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RC3502 Operating Guide



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Abstract:

This manual describes how to operate the RC3502: Power-on, power-off, commands to the operating system OPSYS, operation of the DEBUG console, autoloading.

(This manual replaces RCSL: 52-AA1016).

(58 printed pages).

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1. SWITCHES AND INDICATORS

1.

1.1 Operator's Control Panel

1.1

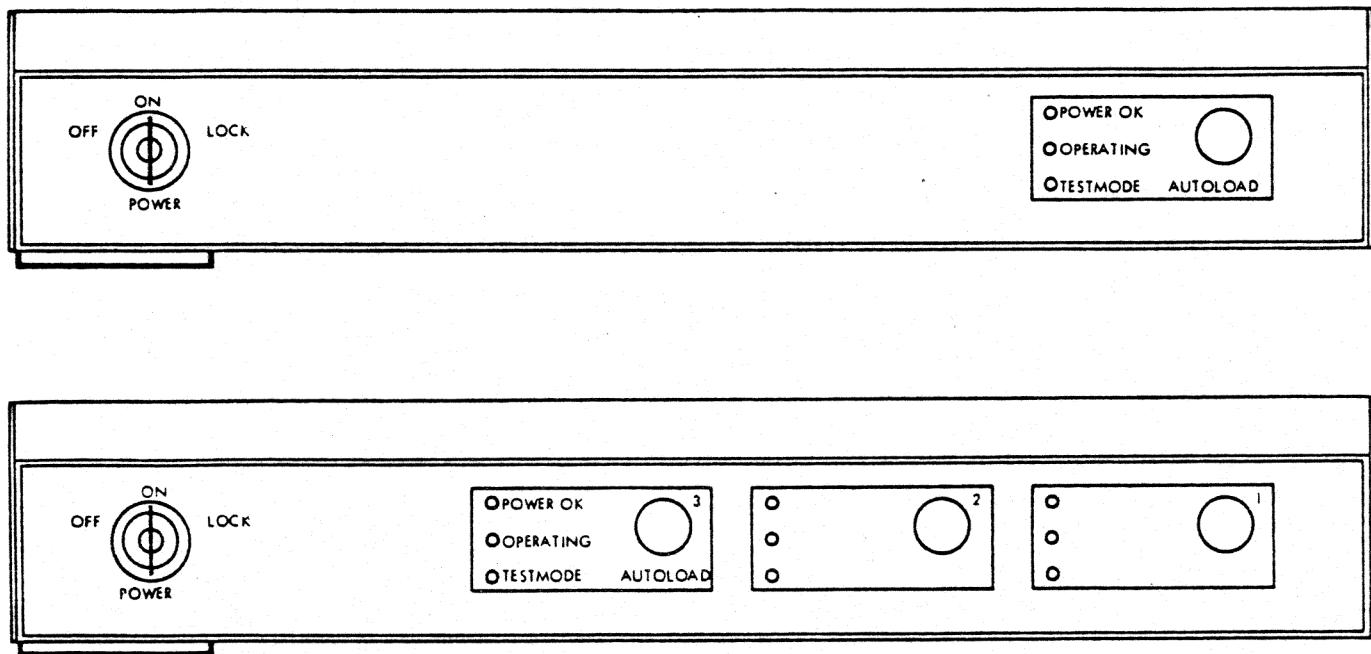


Fig. 1. OCP for Rack with One RC3502 or Three RC3502.

Power off of the RC3502(s) is done by turning the power key to the OFF position.

Power on of the RC3502(s) is done by turning the key to the ON position (or further on to the LOCK position).

The AUTOLOAD button(s) is (are) enabled when the key is in the ON position, and disabled, when in the LOCK position.

The AUTOLOAD button initiates autoloading of the RC3502 in question.

The POWER OK indicator is illuminated during power OK condition on the RC3502.

The OPERATING lamp indicates that the RC3502 is running normally.

The TEST MODE lamp indicates that the RC3502 is executing the built-in test programs.

1.2 Processor Front Panel

The front panel of the processor board contains five switches, five indicators, and a jack.

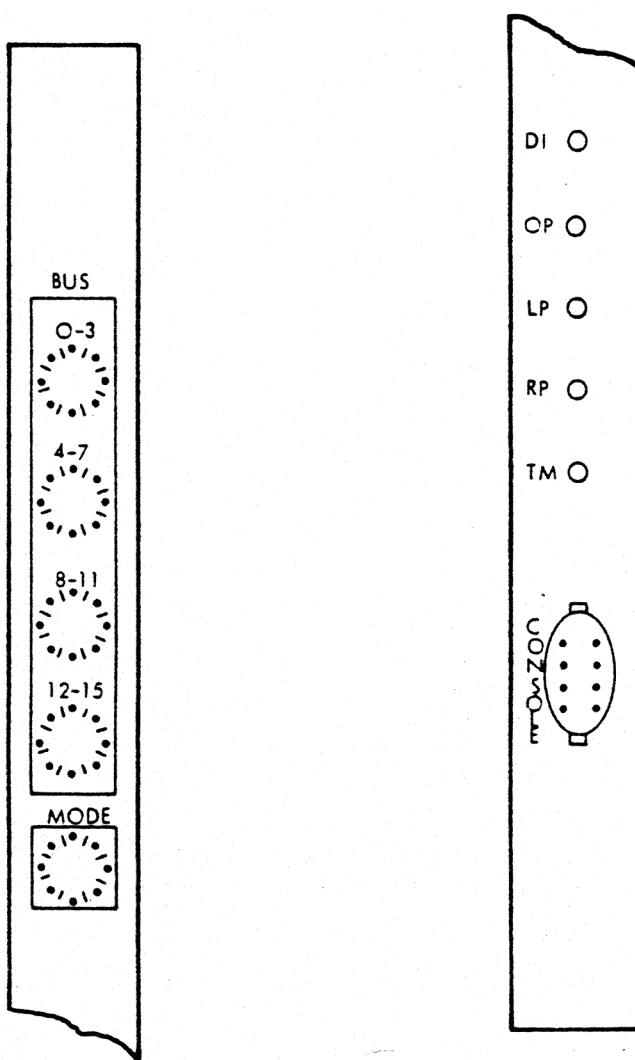


Fig. 2. Processor Front Panel, Switches and Indicators.

1.2.1 Switches

All of the switches are rotary switches with 16 positions, indicated by the hexadecimal numbers 0 to F. The switches are set by means of a screwdriver.

1.2.1

1.2.1.1Bus Switches

The four switches marked BUS are used to supply the processor with data. There is a switch for bits 0 to 3, 4 to 7, 8 to 11, and 12 to 15.

1.2.1.2Mode Switch

The switch marked MODE is used to control the baud rate for the console and the execution of the built-in test programs (sect. 1.2.2).

If the mode switch is equal to, or greater than 8, the console is locked to Terminal-mode (T-mode), i.e. the console will not switch to Debug-mode (D-mode) by activating the BELL key (CTRL G). The mode switch is only read after power restart.

<u>Settings</u>	<u>Baud Rate</u>	<u>Execution Mode</u>
0 (8)	300 bps	run test, loop
1 (9)	1200 bps	run test, loop
2 (A)	300 bps	skip test
3 (B)	1200 bps	skip test
4 (C)	300 bps	run test, no loop
5 (D)	1200 bps	run test, no loop
6 (E)	300 bps	skip test
7 (F)	1200 bps	skip test

Test Program Execution Modes

run test The test programs are executed whenever the autoload button is pressed.

skip test The test programs are not executed.

loop The test programs are executed in an endless loop.

no loop The test programs are executed once.

