x)
$\overline{TxC}$ equals 7.04 kHz (64x).
If Baud Rate equals 9600 Baud,
$\overline{TxC}$ equals 614.4 kHz (64x).

The falling edge of $\overline{TxC}$ shifts the serial data out of the 8251.

Receiver Buffer

The Receiver accepts serial data, converts this serial input to parallel format, checks for bits or characters that are unique to the communication technique and sends an "assembled" character to the CPU. Serial data is input to the RxD pin.

Receiver Control

This functional block manages all receiver-related activities.

RxRDY (Receiver Ready)

This output indicates that the 8251 contains a character that is ready to be input to the CPU. RxRDY can be connected to the interrupt structure of the CPU or for Polled operation the CPU can check the condition of RxRDY using a status read operation. RxRDY is automatically reset when the character is read by the CPU.

$\overline{RxC}$ (Receiver Clock)

The Receiver Clock controls the rate at which the character is to be received. In Synchronous Mode, the frequency of $\overline{RxC}$ is equal to the actual Baud Rate (1x). In Asynchronous Mode, the frequency of $\overline{RxC}$ is a multiple of the actual Baud Rate. A portion of the mode instruction selects the value of the multiplier; it can be 1x, 16x or 64x the Baud Rate.

For Example: If Baud Rate equals 300 Baud,
$\overline{RxC}$ equals 300 Hz (1x)
$\overline{RxC}$ equals 4800 Hz (16x)
$\overline{RxC}$ equals 19.2 kHz (64x).
If Baud Rate equals 2400 Baud,
$\overline{RxC}$ equals 2400 Hz (1x)
$\overline{RxC}$ equals 38.4 kHz (16x)
$\overline{RxC}$ equals 153.6 kHz (64x).

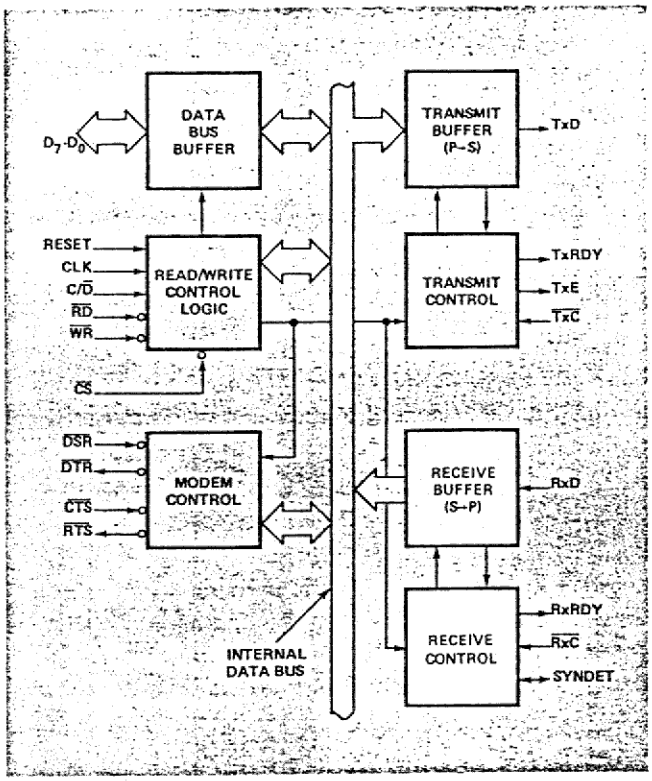
Data is sampled into the 8251 on the rising edge of $\overline{RxC}$.

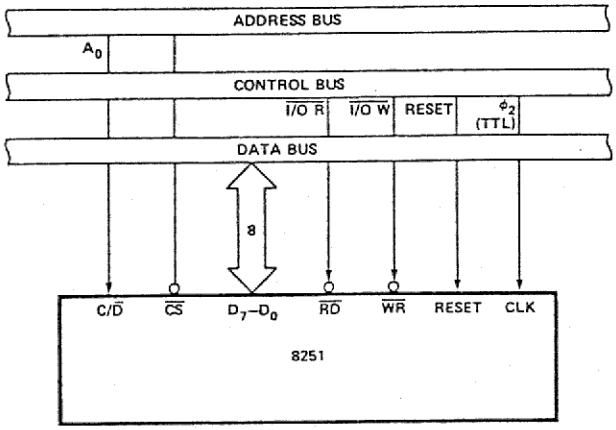
NOTE: In most communications systems, the 8251 will be handling both the transmission and reception operations of a single link. Consequently, the Receive and Transmit Baud Rates will be the same. Both $\overline{TxC}$ and $\overline{RxC}$ will require identical frequencies for this operation and can be tied together and connected to a single frequency source (Baud Rate Generator) to simplify the interface.