1.2.2IndicatorsDI Disabled Interrupt

This lamp, when lit, indicates that the processor is running in the disabled interrupt mode.

OP Operating

This lamp, when lit, indicates that the processor is running normally; when it is extinguished, the processor has stopped.

LP Left Parity Error

This lamp, when lit, indicates that a parity error has been detected during a memory read in the left byte. The lamp can be extinguished only by autoloading.

RP Right Parity Error

This lamp, when lit, indicates that a parity error has been detected during a memory read in the right byte. The lamp can be extinguished only by autoloading.

TM Test Mode

This lamp, when lit, indicates that the processor is executing the built-in test programs. The current program is indicated by the OP, LP, RP, and TM lamps, TM representing the least significant bit of the program number.

If an error is detected by a test program, one of the following messages is displayed on the console:

1 8085 Communication Test

Message: ERR 1 <dummy><dummy>
Y5D gives 6 bytes of transmitted data.
Y70 gives 6 bytes of received data.

3 Communication Test

Microprogram interrupt of control microprocessor.
No message is displayed, but RP and TM are lit.

5 Working Register Address Test

Message: ERR 5 <address><data read>
W <address> gives data read.

7 Working Register Data Test

Message: ERR 7 <address> <data read>
W <address> gives data read.

9 Memory Address Test

Message: ERR 9 <address.displacement> <data read>
<err.type>
Y40 gives memory module number.
M <memory module.displacement>
gives data read.
err.type: + 1 = left parity error
+ 2 = right parity error
+ 4 = dataerror

B Memory Data Test

Pattern 5555.

Message: ERR B <address.displacement> <data read>
<err.type>
Y40 gives memory module number.
M <memory module.displacement>
gives data read.

D Memory Data Test

Pattern AAAA.

Message: ERR D <address.displacement> <data read>
<error type>
Y40 gives memory module number.
M <memory module.displacement>
gives data read.

1.3 Power Supply**1.3**

The power supply can be either POW201 or POW204.

The power supply (POW201) is supplied with a number of controls:

AC MAINS: Manual and automatic circuit breaker.

LOCK: Spring loaded lock switch, which inhibits manual intervention of AC MAINS and AUTO functions.

POWER OK: Indicator which is illuminated during power OK condition.

AUTO: Push button for manual generation of an autoload signal.

TEMP: Indicator which remains on after a power break caused by an overheating condition.

The power supply POW204 is supplied with the following controls:

POWER: Circuit breaker, lit when power on.

POWEROK: Indicator which is illuminated during power ok condition.

POWER FAILURE:

OVER-TEMPERATURE:

OVER-VOLTAGE: Error indicators which are illuminated after an error condition. These indicators are reset after activating the circuit-breaker, or after activating the RESET push-button.

RESET: Push-button for manual generation of an autoload signal and a reset of the error indicators.

2. CONSOLE OPERATION

2.

The console may be in one of two possible modes: Debug-mode (D-mode) or Terminal-mode (T-mode). A switch between the two modes takes place when the BELL key (CTRL G) is activated.

2.1 Terminal Mode

2.1

The console may work as terminal for the RC3502 software system, while in T-mode.

An operator process coordinates the communication between the software system and the operator.

2.1.1 Operator Process

2.1.1

Input and output messages to the operator are identified by a name. The operator process holds a variable 'current name', which identifies the current process incarnation for input or output.

'current name' is updated in the following situations:

1.  <name> 

The input line contains a name which is assigned to 'current name'. The operator searches its queue of pending input messages for a message with <name> as identification. If at least one message is found, it is activated. If it is a reactivation, the old input is repeated.

If no message is found, BELL is echoed.

Note:

  is attention to 'current name'.

2. By output.

If the output message has name = 'current name', the output message is printed on the console.

If the output message has name <> 'current name', 'current name' is updated and

> "current name"

is printed followed by the text from the output message.

3.  ? 

Prints the identifications of all pending input messages. 'current name' is updated to the last name in the printout.

The operator has a number of facilities for controlling output and for editing purposes:

	E	- deletes the whole line
		- deletes the last character
		- repeats the whole line
		- deletes the last character. '<-' is echoed.
	S	- stops output.
	O	- starts output.
	O	- skips output. The function is modulo 2 and is reset to 'no skip' by ESC .

Note:  may be Carriage Return or Line Feed.

2.1.2 OPSYS Commands

2.1.2

OPSYS interprets the following commands. The under-scored characters are sufficient for the interpretation.

More than one command may be typed on one line, unless the syntax is terminated by <nl>.

Whenever <incarnation> or <process> is listed - unless otherwise stated - we refer to children of ADAM with heading:

```
PROCESS pip (VAR sv: system_vector);
```

In the following all numbers are decimal, unless otherwise stated.

BREAK <incarnation>

The child <incarnation> is broken with the current value of excode as exception code.

The child may be any incarnation in the incarnation tree.

E.g.: BREAK S

CHECK <module no>

performs a CRC16 check of the memory module <module no>. If an error is detected, the word address interval, the expected, and computed checksum are printed.

E.g.: CHECK 25

CREATE <incarnation> { AS <process>}¹
0

creates an incarnation of the process <process>. If <process> is omitted the process is supposed to have the same name as the incarnation. The size of the stack is the current value of SIZE (see the SIZE command).

E.g.: CREATE T1 AS TEST CREATE T2 AS TEST

DATE {<year>.<month>.<day> <hour>.<minute>.<seconds>}¹
0

If the parameters are included the date is initialized. The command always responds with the current date.

E.g.: DATE 83.01.04 15.30.20

EXCODE <integer>

initializes the current value of excode to <integer>.

Default: excode = -1.

E.g.: EXCODE 47

FREE lists the free areas in the RAM modules. The start displacement and size in words of the holes are listed, besides the number of holes, the minimum hole, the maximum hole and the sum of the holes per module.

FROM {
 PTR
 FPA}

initializes the current value for load kind to PTR or FPA. Load kind controls the kind of driver used for dynamic load (see LOAD). Default load kind is taken from the hexadecimal switches.

E.g.: FROM PTR

HELP lists the available OPSYS commands.

IN <inchannel>

initializes the current value of the I/O channel used for load. Default <inchannel> is taken from the hexadecimal switches.

E.g.: IN 82

KILL <incarnation>

works as the REMOVE command.

LINK <process>

links a process with name <process> to a process declaration in ADAM.

E.g.: LINK CPUSE

LIST {<incarnation>} <n>

lists the incarnation tree with root <incarnation>. If <incarnation> is missing 'adam' is taken as root.

E.g.:

LIST OPSYS TIMER OPERATOR

incarnation	depth	level	prio	state	size	stack	father
opsys	0	0	1	run	512	00c8.e660	adam
incarnation	depth	level	prio	state	size	stack	father
timer	0	2		wait	157	00c8.df3a	
incarnation	depth	level	prio	state	size	stack	father
operator	0	0	1	wait	190	00c8.e484	adam
console	1	0	1	wait	201	00c8.efb8	operator
debugout	2	4		wait	98	00c8.f2b0	console
debugin	2	3		wait	98	00c8.f1ac	console

LOAD {<program>}ⁿ <n1>
 0

loads the programs from an external device of kind 'current load kind' (see the FROM command) in the I/O channel 'current inchannel' (see the IN command). If no programs are specified, all appearing programs are loaded.

E.g.: FROM PTR IN 82 LOAD PRINTCHAR PRINTNL

Binary relocatable papertapes for load from PTR are produced like

JOB A 1 DEVICE PUNCH

TPN = PUNCH16 MODE.CRC16 {Bxxxx}ⁿ
 1

FINIS

where Bxxxx is the binary output from the PAS-CAL80 compiler.