SYNDET (SYNC Detect)

This pin is used in SYNChronous Mode only. It is used as either input or output, programmable through the Control Word. It is reset to "low" upon RESET. When used as an output (internal Sync mode), the SYNDET pin will go "high" to indicate that the 8251 has located the SYNC character in the Receive mode. If the 8251 is programmed to use double Sync characters (bi-sync), then SYNDET will go "high" in the middle of the last bit of the second Sync character. SYNDET is automatically reset upon a Status Read operation.

When used as an input, (external SYNC detect mode), a positive going signal will cause the 8251 to start assembling data characters on the falling edge of the next $\overline{RxC}$. Once in SYNC, the "high" input signal can be removed. The duration of the high signal should be at least equal to the period of $\overline{RxC}$.





8251 Interface to 8080 Standard System Bus

DETAILED OPERATION DESCRIPTION

General

The complete functional definition of the 8251 is programmed by the systems software. A set of control words must be sent out by the CPU to initialize the 8251 to support the desired communications format. These control words will program the: BAUD RATE, CHARACTER LENGTH, NUMBER OF STOP BITS, SYNCHRONOUS or ASYNCHRONOUS OPERATION, EVEN/ODD PARITY etc. In the Synchronous Mode, options are also provided to select either internal or external character synchronization.

Once programmed, the 8251 is ready to perform its communication functions. The TxRDY output is raised "high" to signal the CPU that the 8251 is ready to receive a character. This output (TxRDY) is reset automatically when the CPU writes a character into the 8251. On the other hand, the 8251 receives serial data from the MODEM or I/O device, upon receiving an entire character the RxRDY output is raised "high" to signal the CPU that the 8251 has a complete character ready for the CPU to fetch. RxRDY is reset automatically upon the CPU read operation.

The 8251 cannot begin transmission until the TxEN(Transmitter Enable) bit is set in the Command Instruction and it has received a Clear To Send (CTS) input. The TxD output will be held in the marking state upon Reset.

Programming the 8251

Prior to starting data transmission or reception, the 8251 must be loaded with a set of control words generated by the CPU. These control signals define the complete functional definition of the 8251 and must immediately follow a Reset operation (internal or external).

The control words are split into two formats:

1. Mode Instruction
2. Command Instruction

Mode Instruction

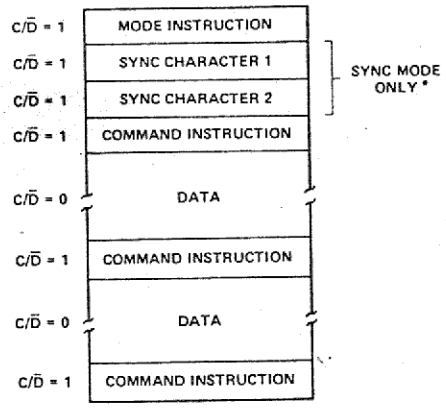
This format defines the general operational characteristics of the 8251. It must follow a Reset operation (internal or external). Once the Mode instruction has been written into the 8251 by the CPU, SYNC characters or Command instructions may be inserted.

Command Instruction

This format defines a status word that is used to control the actual operation of the 8251.

Both the Mode and Command instructions must conform to a specified sequence for proper device operation. The Mode Instruction must be inserted immediately following a Reset operation, prior to using the 8251 for data communication.

All control words written into the 8251 after the Mode Instruction will load the Command Instruction. Command Instructions can be written into the 8251 at any time in the data block during the operation of the 8251. To return to the Mode Instruction format a bit in the Command Instruction word can be set to initiate an internal Reset operation which automatically places the 8251 back into the Mode Instruction format. Command Instructions must follow the Mode Instructions or Sync characters.



*The second SYNC character is skipped if MODE instruction has programmed the 8251 to single character Internal SYNC Mode. Both SYNC characters are skipped if MODE instruction has programmed the 8251 to ASYNC mode.

Typical Data Block

Mode Instruction Definition

The 8251 can be used for either Asynchronous or Synchronous data communication. To understand how the Mode Instruction defines the functional operation of the 8251 the designer can best view the device as two separate components sharing the same package. One Asynchronous the other Synchronous. The format definition can be changed "on the fly" but for explanation purposes the two formats will be isolated.

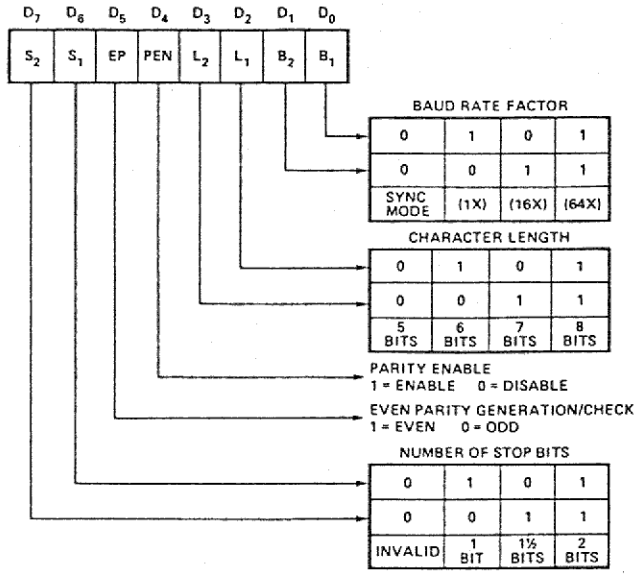
Asynchronous Mode (Transmission)

Whenever a data character is sent by the CPU the 8251 automatically adds a Start bit (low level) and the programmed number of Stop bits to each character. Also, an even or odd Parity bit is inserted prior to the Stop bit(s), as defined by the Mode Instruction. The character is then transmitted as a serial data stream on the TxD output. The serial data is shifted out on the falling edge of $\overline{TxC}$ at a rate equal to 1, 1/16, or 1/64 that of the $\overline{TxC}$, as defined by the Mode Instruction. BREAK characters can be continuously sent to the TxD if commanded to do so.

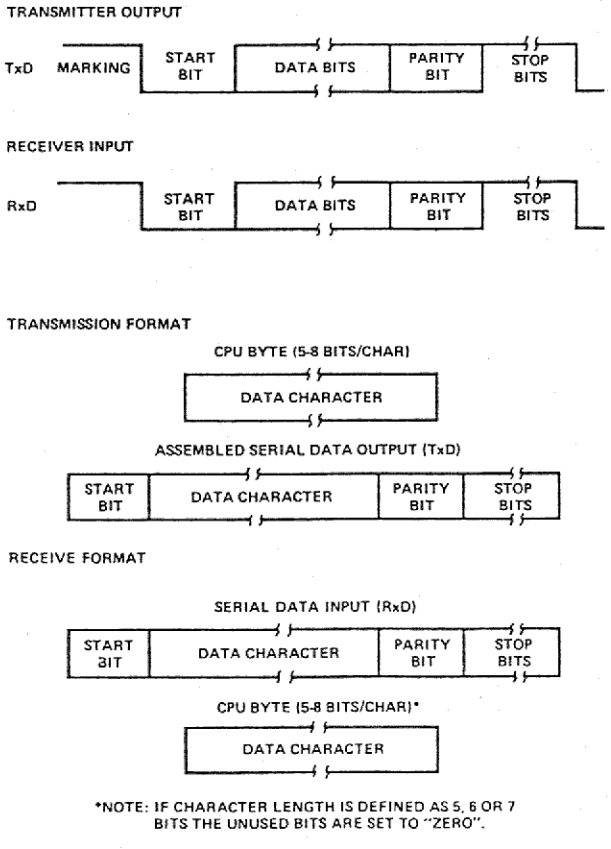
When no data characters have loaded into the 8251 the TxD output remains "high" (marking) unless a Break (continuously low) has been programmed.

Asynchronous Mode (Receive)

The RxD line is normally high. A falling edge on this line triggers the beginning of a START bit. The validity of this START bit is checked by again strobing this bit at its nominal center. If a low is detected again, it is a valid START bit, and the bit counter will start counting. The bit counter locates the center of the data bits, the parity bit (if it exists) and the stop bits. If parity error occurs, the parity error flag is set. Data and parity bits are sampled on the RxD pin with the rising edge of $\overline{RxC}$. If a low level is detected as the STOP bit, the Framing Error flag will be set. The STOP bit signals the end of a character. This character is then loaded into the parallel I/O buffer of the 8251. The RxRDY pin is raised to signal the CPU that a character is ready to be fetched. If a previous character has not been fetched by the CPU, the present character replaces it in the I/O buffer, and the OVERRUN flag is raised (thus the previous character is lost). All of the error flags can be reset by a command instruction. The occurrence of any of these errors will not stop the operation of the 8251.