A binary relocatable file for load from FPA is produced like

JOB A 1

xxxx = PUNCH16 MODE.CRC16 {Bxxxx}ⁿ
 1

SCOPE yyyy xxxx

FINIS

where Bxxxx is the binary output from the PAS-CAL80 compiler.

The file xxxx is loaded by e.g.:

JOB A 1 DEVICE 18

main35001 = autoload xxxx start.no

LOOKUP {<program>}_n
 }1
 <n1>

makes a lookup in the LINKER catalog for the listed programs.

E.g.:

LOOKUP CREATE LINKER OUTINTEGER							
FUNCTION create	1982.11.23	13.58	1	12000	768	34	5
PROCESS linker	1982.11.29	08.32	1	12000	3238	358	1
PROCEDURE outinteger	1982.11.23	13.58	1	12000	300	23	3

1) 2) 3) 4) 5) 6) 7) 8)

The output has the interpretation:

1. program kind
2. program name
3. date of compilation
4. number of code pages
5. pagesize in bytes
6. last page size in bytes
7. default appetite (create size) in words

8. number of parameters

PRINT { <base> { <first disp> { <last disp>
 } 1 } 1 } 1 } 1 } 1 } <n1>
 { <no of words per line> { <delta> } 0 } 0 } 0 } 0 } 0 }

outputs the specified memory area with a fixed format (see the example): <base>, <first disp>, and <last disp> are hexadecimal.

<delta> defines the default increase of <first disp> if <last disp> is not specified. After the PRINT command <first disp> := <last disp> + 2.

E.g:

```
PRINT C8 E660 E760
address
00c8.e660 00c8 200 0 200
00c8.e662 e661 -6559 230 97 a
00c8.e664 0000 0 0 0
00c8.e666 0000 0 0 0
00c8.e668 00c8 200 0 200
00c8.e66a e6ae -6482 230 174
00c8.e66c 00c8 200 0 200
00c8.e66e d7ed -10259 215 237
00c8.e670 4000 16384 64 0 @
00c8.e672 e7eb -6165 231 235
00c8.e674 ffff -1 255 255
00c8.e676 00c0 192 0 192
00c8.e678 5fc9 24521 95 201
00c8.e67a 00c0 192 0 192
00c8.e67c ae8a -20806 174 186
00c8.e67e ea5d -5539 234 93 A
00c8.e680 0020 32 0 32
00c8.e682 e7f9 -6151 231 249
00c8.e684 e7eb -6165 231 235
00c8.e686 00c0 192 0 192
00c8.e688 46ce 18126 70 206 F
00c8.e68a 0000 0 0 0
00c8.e68c ea5f -5537 234 95 -
00c8.e68e 00c8 200 0 200
00c8.e690 e13e -7874 225 62 >
00c8.e692 00c8 200 0 200
00c8.e694 e74e -6322 231 78 N
00c8.e696 00c8 200 0 200
00c8.e698 e73e -6338 231 62 >
00c8.e69a 4000 16384 64 0 @
00c8.e69c e77a -6278 231 122 z
00c8.e69e 00c8 200 0 200
00c8.e6a0 eeec -4372 238 236
00c8.e6a2 4000 16384 64 0 @
00c8.e6a4 0000 0 0 0
00c8.e6a6 4000 16384 64 0 @
00c8.e6a8 e661 -6559 230 97 a
```

00c8.e6aa	4000	16384	64	0	@
00c8.e6ac	0000	0	0	0	
00c8.e6ae	4000	16384	64	0	@
00c8.e6b0	e3a0	-7264	227	160	
00c8.e6b2	4000	16384	64	0	@
00c8.e6b4	0000	0	0	0	
00c8.e6b6	00c0	192	0	192	
00c8.e6b8	00a0	160	0	160	
00c8.e6ba	00c0	192	0	192	
00c8.e6bc	6156	24918	97	86	a v
00c8.e6be	6f70	28528	111	112	a p
00c8.e6c0	7379	29561	115	121	s y
00c8.e6c2	7320	29472	115	32	s
00c8.e6c4	2020	8224	32	32	
00c8.e6c6	2020	8224	32	32	
00c8.e6c8	2020	8224	32	32	
00c8.e6ca	00c8	200	0	200	
00c8.e6cc	e074	-8076	224	116	t
00c8.e6ce	00c8	200	0	200	
00c8.e6d0	e0e6	-7962	224	230	
00c8.e6d2	4000	16384	64	0	@
00c8.e6d4	e3a0	-7264	227	160	
00c8.e6d6	5555	21845	85	85	U U
00c8.e6d8	aaaa	-21846	170	170	
00c8.e6da	4000	16384	64	0	@
00c8.e6dc	0000	0	0	0	
00c8.e6de	00c0	192	0	192	
00c8.e6e0	0054	84	0	84	T
00c8.e6e2	00c8	200	0	200	
00c8.e6e4	e6e6	-6426	230	230	
00c8.e6e6	00c8				

PRIORITY <integer>

initializes the current value for priority used by the START or RUN command.

Default: priority = -3.

E.g.: PRIORITY -1

REMOVE <incarnation>

removes the child <incarnation> of ADAM and the associated subtree.

E.g.: REMOVE S

RUN <incarnation> { AS <process> }
links, creates, and starts an incarnation with name <incarnation> of the process <process>.
0 1

If <process> is omitted, the process is supposed to have the same name as the incarnation.

E.g.: RUN T1 AS TEST RUN MIRROR

SIZE <integer>

initializes the current value of SIZE used when creating ADAM children.

Default: SIZE = 0.

(Note: SIZE = 0 will trigger the use of the default create size for the program (see the LOOKUP command)).

E.g.: SIZE 763

START <incarnation>

starts the ADAM child <incarnation> with the current value of PRIORITY as priority.

E.g.: START S

STOP <incarnation>

stops the ADAM child <incarnation>.

E.g.: STOP S

UNLINK <process>

unlink a process with name <process> from a process declaration in ADAM.

E.g.: UNLINK CPUSE

UNLOAD {<program>} <n1>
}n

deletes the programs from the LINKER catalog, if the programs are not referenced by other programs. If other programs become not referenced after the delete, these programs are also deleted.

E.g.: UNLOAD CPUSE TEST

2.1.3 Messages from OPSYS

2.1.3

The rest of the command line is skipped if any of the following messages appear:

*** loader not ready

- the LOADER is not included in the system or is unable to run owing to lack of memory.

*** command not implemented

- the command is not available in this version of OPSYS

*** syntax error

- misspelling of a command

*** processname missing

*** unknown incarnation

*** unknown process

*** processname busy

- incarnations of this process still exist

*** incarnationname missing

*** name in use

*** no free processdeclarations

- you must release a process declaration in ADAM
by the command UNLINK

*** process not loaded

- the LINKER catalog does not contain the stated
process

*** process parameters not equal

- a process with the stated name exists in the
LINKER catalog, but the parameter list does not
fulfil the declaration

PROCESS pip (VAR sv : system_vector);

*** size too small or too large

- use the SIZE command to adjust the SIZE
parameter

*** process not linked

- use the LINK command

*** unknown program

- the program is not in the LINKER catalog. The
program may be loaded by the LOAD command

*** program busy

- the program is still accessed by other programs
in the system

2.1.4 Messages from LOADER

2.1.4

***** install more ram memory**

- the LOADER cannot get enough memory to run

***** loaddriver no stack**

- the driver cannot be created due to lack of memory

***** level reservation trouble**

- the interrupt level requested for load is occupied by another process incarnation in the system

scan no: x from fpa in xxxx

- initialize load from RC8000 when the first scan is announced (Note: xxxx is decimal). Later scans are performed by the loader itself with no need for operator assistance.

scan no: x from ptr in xxxx

- place the paper tape in the reader whenever a scan is announced

expected: xxxx

received: xxxx

- the crc16 data check reports an error. The programs should be reloaded

end loader

- normal finis message from the LOADER. A list of the loaded programs is printed with name and compilation date. The list may be extended with the information

***** warning: versionerror**

- the program should be recompiled, but loading continues

***** overlap**

- the program is already in the LINKER catalog.
The program in the catalog is used instead and
the loaded program deleted

***** skipped**

- the loaded program is deleted because of
problems during load. E.g. an external reference
could not be defined

***** not loaded**

- the program was not in the LINKER catalog or
amongst the loaded programs.