Mode Instruction Format, Asynchronous Mode



Asynchronous Mode

Synchronous Mode (Transmission)

The TxD output is continuously high until the CPU sends its first character to the 8251 which usually is a SYNC character. When the $\overline{CTS}$ line goes low, the first character is serially transmitted out. All characters are shifted out on the falling edge of $\overline{TxC}$. Data is shifted out at the same rate as the $\overline{TxC}$.

Once transmission has started, the data stream at TxD output must continue at the $\overline{TxC}$ rate. If the CPU does not provide the 8251 with a character before the 8251 becomes empty, the SYNC characters (or character if in single SYNC word mode) will be automatically inserted in the TxD data stream. In this case, the TxEMPTY pin is raised high to signal that the 8251 is empty and SYNC characters are being sent out. The TxEMPTY pin is internally reset by the next character being written into the 8251.

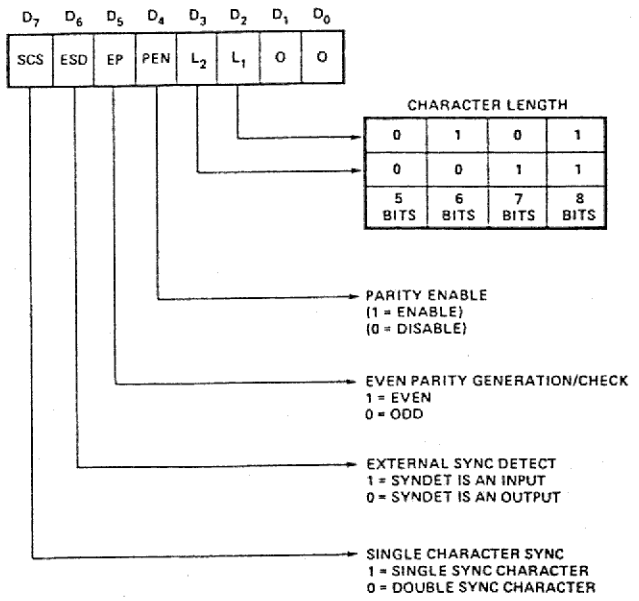
Synchronous Mode (Receive)

In this mode, character synchronization can be internally or externally achieved. If the internal SYNC mode has been programmed, the receiver starts in a HUNT mode. Data on the RxD pin is then sampled in on the rising edge of $\overline{RxC}$. The content of the Rx buffer is continuously compared with the first SYNC character until a match occurs. If the 8251 has been programmed for two SYNC characters, the subsequent received character is also compared; when both SYNC characters have been detected, the USART ends the HUNT mode and is in character synchronization. The SYNDET pin is then set high, and is reset automatically by a STATUS READ.

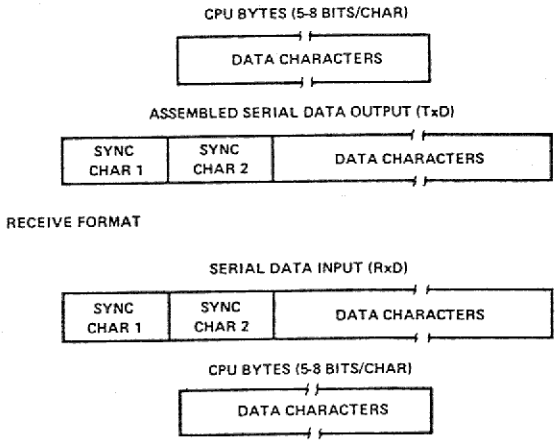
In the external SYNC mode, synchronization is achieved by applying a high level on the SYNDET pin. The high level can be removed after one $\overline{RxC}$ cycle.

Parity error and overrun error are both checked in the same way as in the Asynchronous Rx mode.

The CPU can command the receiver to enter the HUNT mode if synchronization is lost.