2.2 Debug Mode

2.2

2.2.1 Activation

2.2.1

If the MODE switch is set in the range 0 to 7, the console may be put in Debug-mode (D-mode) at any time by pressing the BELL key (CTRL and G keys) without stopping instruction execution in the processor. A number of display and control commands become available for technical purposes.

2.2.2 Display Commands

2.2.2

Display commands cause the display of eight words of data. The following display commands are available:

M <addr>	<u>Modify Memory</u> Displays the contents of the 8 memory locations starting at <addr>.
W <register>	<u>Modify Working Registers</u> Displays the contents of the 8 working registers starting at <register>.
L <level>	<u>Modify Working Registers</u> Displays the level number and the contents of the 8 working registers belonging to <level>.

Y <yaddr> Modify Control Microprocessor RAM
 Displays the contents of the 8 control
 microprocessor RAM locations starting
 at <yaddr>.

Display commands are executed in the following situations:

1. When a display command is entered

One can now modify the displayed data by entering new data in the same positions on the following line. Pressing the space bar will move the cursor one position to the right.

A display command is terminated by pressing one of the following keys:

CR The CR key terminates the current display command. The console will await the next command.

+ The + key terminates the current display command and executes a display command for the succeeding 8 words (M or Y) or the 8 registers on the succeeding level (W).

- The - key terminates the current display command and executes a display command for the preceding 8 words (M or Y) or the 8 registers on the preceding level (W).

ESC The ESC key terminates the current display command, but no data modification takes place. The text ESC is displayed. The console will await the next command.

2. When a control command (sect.3.1.3) is terminated

The last executed display command is repeated, but modification of the displayed data is not allowed. The console will await the next command.

2.2.3 Control Commands

The following control commands are available:

R

Run

The processor will start instruction execution.

S

Instruction Step

The processor will execute one instruction, stop, and reactivate the console.

S <steps>

Multi-Instruction Step

The processor will execute <steps> instructions, stop and reactivate the console.

2.2.4 Command Parameters

All numbers entered or displayed are hexadecimal.

At any time the entering of an empty command (i.e. pressing the CR key) will cause the previous command to be repeated.

An address (<addr>) is entered using one of the following formats:

<base> : <disp>

or

: <disp>

<base> is the leftmost 16 bits of the 32-bit address.

<disp> is the displacement within the selected memory module, i.e. the rightmost 16 bits of the address.

If the second format (: <disp>) is used, the last entered address base will be echoed and used.

3. AUTOLOADING

3.

The autoload function may be initiated by:

- Power Restart
- Watchdog Restart

Power Restart

Power Restart happens:

- when power ON is performed manually on the OCP or on the power supply,
- by temporary power failure,
- by manual activation of the autoload button on the OCP or the AUTO push button on the power supply.

The built-in test programs are activated controlled by the 'MODE' switch, the CPU initializes the registers, whereafter control is passed to the autoload program residing on the first memory module.

Watchdog Restart

Watchdog Restart may be activated both manually by means of the 'Y' debug console command and from the software.

The CPU initializes the registers, whereafter control is given to the autoload program. No built-in test programs are activated.

3.1 Autoload Switch Format

3.1

The autoload program interprets the four BUS switches on the Processor Front Panel according to the format:

	0-3	4-7	8-11	12-15
D/E	KIND	MODULE#	ADDRESS	

D/EAutoload Disabled/Enabled

is intended for drivers controlling external devices, which may autoload RC3502. A driver may activate the watchdog function if autoload enabled.

- 0 ~ enabled
- 1 ~ disabled

KINDAutoload Kind

defines which algorithm the autoload program executes.

0 JUMP

An unconditional jump is performed to the location defined by 'MODULE#' and 'ADDRESS'. Only jumps with base in the range 00C0 to 00DE are possible.

1 IFP MB Master

Defines this RC3502 as the Multibus Master in a multi processor configuration. Autoload is from IFP whereafter the software in EPROMs is included.

2 FPA

Autoload is from FPA, and the software in EPROMs is included.

3 IFP MB Slave

Defines this RC3502 as a Multibus Slave in a multi processor configuration. Autoload is from IFP, and the software in EPROMs is included.

4 PTR

Autoload is from paper tape reader, and the software in EPROMs is included.

5 Autoload is from COM204 (Intelligent HDLC Controller), and the software in EPROMs is included.

6 EPROM

No autoload from external device. Only software in EPROMs is included.

7 (Not used).

MODULE#**Module Number**

Defines the value of the module select field in an address.

KIND = JUMP (0)

Module is the module number in the jump address.

KIND = IFP (1 or 3)

Module is the module number in the start address of the IFP memory.

KIND = COM204 (5)

The field has another interpretation:

4-7

 ! ! ! ! !
 ! F ! F A N !
 ! ! ! ! !

F - defines the type of load request transmitted on the HDLC line:

0 NNP loadrequest

1 X.25/3 loadrequest

FAN - defines the maximum relative channel no. used for autoload in a cyclic way if a channel fails. Channels 0,1,...FAN relative to the start channel (see later) are used.

ADDRESS

specifies the displacement part of an address or interrupt level (input/output channel) depending on the value of KIND.

KIND	ADDRESS
0	Displacement
1	IFP interrupt level
2	FPA100 REC input/output channel
3	IFP interrupt level
4	PTR input/output channel
5	CHANNELx128+COM204 interrupt level
6	'Not used'
7	'Not used'

Example 0 GOTO 00C8.007A

----- ! 047A ! or ! 847A ! -----

Example 1 Autoload from IFP which starts in address 0086.0000 and interrupts on level 112 (decimal)

----- ! 1370 ! or ! 9370 ! -----

Example 2 Autoload from FPA in channel 81 (decimal)

----- ! 2x51 ! or ! Ax51 ! -----

Example 3 (See example 1)

Example 4 Autoload from paper tape reader in channel 83 (decimal)

----- ! 4x53 ! or ! Cx53 ! -----

Example 5 Autoload from COM204 address 0092.8000 level 19 (decimal) channel 1 using NNP loadrequest and a fan consisting of 3 channels:

! 5293 ! or ! D293 !

Conventions:

1. Start address of the reference controller must be 0090.0000.
2. Interrupt level of the reference controller must be a multiplum of 8.
3. The controllers must be consecutive and increasing memorywise and according to interrupt levels (see the following table).

COM204 (Example 5 cont.)

	! address	! level	! channel	!
Reference Controller	! 0090.0000 !	16	! 0	!
	!	!	! 1	!
	! 0090.8000 !	17	! 0	!
	!	!	! 1	!
	! 0092.0000 !	18	! 0	!
	!	!	! 1	!
First Controller	! 0092.8000 !	19	! 0	!
	!	!	! 1	! <- 1)
Last Controller	! 0094.0000 !	20	! 0	!
	!	!	! 1	! <- 2)
	! 0094.8000 !	21	! 0	!
	!	!	! 1	!
	! 0096.0000 !	22	! 0	!
	!	!	! 1	!
	! 0096.8000 !	23	! 0	!
	!	!	! 1	!

- 1) first channel in fan
 2) last channel in fan

Example 6 No autoload, only inclusion of software in EPROMs.

! 6xxx ! or ! Exxx !

3.2 Autoload Messages

3.2

Autoload from ifp in xxxxH
 Autoload from ifp in xxxxH
 Autoload from ptr in xxxxH
 Autoload from COM204 addr xxxx.xxxx level xxxxH channel xxxxH
 Autoload from eprom
 *** undefined switchkind

.....

- a full stop is printed for every program loaded.

*** exception: xxxx at: xxxx.xxxx

- consult appendix I for interpretation of the exception code.

*** buy more memory!!!!

- more RAM memory must be installed to hold the autoloaded programs.

**** warning: versionerror at xxxx.xxxx

- the program identified by the address must be recompiled to be autoloaded. Consult the output from CROSSLINK for identification.

**** warning: <program> overlapping at xxxx.xxxx

- the program identified by the address has a double in the system. The program is included and operation continues.

expected: xxxx
received: xxxx

- the crc16 data check reports an error. If more than 5 errors occur, the autoload program will start all over again.

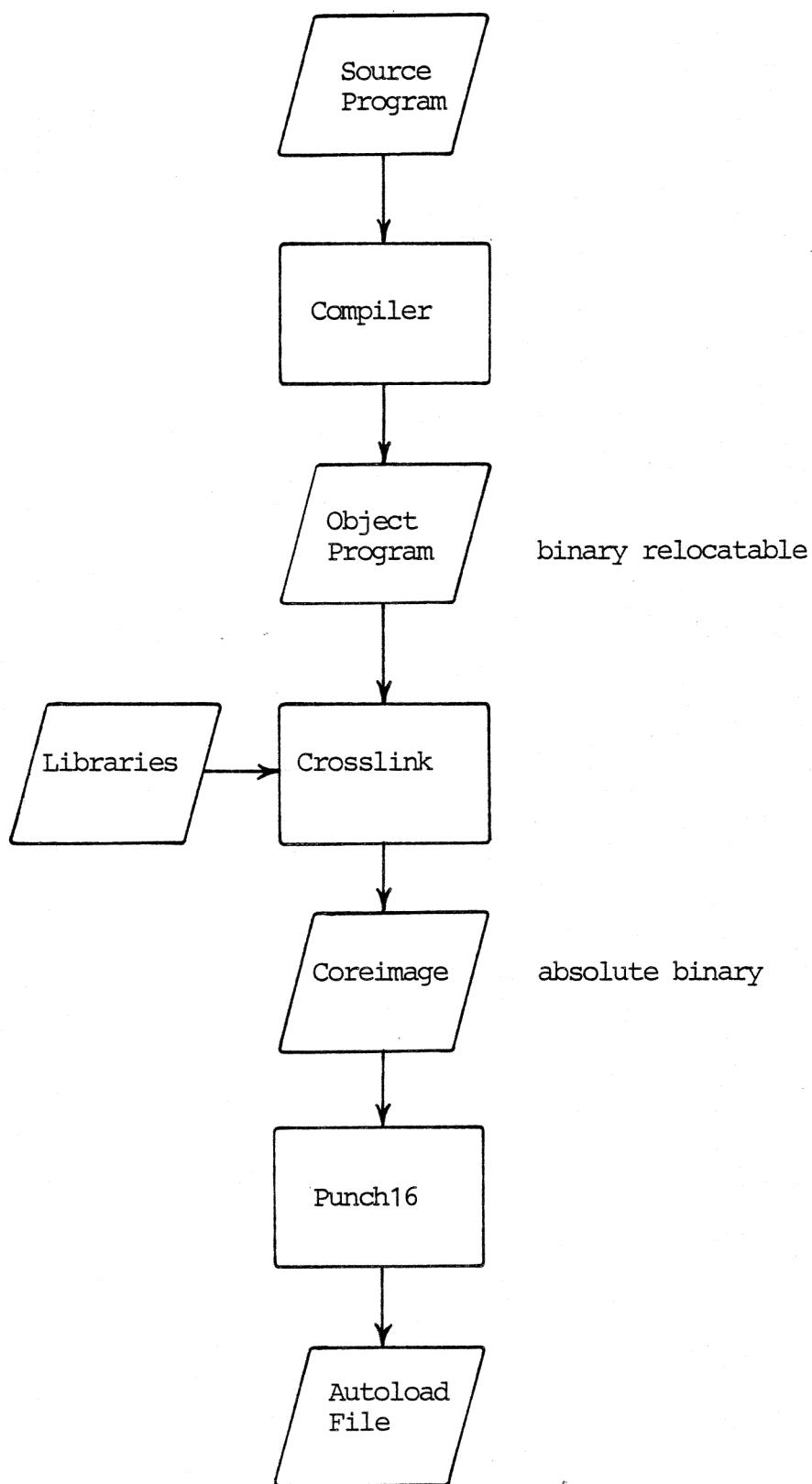
Generating Autoload Files

Fig. 3. Autoload File Generation.

3.3.1 Generating a Paper Tape Autoloadfile

3.3.1

If the file 'coreimage' has been produced by the 'CROSSLINK' program, the following call will generate a paper tape with the correct format for the autoloadprogram in RC3502:

```
tpn = punch16 mode.crc16 coreimage
```

3.3.2 Generating an FPA/IFP Autoloadfile

3.3.2

If the file 'coreimage' has been produced by the 'CROSSLINK' program, the following calls will generate an autoloadfile and autoload the RC3502 if connected via the process 'main35001':

```
bootfile = punch16 mode.crc16 coreimage  
main35001 = autoload bootfile start.no
```

3.3.3 Generating TES202 Eproms

3.3.3

Consult ref. 10.

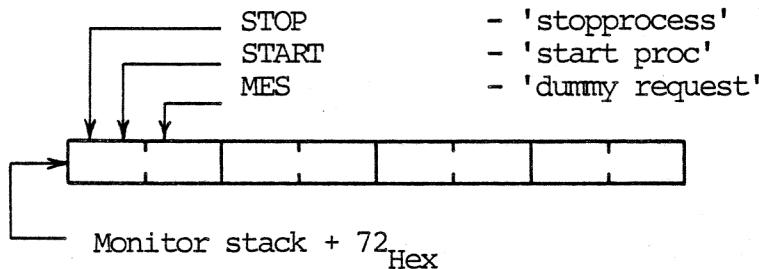
4. ERROR PROCEDURES

For use in error situations it might be useful to get testoutput from the autoload program 'BOOT' or from the process MONITOR which starts and stops process incarnations.

4.1 Monitor Testoutput

4.1

The monitor stack address is obtained by the LIST MONITOR command to OPSYS or from the testoutput from BOOT (see 4.2).



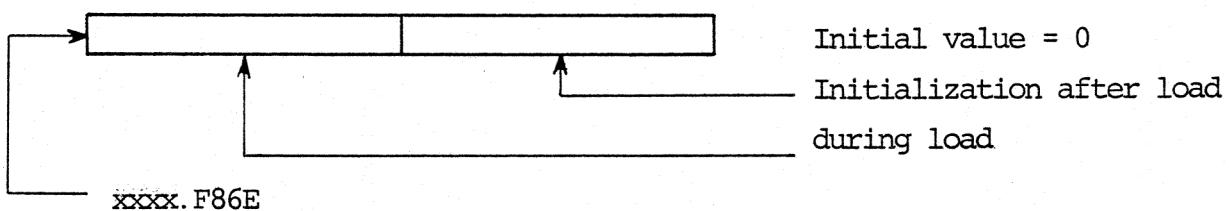
- 'stopprocess'
- 'start proc'
- 'dummy request'

Initial value = 0.