Mode Instruction Format, Synchronous Mode

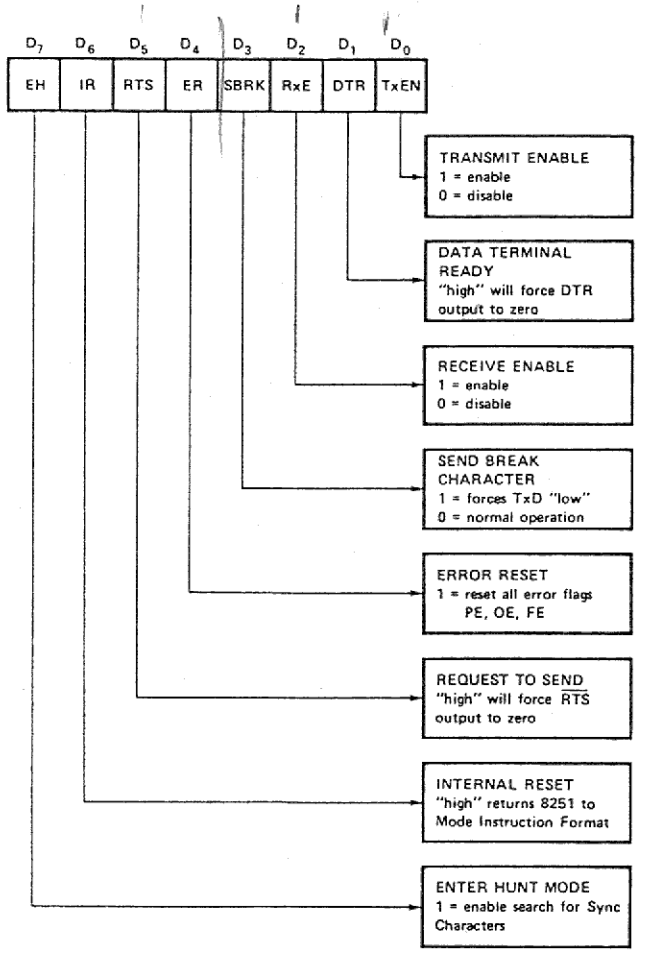


Synchronous Mode, Transmission Format

COMMAND INSTRUCTION DEFINITION

Once the functional definition of the 8251 has been programmed by the Mode Instruction and the Sync Characters are loaded (if in Sync Mode) then the device is ready to be used for data communication. The Command Instruction controls the actual operation of the selected format. Functions such as: Enable Transmit/Receive, Error Reset and Modem Controls are provided by the Command Instruction.

Once the Mode Instruction has been written into the 8251 and Sync characters inserted, if necessary, then all further "control writes" ($C/\overline{D}$ = 1) will load the Command Instruction. A Reset operation (internal or external) will return the 8251 to the Mode Instruction Format.



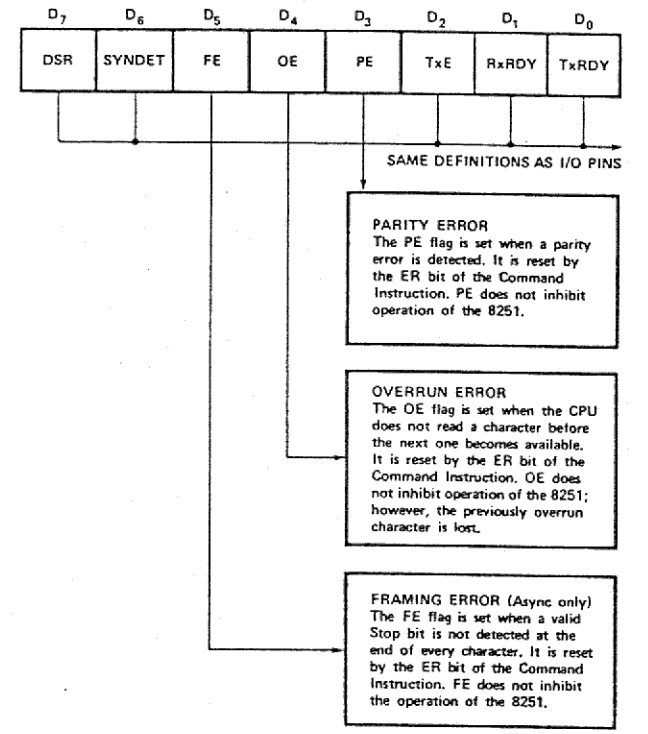
Command Instruction Format

STATUS READ DEFINITION

In data communication systems it is often necessary to examine the "status" of the active device to ascertain if errors have occurred or other conditions that require the processor's attention. The 8251 has facilities that allow the programmer to "read" the status of the device at any time during the functional operation.