4.2 Boot Testoutput

4.2

The BOOT stack address is xxxx.F800 where xxxx is the base address of the last RAM memory module in the RC3502. If testoutput during autoload from FPA is wanted, you must increase the software time out in the FPA xmt driver in RC8000 from 1 sec. to at least 5 sec.



A. REFERENCES

A.

1. RCSL No. 42-i1577
PASCAL80, Introduction
2. RCSL No. 52-AA964
PASCAL80, Report
3. RCSL No. 42-i1539
PASCAL80, User's Guide
4. RCSL No. 31-D617
PASCAL80, Driver Conventions
5. RCSL No. 31-D627
RC3502, Introduction
6. RCSL No. 52-AA972
RC3502, Reference Manual
7. RCSL No. 52-AA1167
RC3502-PASCAL80
Reference Manual
8. RCSL No. 30-M300
RC3502 PROM Blasting Program
User's Guide

B. OPSYS COMMANDS

break <incarnation>

check <module no>

create <incarnation> { as <process> }
0 1

date { <year>. <month>. <day> <hour>. <minute>. <seconds> }
0 1

excode <integer>

free

from { ptr
 { fpa } }

help

in <inchannel>

kill <incarnation>

link <process>

list { <incarnation> }
n
0

load { <program> }
n
0

lookup { <program> }
n
1

print { <base> { <firstdisp> { <lastdisp> {
 { <no_of_words_per_line> { <delta> } } } } } }
1 1 1 1 1 1
0 0 0 0 0 0
<n1>

priority <integer>

remove <incarnation>

run <incarnation> as <process>

size <integer>

start <incarnation>

stop <incarnation>

unlink <process>

unload <program> <n1>

C. AUTOLOAD SWITCH LAYOUT

C.

D/E	KIND	MODULE #	ADDRESS

D/E - Autoload Disabled/Enabled

disabled = 1
 enabled = 0

Intended for drivers controlling External Devices, which may autoload RC3502. The drivers may activate the watchdog function, if D/E = 0. BOOT ignores this switch.

KIND

- 0 JUMP
- 1 IFP MB master
- 2 FPA
- 3 IFP MB slave
- 4 PTR
- 5 COM204
- 6 EPROM

ADDRESS

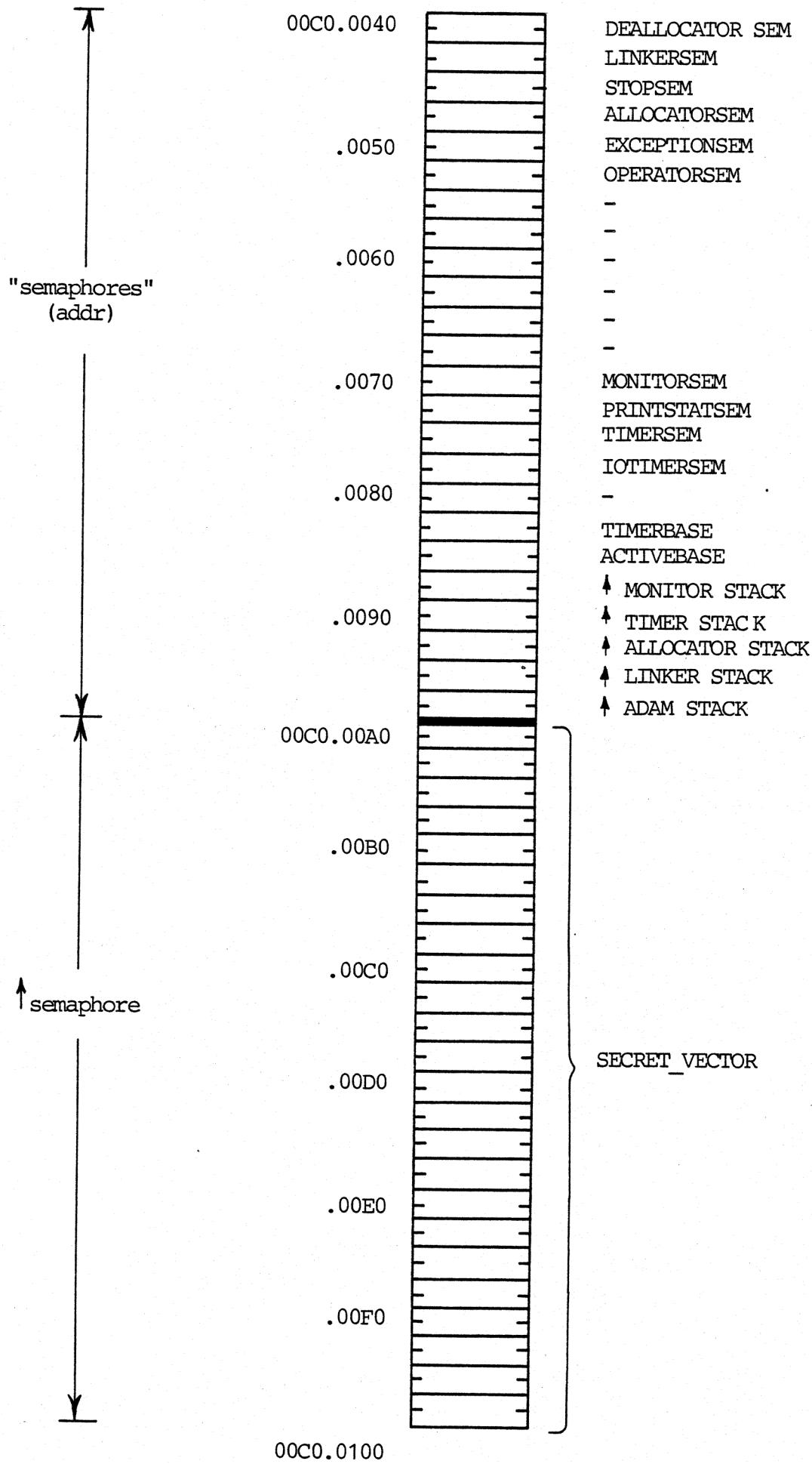
- Displacement if JUMP kind
- I/O channel if FPA or PTR
- Interrupt level if IFP
- Channel x 128 + interrupt level if COM204

MODULE#

- Module number if JUMP kind
- Multibus Module No. if IFP
- Load request x 8 + fan if COM204

D. SECRET VECTOR LAYOUT

D.



E. INSTRUCTION CODES

```

00: except    2b: l0fbx   2c: trap   1      57: settm   82: svsb2   21
       bl: rec1    2d: trapr  1      58: mc1s   83: rvsb2   21
       02: rec2    2e: mxept   59: seteq   84: svsb4   4
       03: rec3    2f: mnnoop  5a: setsb  85: rvsb4   4
       04: rec4    30: mwst   5b: setsb  86: svsb6   1
       05: rec5    31: ult    5c: setun   87: rvsb6   2
       06: rec6    32: eq     5d: setin   88: mw1    b2: stvgw  2
       07: rec7    33: ne     5e: setd1   89: revabs 1
       08: rec8    34: lt     5f: setad   b3: revgn  2
       09: rec9    35: gt     60: recD   b4: stviw  1 2
       0a: rec10   36: le     61: jmzeq  b5: reviw  1 2
       0b: rec11   37: ge     62: jmzne  b6: stvhw 2
       0c: rec12   38: mwlist 63: jmzlt  b7: reviw  2
       0d: rec13   39: tn111  64: jmzgt  b8: stvbs 1
       0e: rec14   3a: open   65: jmzle  b9: reviw  2
       0f: rec15   3b: tlock  66: jmzge  ba: stvaw  4
       10: cwait   3c: teqad  67: jmprw  bb: revab  4
       11: csign   3d: not   68: mcit   bc: svsw28
       12: crele   3e: except 69: jmphc  bd: svsw29
       13: cl1st   3f: except 6a: jmpdd  be: svsw30
       14: csk1p   40: madd  6b: jmcht  bf: svsw31
       15: csens   41: msup  6c: intrs  c0: svft0 1
       16: cwtac   42: uadd  6d: index  c1: rvft0 1
       17: mwtaic  43: usub  6e: inprs  c2: svft2 1
       18: mw15    44: add   6f: inps  c3: rvft4 1
       19: mtme    45: sub   70: iorbbc  c4: svft4 1
       1a: csel1   46: umul  71: iorbb  c5: rvft4 1
       1b: cstop   47: udify 72: iowbbc  c6: svft6 1
       1c: cstdr   48: umod  73: iowbb  c7: rvft6 1
       1d: sched   49: mul   74: iorbbc  c8: rechws 1
       1e: cslev   4a: div   75: iorbb  c9: revfts 1
       1f: cgreq   4b: mod   76: iowbbc  ca: stvls  1
       20: mwt    4c: and   77: iowbw  c1: revfts 1
       21: lowc   4d: or    78: mcist  c2: stvsd  2
       22: l0rs   4e: xor   79: pcald  c3: reags 1
       23: l0rw   4f: crc16 7a: pcals 1 4
       24: l0ww   50: neg   7b: pexit  a4: svsw4
       25: l0go   51: abs   7c: lpush  a5: rvsw4
       26: l0gi   52: comp1 7d: lpop   a6: svsw6
       27: l0nc1  53: shc   7e: lrese  a7: rvsw6
       28: l0wt   54: shc8  7f: llock  a8: rechw 2
       29: l0cc1  55: except 80: svsb0  a9: revws 1
       2a: l0cd8

```

F. INSTRUCTION MNEMONICS

G.

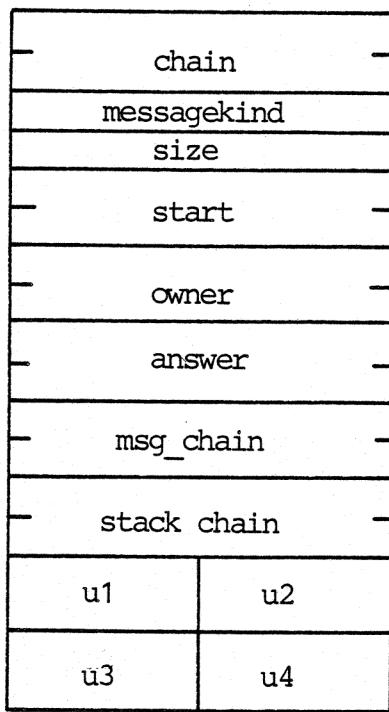
PROCESS INCARNATION DESCRIPTOR LAYOUT

G.

0	-	chain
2	-	
4	/ / / / /	level
6	-	in c state
8	-	msg_waited
A	-	
C	-	activequeue
E	-	
10	-	chainhead
2	-	
4	-	exception code
6	-	exception point
8	-	
A	-	exic
C	-	
E	-	dumplm
20	-	dumpps
2	-	dumplu
4	-	dumplf
6	-	
8	-	entry point
A	-	
C	-	timer
E	-	maxstack
30	-	processref
2	-	
4	-	semchain
6	-	refchain
8	-	
A	-	shadowchain
C	-	
E	-	msg_chain
40	-	
2	-	exit_point
4	-	
6	-	exit semaphore
8	-	
A	-	delay chain
C	-	
E	-	exitref
50	-	
2	-	statistic
4	-	
6	-	secret pointer
8	-	
A	-	plinetable
C	-	
E	-	
60	-	
2	-	incname
4	-	
6	-	
8	-	
A	-	father
C	-	

H. MESSAGE HEADER LAYOUT

H.



I.

I. EXCEPTION CODES

<u>Code (hexadecimal)</u>	<u>Meaning</u>
1	signal: reference = nil
2	renpb odd number of bytes
3	illegal field (last < first)
4	field overflow
5	reference = nil
6	not channel message
7	block i/o at level 0
8	not data message
9	size too small
A	last < first
B	arithmetic overflow
C	index out of bounds
D	undefined opcode
E	odd length in sets
F	setad truncation error
10	stack overflow
11	subrange out of bounds:
12	pointer = nil
13	push: first param = nil
14	push: first param not empty
15	push: identical arguments
16	push: second param locked
17	pop: first param <> nil
18	pop: second param = nil
19	pop: second param locked
1a	wait: reference <> nil
1b	reference locked
1c	lock: not data message
1d	lock: size error
1e	multiple wait on locked semaphore
1f	pool: no core
20	break: shadow = nil
21	remove: shadow = nil
22	start: shadow = nil
23	stop: shadow = nil
24	illegal switch in case construction
25	upper limit in call of succ
26	lower limit in call of pred
27, 28	system error
29	local reference variable not nil at routine exit
2A-2E	system error

"system error" indicates hardware error or microprogram error.

J. WORKING REGISTER LAYOUT

J.

Description of the working registers:
 (for a more detailed description, refer to the reference manual)

usage of the w-registers:

000-007	regset 0
008-00f	regset 1
-	-
-	-
-	-
3d8-3df	regset 123
3e0-3e7	monitor regset
3e8-3ef	com8085
3f0-3f7	work regset
3f8-3ff	dummy regset

regset 0 thru regset 123:

normal mode

1st reg.	lm
2nd reg.	ps (bit 7-15): psc, pst, pss, psi, ri, 0, to, eoi, supp arith ovf
3rd reg.	pb
4th reg.	lu
5th reg.	sf
6th reg.	pr
7th reg.	ib
8th reg.	ic

dummy mode

7th reg.	ffff
the other registers are undefined	

block i/o mode

1st reg.	top = last+1
2nd reg.	ps (as above)
3rd reg.	pb
4th reg.	next address.disp - 1
5th reg.	next address.base
6th reg.	pr
7th reg.	83xx, where xx = instruction code (which is <= 7f)
8th reg.	count

monitor regset:

1st reg.	↑actq(0).base
2nd reg.	↑actq(0).disp
3rd reg.	n
4th reg.	m
5th reg.	k
6th reg.	nxt
7th and	
8th reg.	dummy loop counter

com8085:

1st reg.	fifo5, fifo6
2nd reg.	fifo3, fifo4
3rd reg.	fifol, fifo2
4th reg.	cow (value, disp)
5th reg.	unused
6th reg.	message.errorcode
7th reg.	message.base
8th reg.	message.disp