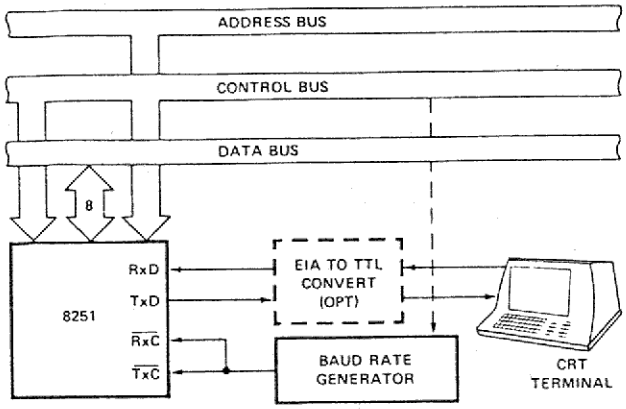
A normal "read" command is issued by the CPU with the C/D input at one to accomplish this function.

Some of the bits in the Status Read Format have identical meanings to external output pins so that the 8251 can be used in a completely Polled environment or in an interrupt driven environment.

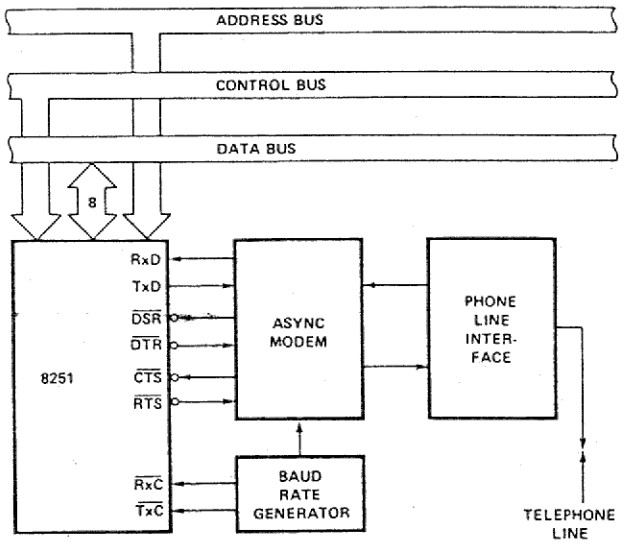


Status Read Format

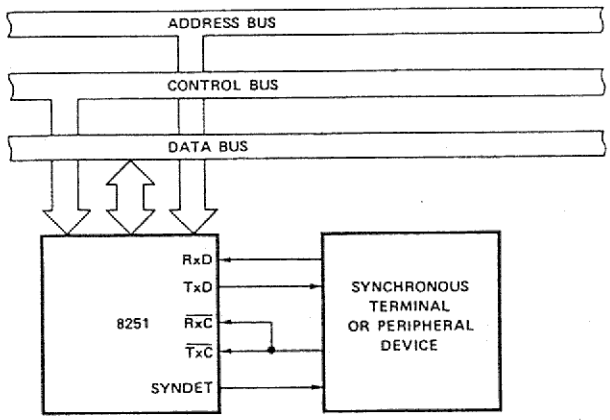
APPLICATIONS OF THE 8251



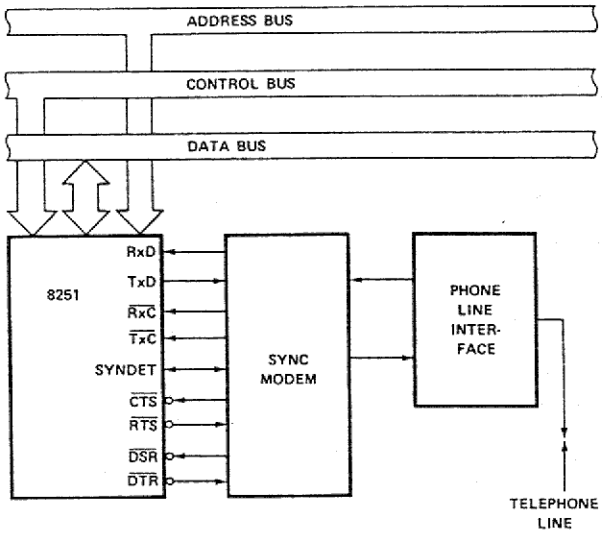
Asynchronous Serial Interface to CRT Terminal, DC-9600 Baud



Asynchronous Interface to Telephone Lines



Synchronous Interface to Terminal or Peripheral Device



Synchronous Interface to Telephone Lines

D.C. Characteristics:

T_A = 0°C to 70°C; V_{CC} = 5.0V ± 5%; V_{SS} = 0V

Symbol	Parameter	Min.	Typ.	Max.	Unit	Test Conditions
V_{IL}	Input Low Voltage	V_{SS}-.5		0.8	V	
V_{IH}	Input High Voltage	2.0		V_{CC}	V	
V_{OL}	Output Low Voltage			0.45	V	I_{OL} = 1.6mA
V_{OH}	Output High Voltage	2.2			V	I_{OH} = -100μA (DB_{0-7}) I_{OH} = -100μA (Others)
I_{DL}	Data Bus Leakage			50	μA	V_{OUT} = 4.5V
I_{LI}	Input Load Current			10	μA	@ 5.5V
I_{CC}	Power Supply Current		45	80		

Capacitance

T_A = 25°C; V_{CC} = V_{SS} = 0V

Symbol	Parameter	Min.	Typ.	Max.	Unit	Test Conditions
C_{IN}	Input Capacitance			10	pF	fc = 1MHz
$C_{I/O}$	I/O Capacitance			20	pF	Unmeasured pins returned to V_{SS}.

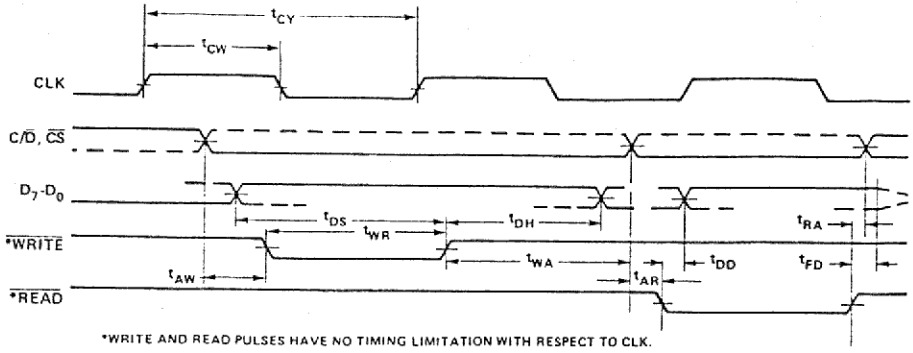
A.C. Characteristics:

T_A = 0°C to 70°C; V_{CC} = 5.0V ±5%; V_{SS} = 0V

Symbol	Parameter	Min.	Typ.	Max.	Unit	Test Conditions
t_{CY}	Clock Period	.420		1.35	μs	
$t_{\phi W}$	Clock Pulse Width	220		300	ns	
t_R,t_F	Clock Rise and Fall Time	0		50	ns	
t_{WR}	$\overline{\text{WRITE}}$ Pulse Width	430			ns	
t_{DS}	Data Set-Up Time for $\overline{\text{WRITE}}$	0			ns	
t_{DH}	Data Hold Time for $\overline{\text{WRITE}}$	65			ns	
t_{AW}	Address Stable before $\overline{\text{WRITE}}$	20			ns	
t_{WA}	Address Hold Time for $\overline{\text{WRITE}}$	35			ns	
t_{RD}	READ Pulse Width	430			ns	
t_{DD}	Data Delay from $\overline{\text{READ}}$	350			ns	C_L=100pF
t_{DF}	$\overline{\text{READ}}$ to Data Floating	150			ns	C_L=100pF
t_{AR1}	Address Stable before $\overline{\text{READ}}$, CE (C/D)	50			ns	
t_{RA1}	Address Hold Time for $\overline{\text{READ}}$, CE	5			ns	
t_{RA2}	Address Hold Time for $\overline{\text{READ}}$, C/D	370			ns	
t_{DTx}	TxD Delay from Falling Edge of TxC	1			μs	C_L=100pF
t_{SRx}	Rx Data Set-Up Time to Sampling Pulse	2			μs	C_L=100pF
t_{HRx}	Rx Data Hold Time to Sampling Pulse	2			μs	C_L=100pF
f_{Tx}	Transmitter Input Clock Frequency 1X Baud Rate 16X and 64X Baud Rate	 DC DC		 56 615	 KHz KHz	
f_{Rx}	Receiver Input Clock Frequency 1X Baud Rate 16X and 64X Baud Rate	 DC DC		 56 615	 KHz KHz	
t_{Tx}	TxRDY Delay from Center of Data Bit			16	CLK Period	C_L=50pF
t_{Rx}	RxRDY Delay from Center of Data Bit	15		20	CLK Period	
t_{IS}	Internal Syndet Delay from Center of Data Bit	20		25	CLK Period	
t_{ES}	External Syndet Set-Up Time before Falling Edge of RxC			15	CLK Period	