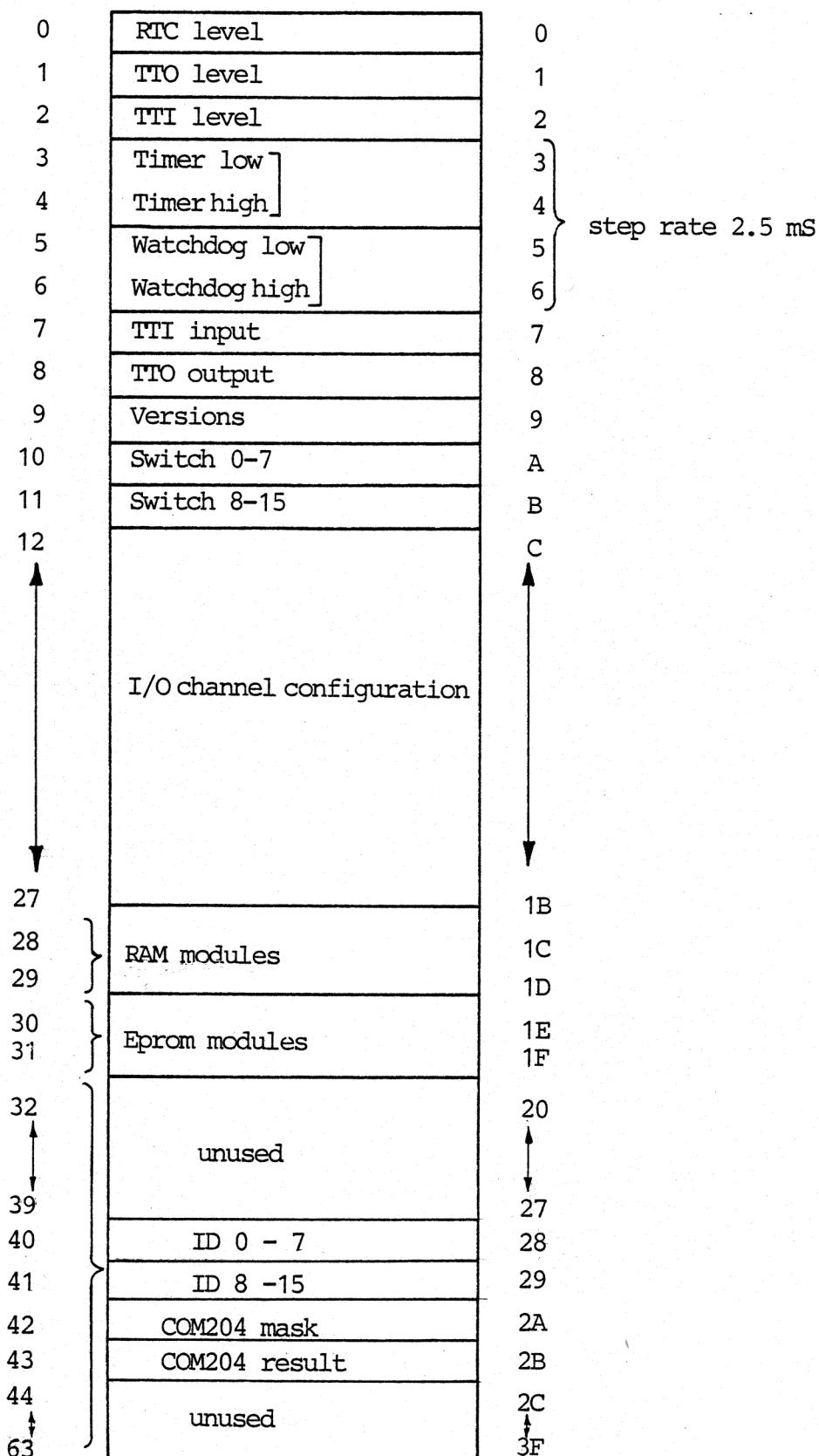
work regset:
used as working registers

dummy regset:

1st reg.	breakpoint address.base
2nd reg.	breakpoint address.disp
3rd reg.	puerrmsk + stat base
4th reg.	breakpointmode (8000 means breakpoint active)
5th reg.	dummy interrupt.lastlev
6th reg.	dummy interrupt.count
7th reg.	parity error address.base
8th reg.	parity error address.disp

K. CONTROL MICROPROCESSOR RAM LAYOUT

K.



L.

INSTALLATION STANDARDS AND RECOMMENDATIONS

This is a recommendation concerning installation of hardware modules in the RC3502. The guidelines concern interrupt levels, input/output priorities, module number selections, DMA priority.

L.1

Input/Output Modules

The priorities and interrupt levels in the following table should be followed according to input/output channels and priority. The first module in a group should be the lowest channel number.

L.2

Memory Modules

MEM204 occupies two module addresses: one RAM module address in the INTERNAL memory section modules 0-15 and one PROM address in the INTERNAL memory section modules 16-31.

TES201/TES202 should be installed in the INTERNAL memory section modules 16-31. To avoid conflict between MEM204 and TES201/TES202 concerning the PROM module numbers 16-31, the first MEM204 module should be installed with the lowest possible module number (0) and the following in increasing, consecutive order. TES201/TES202 groups should be installed with the last module with the highest module number (31), and the other modules in decreasing, consecutive module numbers (30,29,28,...).

To obtain that input/output priorities and DMA priorities follow interrupt levels, the modules should be installed as follows:

```
! ! ! ! !
! ! ! 1. ! 2. ! 1. ! 2. ! 1. !
! ! ! ! !
! C ! C ! M ! I ! I ! C ! C !
! P ! P ! B ! O ! O ! O ! O !
! U ! U ! A ! M ! M ! M ! M !->
! 2 ! 2 ! 2 ! 2 ! 2 ! 2 ! 2 !
! 1 ! 1 ! 0 ! 0 ! 0 ! 0 ! 0 !
! 3 ! 4 ! 1 ! 1 ! 1 ! 4 ! 4 !
!
```

```
! ! ! ! !
! 2. ! 2. ! 1. ! 1. ! 2. ! 1. ! 2. ! 1. ! 2. ! 1. ! 2. ! 1. !
! ! ! !
! S ! C ! S ! C ! V ! V ! I ! I ! M ! M ! T ! T !
! L ! O ! L ! O ! D ! D ! M ! M ! E ! E ! E !
->! A ! M ! A ! M ! C ! C ! S ! S ! M ! M ! S ! S !
! 2 ! 2 ! 2 ! 2 ! 2 ! 2 ! 2 ! 2 ! 2 ! 2 ! 2 ! 2 !
! 0 ! 0 ! 0 ! 0 ! 0 ! 0 ! 0 ! 0 ! 0 ! 0 ! 0 !
! 1 ! 3 ! 1 ! 3 ! 1 ! 1 ! 8 ! 8 ! 4 ! 4 ! 2 ! 2 !
!
```

The following three points should be observed:

1. The interrupt level priority chain starts at the CPU and must not be broken by empty positions until the last module, which uses interrupt level priority.
2. The DMA priority chain starts at the CPU and must not be broken by empty positions until the last module, which uses DMA priority.
3. The module, which is closest to the CPU, has highest priority, both according to interrupt level and DMA.

Dual Port Memory						
		Moduleno.		No. of		
Module	Interrupt	-----		interrupt		
name	level	Base	Moduleno.	levels	No. x	
	(Hex)	(Hex)	(Decimal)	(Decimal)	salesnumber	
	Lowest					
	priority					
CPU	00-04	-	-	5		
SPARE	05-07	-	-	3		
IMS208	08-0F	80-8E	EXT 0- 7	8	8 x RC3542	
VDC201	10-2F	-	-	32	16 x RC3522	
COM203	30-4F	-	-	32	4 x RC3543	
COM204	48-4F	90-96	EXT 8-11	8	8 x RC3546	
IOM201	50-6F	-	-	32	4 x RC3521	
MBA201	70-77	98-9E	EXT 12-15	8	1 x RC3555	
SPARE	78-7B	-	-	4		
	Highest					
	priority					

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RETURN LETTER

Title: RC3502 Operating Guide

RCSL No.: 52-AA1156

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