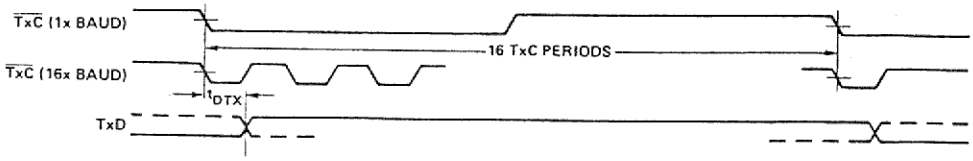
Note: The TxC and RxC frequencies have the following limitation with respect to CLK.
For ASYNC Mode, t_{Tx} or $t_{Rx} \geq 4.5\ t_{CY}$
For SYNC Mode, t_{Tx} or $t_{Rx} \geq 30\ t_{CY}$

READ AND WRITE TIMING

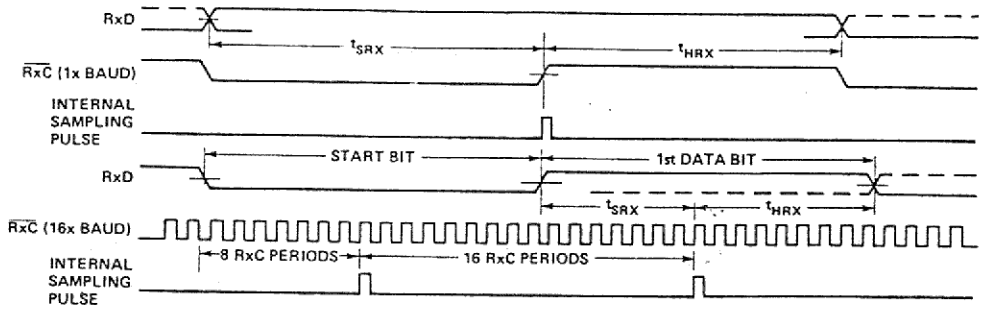


*WRITE AND READ PULSES HAVE NO TIMING LIMITATION WITH RESPECT TO CLK.

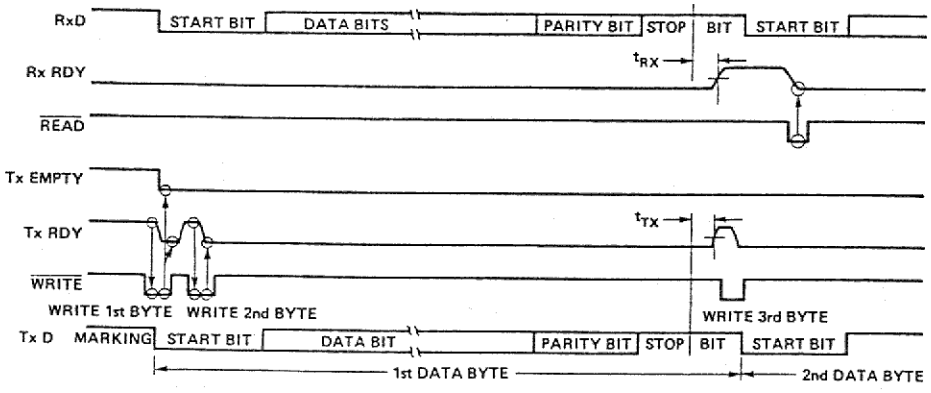
TRANSMITTER CLOCK AND DATA



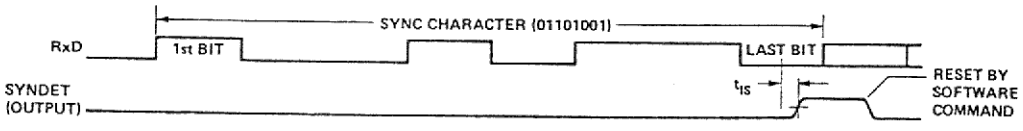
RECEIVER CLOCK AND DATA



Tx RDY AND Rx RDY TIMING (ASYNC MODE)



INTERNAL SYNC DETECT



EXTERNAL SYNC DETECT